

1 $\frac{dx}{dt} = 4t^3 - \frac{4}{t}, \frac{dy}{dt} = 8t$ $\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 = \left(4t^3 - \frac{4}{t}\right)^2 + (8t)^2$ $= 16t^6 - 32t^2 + \frac{16}{t^2} + 64t^2$ $= 16t^6 + 32t^2 + \frac{16}{t^2}$ $= 16\left(t^6 + 2t^2 + \frac{1}{t^2}\right)$ $= 16\left(t^3 + \frac{1}{t}\right)^2$ $= \frac{16(t^4 + 1)^2}{t^2}$ <p>Surface area</p> $= \int_1^k 2\pi(4t^2) \frac{4(t^4 + 1)}{t} dt$ $= 32\pi \int_1^k t^5 + t dt$ $= 32\pi \left[\frac{1}{6}t^6 + \frac{1}{2}t^2 \right]_1^k = 32\pi \left(\frac{1}{6}k^6 + \frac{1}{2}k^2 - \frac{2}{3} \right)$ <p>Solving $32\pi \left(\frac{1}{6}k^6 + \frac{1}{2}k^2 - \frac{2}{3} \right) = 384\pi$, we get $k = \pm 2$.</p> <p>Since $k > 1$, $k = 2$.</p>	2 Multiply throughout by n^{n-1} $n^n x_n = 4(n-1)^{n-1} x_{n-1} + 2$ Let $n^n x_n = y_n$, $y_n = 4y_{n-1} + 2$ where $y_1 = 1$ $4y_{n-1} + 2$ $= 4^2 y_{n-2} + 4 \times 2 + 2$ $= 4^3 y_{n-3} + 4^2 \times 2 + 4 \times 2 + 2$ $= \dots$ $= 4^{n-1} y_1 + 4^{n-2} \times 2 + 4^{n-3} \times 2 + \dots + 4 \times 2 + 2$ $= 4^{n-1} + \frac{2(1-4^{n-1})}{1-4}$ $= 4^{n-1} - \frac{2}{3}(1-4^{n-1})$
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	$= \frac{-2 + 5 \cdot 4^{n-1}}{3}$ <p>Hence $x_n = \frac{-2 + 5 \cdot 4^{n-1}}{3n^n}$.</p>	
	<p>Alternative solution</p> <p>$y_n = 4y_{n-1} + 2$ where $y_1 = 1$</p> <p>The general solution is of the form $y_n = A + k(4^{n-1})$.</p> <p>Let $k = 0$, so $A = 4A + 2 \Rightarrow A = -\frac{2}{3}$.</p> <p>So the general solution is $y_n = -\frac{2}{3} + k(4^{n-1})$.</p> <p>Since $y_1 = 1$, we have $1 = -\frac{2}{3} + \frac{k}{4} \Rightarrow k = \frac{5}{3}$.</p> <p>Hence $y_n = -\frac{2}{3} + \frac{5}{3}(4^{n-1})$.</p>	
3(a)	<p>Let $y = ux \Rightarrow \frac{dy}{dx} = u + x \frac{du}{dx}$</p> $x^2 y \frac{dy}{dx} = x^3 + x^2 y - y^3$ $\Rightarrow x^2 (ux) \left(u + x \frac{du}{dx} \right) = x^3 + x^2 (ux) - (ux)^3$ $\Rightarrow u^2 x^3 + ux^4 \frac{du}{dx} = x^3 + ux^3 - u^3 x^3$ $\Rightarrow ux \frac{du}{dx} = 1 + u - u^2 - u^3$ $\Rightarrow \frac{u}{u^3 + u^2 - u - 1} \frac{du}{dx} = -\frac{1}{x}$ $\Rightarrow \int \frac{u}{(u-1)(u+1)^2} du = \int -\frac{1}{x} dx$ <p>Let $\frac{u}{(u-1)(u+1)^2} \equiv \frac{A}{u-1} + \frac{B}{u+1} + \frac{C}{(u+1)^2}$</p> $\Rightarrow u \equiv A(u+1)^2 + B(u+1)(u-1) + C(u-1)$ <p>Let $u = 1$: $1 = 4A \Rightarrow A = \frac{1}{4}$</p> <p>Let $u = -1$: $-1 = -2C \Rightarrow C = \frac{1}{2}$</p> <p>Let $u = 0$: $0 = \frac{1}{4} - B - \frac{1}{2} \Rightarrow B = -\frac{1}{4}$</p> $\Rightarrow \int \frac{1}{4(u-1)} - \frac{1}{4(u+1)} + \frac{1}{2(u+1)^2} du = -\ln x + c$ $\Rightarrow \frac{1}{4} \ln u-1 - \frac{1}{4} \ln u+1 - \frac{1}{2(u+1)} = -\ln x + c$ $\Rightarrow \frac{1}{4} \ln \left \frac{u-1}{u+1} \right + \ln x = \frac{1}{2(u+1)} + c$	

	$\Rightarrow \frac{1}{4} \ln \left \frac{x^4(u-1)}{u+1} \right = \frac{1}{2(u+1)} + c$ $\Rightarrow \ln \left \frac{x^4(u-1)}{u+1} \right = \frac{2}{u+1} + c' \text{ (where } c' = 4c)$ <p>Sub. $u = \frac{y}{x}$:</p> $\ln \left \frac{x^4 \left(\frac{y}{x} - 1 \right)}{\frac{y}{x} + 1} \right = \frac{2}{\frac{y}{x} + 1} + c'$ $\Rightarrow \ln \left \frac{x^4(y-x)}{y+x} \right = \frac{2x}{y+x} + c$ <p>Since $x > y$, $y-x < 0$, so the general solution is</p> $\ln \frac{x^4(x-y)}{y+x} = \frac{2x}{y+x} + c$	
3(b)	$\frac{dy}{dx} = \frac{x^3 + x^2y - y^3}{x^2y}$ <p>Let $f(x, y) = \frac{x^3 + x^2y - y^3}{x^2y} = \frac{x}{y} + 1 - \frac{y^2}{x^2}$, $x_0 = 2$, $y_0 = 1$.</p> <p>Using Euler method with step size 0.5,</p> $y_1 = y_0 + 0.5f(x_0, y_0)$ $= 1 + 0.5 \left(\frac{2}{1} + 1 - \frac{1^2}{2^2} \right)$ $= 2.375$	
3(c)	<p>The approximation is an <u>over-estimate</u>.</p>	
4(i)	$\det(\mathbf{A}) = \det(\mathbf{A}^T) = \det(-\mathbf{A}) = (-1)^3 \det(\mathbf{A}) = -\det(\mathbf{A})$ <p>since \mathbf{A} is skew symmetric</p> <p>Since $\det(\mathbf{A}) = -\det(\mathbf{A}) \Rightarrow \det(\mathbf{A}) = 0$.</p>	
4(ii)(a)	<u>Method 1</u>	

$$\begin{aligned}
\mathbf{a} \times \mathbf{x} &= \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \\
&= \begin{pmatrix} a_2 x_3 - a_3 x_2 \\ a_3 x_1 - a_1 x_3 \\ a_1 x_2 - a_2 x_1 \end{pmatrix} \\
&= \begin{pmatrix} 0 & -a_3 & a_2 \\ a_3 & 0 & -a_1 \\ -a_2 & a_1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \\
\therefore \mathbf{M} &= \begin{pmatrix} 0 & -a_3 & a_2 \\ a_3 & 0 & -a_1 \\ -a_2 & a_1 & 0 \end{pmatrix}
\end{aligned}$$

Method 2

$$\begin{aligned}
\mathbf{a} \times \mathbf{i} &= \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ a_3 \\ -a_2 \end{pmatrix} \\
\mathbf{a} \times \mathbf{j} &= \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -a_3 \\ 0 \\ a_1 \end{pmatrix} \\
\mathbf{a} \times \mathbf{k} &= \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} a_2 \\ -a_1 \\ 0 \end{pmatrix} \\
\therefore \mathbf{M} &= \begin{pmatrix} 0 & -a_3 & a_2 \\ a_3 & 0 & -a_1 \\ -a_2 & a_1 & 0 \end{pmatrix}
\end{aligned}$$

4(ii)(b) \mathbf{M} is skew symmetric and so by (i) $\det(\mathbf{M}) = 0$
Hence \mathbf{M} is not invertible.

4(ii0(c)) $\ker(T) = \{k\mathbf{a} \mid k \in \mathbb{R}\}$, the set of vectors parallel to \mathbf{a} or
line through origin and parallel to \mathbf{a}
 $R(T) = \{\mathbf{v} \in \mathbb{R}^3 \mid \mathbf{a} \cdot \mathbf{v} = 0\}$, the set of vectors
perpendicular to \mathbf{a} or plane through origin and
perpendicular to \mathbf{a}

5(i)	$\begin{aligned}\mathbf{T}_\theta \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} &= \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix} \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \\ &= \begin{pmatrix} \cos 2\theta \cos \theta + \sin 2\theta \sin \theta \\ \sin 2\theta \cos \theta - \cos 2\theta \sin \theta \end{pmatrix} \\ &= \begin{pmatrix} \cos(2\theta - \theta) \\ \sin(2\theta - \theta) \end{pmatrix} \\ &= \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \\ \mathbf{T}_\theta \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} &= \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix} \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} -\cos 2\theta \sin \theta + \sin 2\theta \cos \theta \\ -\sin 2\theta \sin \theta - \cos 2\theta \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} \sin(2\theta - \theta) \\ -\cos(2\theta - \theta) \end{pmatrix} \\ &= -\begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}\end{aligned}$ <p>The eigenvalues are 1 and -1 with eigenvector $\begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$ and $\begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$ respectively.</p>
5(ii)	$\mathbf{T}_\theta = \mathbf{R} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \mathbf{R}^{-1}$
5(iii)	$\theta = \frac{\pi}{3}$ $\mathbf{T}_\theta = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$ $\mathbf{T}_\theta \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 + \frac{\sqrt{3}}{2} \\ \sqrt{3} + \frac{1}{2} \end{pmatrix}$
5(iv)	$\mathbf{T}_\alpha \mathbf{T}_\beta$ $= \begin{pmatrix} \cos 2\alpha & \sin 2\alpha \\ \sin 2\alpha & -\cos 2\alpha \end{pmatrix} \begin{pmatrix} \cos 2\beta & \sin 2\beta \\ \sin 2\beta & -\cos 2\beta \end{pmatrix}$ $= \begin{pmatrix} \cos 2\alpha \cos 2\beta + \sin 2\alpha \sin 2\beta & \cos 2\alpha \sin 2\beta - \sin 2\alpha \cos 2\beta \\ \sin 2\alpha \cos 2\beta - \cos 2\alpha \sin 2\beta & \sin 2\alpha \sin 2\beta + \cos 2\alpha \cos 2\beta \end{pmatrix}$

	$= \begin{pmatrix} \cos 2(\alpha - \beta) & -\sin 2(\alpha - \beta) \\ \sin 2(\alpha - \beta) & \cos 2(\alpha - \beta) \end{pmatrix}$ <p>which is a rotation through an angle of $2(\alpha - \beta)$</p>	
6(i)	$f(x) = \frac{1}{x^2} - \sqrt{x-2}$ $f(2) = \frac{1}{2^2} - \sqrt{2-2} = \frac{1}{4} > 0$ $f(3) = \frac{1}{3^2} - \sqrt{3-2} = -\frac{8}{9} < 0$ <p>Since $y = f(x)$ is a continuous curve over the interval $[2, 3]$ with $f(2) \cdot f(3) < 0$, therefore there exists a root α in the interval.</p>	
6(ii)	<p>Let $x_1 = \frac{2 f(3) + 3 f(2) }{ f(3) + f(2) } = \frac{91}{41}$</p> <p>Note that $f\left(\frac{91}{41}\right) < 0 \therefore \alpha \in \left[2, \frac{91}{41}\right]$</p> $\beta = \frac{2 f(\frac{91}{41}) + \frac{91}{41} f(2) }{ f(\frac{91}{41}) + f(2) } = 2.106450495$ $\beta = 2.11$ (3.s.f)	
6(iii)	$f(x) = \frac{1}{x^2} - \sqrt{x-2}$ $f'(x) = -\frac{2}{x^3} - \frac{1}{2}(x-2)^{-\frac{1}{2}} < 0 \text{ for } 2 \leq x \leq \frac{91}{41}$ $f''(x) = \frac{6}{x^4} + \frac{1}{4}(x-2)^{-\frac{3}{2}} > 0 \text{ for } 2 \leq x \leq \frac{91}{41}$ <p>$f(x) = \frac{1}{x^2} - \sqrt{x-2}$ is concave upward and its gradient negative over the interval $2 \leq x \leq \frac{91}{41}$, β is an overestimate of the root.</p>	
6(iv)	$f(x) = \frac{1}{x^2} - \sqrt{x-2}, f'(x) = -\frac{2}{x^3} - \frac{1}{2\sqrt{x-2}}$ <p>Applying $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$ with $x_0 = 2.5$,</p> $x_1 = x_0 - \frac{f(x_0)}{f'(x_0)} = 1.844866$ $f'(x_1) = -\frac{2}{(x_1)^3} - \frac{1}{2\sqrt{x_1-2}}$ is undefined for $x_1 = 1.84486$. <p>Therefore the Newton-Raphson method failed.</p>	

6(v)	$x_{n+1} = 2 + \frac{1}{(x_n)^4}$ $x_0 = 3$ $x_1 = 2 + \frac{1}{(x_0)^4} = 2.012$ $x_2 = 2 + \frac{1}{(x_1)^4} = 2.061$ $x_3 = 2 + \frac{1}{(x_2)^4} = 2.055$ <p>γ is 2.06 correct to 3 s.f.</p> <p>Since $f(2.055) = 0.00227 > 0$ and $f(2.065) = -0.02044 < 0$, $\gamma = 2.06$ is sufficiently accurate correct to 3 significant figures.</p>	
7(i)	Volume of revolution about y-axis, V $= \int_0^{a(\frac{3\pi}{2}+1)} 2\pi xy \, dx$ $= \int_0^{\frac{3\pi}{2}} 2\pi [a(t - \sin t)][a(1 - \cos t)] \frac{dx}{dt} dt$ $= \int_0^{\frac{3\pi}{2}} 2\pi [a(t - \sin t)][a(1 - \cos t)]^2 dt$ $= 2\pi a^3 \int_0^{\frac{3\pi}{2}} (t - \sin t)(1 - \cos t)^2 dt \quad (\text{Shown})$	
7(ii)	$V = 2\pi a^3 \int_0^{\frac{3\pi}{2}} [(t - 2t \cos t + t \cos^2 t) + (-\sin t)(1 - \cos t)^2] dt$ <p>Let $I = \int t \cos t \, dt = t \sin t + \cos t + c \quad \text{----(1)}$</p> <p>Let $J = \int t \cos^2 t \, dt$</p> $u = t \Rightarrow \frac{du}{dt} = 1$ $\frac{dv}{dt} = \cos^2 t \Rightarrow v = \int \frac{1}{2}(1 + \cos 2t) dt = \frac{1}{2}t + \frac{1}{4}\sin 2t$ $J = \frac{1}{2}t^2 + \frac{1}{4}t \sin 2t - \frac{1}{2} \int (t + \frac{1}{2}\sin 2t) dt$ $J = \frac{1}{2}t^2 + \frac{1}{4}t \sin 2t - \frac{1}{2} \left[\frac{1}{2}t^2 - \frac{1}{4}\cos 2t \right] + c$ $J = \frac{1}{2} \left[\frac{1}{2}t^2 + \frac{1}{2}t \sin 2t + \frac{1}{4}\cos 2t \right] + c$	

	<p>Let $K = \int (-\sin t)(1 - \cos t)^2 dt$</p> $K = \int (-\sin t)(1 - \cos t)^2 dt = -\frac{1}{3}(1 - \cos t)^3 + c$ <p>V</p> $= 2\pi a^3 \int_0^{\frac{3\pi}{2}} \left[(t - 2t \cos t + t \cos^2 t) + (-\sin t)(1 - \cos t)^2 \right] dt$ $= 2\pi a^3 \left[\begin{array}{l} \frac{1}{2}t^2 - 2(t \sin t + \cos t) \\ + \frac{1}{2} \left[\frac{1}{2}t^2 + \frac{1}{2}t \sin 2t + \frac{1}{4}\cos 2t \right] \\ - \frac{1}{3}(1 - \cos t)^3 \end{array} \right]_0^{\frac{3\pi}{2}}$ $= 2\pi a^3 \left[\begin{array}{l} \frac{3}{4}t^2 - 2t \sin t - 2 \cos t \\ + \frac{1}{4}t \sin 2t + \frac{1}{8}\cos 2t \\ - \frac{1}{3}(1 - \cos t)^3 \end{array} \right]_0^{\frac{3\pi}{2}}$ $= 2\pi a^3 \left[\begin{array}{l} \frac{27}{16}\pi^2 - 0 + 3\pi \\ + 0 - \frac{1}{8} \\ - \frac{1}{3} \end{array} \right] - 2\pi a^3 \left[\begin{array}{l} 0 - 2 - 0 \\ + 0 + \frac{1}{8} \\ - 0 \end{array} \right]$ $= 2\pi a^3 \left[\frac{27}{16}\pi^2 + 3\pi + \frac{17}{12} \right]$
8(a)	$m \frac{dv}{dt} = C - kv$ $\Rightarrow \frac{1}{C - kv} \frac{dv}{dt} = \frac{1}{m}$ $\Rightarrow \int \frac{1}{C - kv} dv = \int \frac{1}{m} dt$ $\Rightarrow -\frac{1}{k} \ln C - kv = \frac{t}{m} + c \text{ (for arbitrary constant } c)$ $\Rightarrow \ln C - kv = -\frac{kt}{m} - kc$ $\Rightarrow C - kv = \pm e^{-\frac{kt}{m} - kc}$ $= Ae^{-\frac{kt}{m}} \text{ (where } A = \pm e^{-kc})$ <p>When $t = 0$, $v = v_0$: $A = C - kv_0$</p> $\Rightarrow C - kv = (C - kv_0) e^{-\frac{kt}{m}}$ $\Rightarrow v = \frac{C - (C - kv_0) e^{-\frac{kt}{m}}}{k}$
8(b)	As $t \rightarrow \infty$, $e^{-\frac{kt}{m}} \rightarrow 0$, so $v \rightarrow \frac{C}{k}$.

	<p>After a long time, the velocity of the falling body approaches the constant value $\frac{C}{k}$, which is independent of the initial velocity v_0.</p>	
8(c)(i)	$m \frac{dv}{dt} = C - qt - kv$ $\Rightarrow \frac{dv}{dt} + \frac{k}{m} v = \frac{C - qt}{m}$ <p>Multiply both sides by integrating factor $e^{\int \frac{k}{m} dt} = e^{\frac{kt}{m}}$:</p> $e^{\frac{kt}{m}} \frac{dv}{dt} + \frac{k}{m} e^{\frac{kt}{m}} v = e^{\frac{kt}{m}} \left(\frac{C - qt}{m} \right)$ $\Rightarrow \frac{d}{dt} \left(e^{\frac{kt}{m}} v \right) = \frac{e^{\frac{kt}{m}}}{m} (C - qt)$ $\Rightarrow e^{\frac{kt}{m}} v = \int \frac{e^{\frac{kt}{m}}}{m} (C - qt) dt$ $= \frac{e^{\frac{kt}{m}}}{k} (C - qt) - \int \frac{e^{\frac{kt}{m}}}{k} (-q) dt$ $= \frac{e^{\frac{kt}{m}}}{k} (C - qt) + \frac{q}{k} \int e^{\frac{kt}{m}} dt$ $= \frac{e^{\frac{kt}{m}}}{k} (C - qt) + \frac{q}{k} \left(\frac{me^{\frac{kt}{m}}}{k} \right) + c \text{ (arbitrary constant)}$ <p>c)</p> $\Rightarrow v = \frac{C - qt}{k} + \frac{qm}{k^2} + ce^{-\frac{kt}{m}}$ <p>When $t = 0$, $v = 0$: $c + \frac{W}{k} + \frac{qm}{k^2} = 0 \Rightarrow c = -\frac{C}{k} - \frac{qm}{k^2}$</p> $\therefore v = \frac{C - qt}{k} + \frac{qm}{k^2} - \left(\frac{C}{k} + \frac{qm}{k^2} \right) e^{-\frac{kt}{m}}$ $\Rightarrow v = \left(\frac{C}{k} + \frac{qm}{k^2} \right) \left(1 - e^{-\frac{kt}{m}} \right) - \frac{qt}{k} \text{ (shown)}$	
8(c)(ii)	$F(t) = C - qt = 0 \Rightarrow qt = C \Rightarrow t = \frac{C}{q}$ <p>Substitute into equation for v:</p> $v = \left(\frac{C}{k} + \frac{qm}{k^2} \right) \left(1 - e^{-\frac{Ck}{qm}} \right) - \frac{C}{k}$ $= \frac{qm}{k^2} - \left(\frac{qm}{k^2} + \frac{C}{k} \right) e^{-\frac{Ck}{qm}}$	

	<p>Since $\frac{Ck}{qm} > 0$, $e^{-\frac{Ck}{qm}} < \frac{1}{1 + \frac{Ck}{qm}} = \frac{qm}{qm + Ck}$</p> $\Rightarrow v > \frac{qm}{k^2} - \left(\frac{qm + Ck}{k^2} \right) \left(\frac{qm}{qm + Ck} \right)$ $= \frac{qm}{k^2} - \frac{qm}{k^2}$ $= 0$ <p>$\therefore v$ is positive when $F(t) = 0$. (shown)</p>	
9(a)(i)	$4u_r = 2u_{r-1} - u_{r-2}$ $4\lambda^2 - 2\lambda + 1 = 0$ $\lambda = \frac{2 \pm \sqrt{-12}}{8} = \frac{1}{4}(1 \pm \sqrt{3}i)$ $u_r = \left(\frac{1}{2}\right)^r \left(A \sin \frac{r\pi}{3} + B \cos \frac{r\pi}{3} \right)$	
9(a)(ii)	$u_{k+3} = \left(\frac{1}{2}\right)^{k+3} \left(A \sin \frac{(k+3)\pi}{3} + B \cos \frac{(k+3)\pi}{3} \right)$ $= \left(\frac{1}{2}\right)^{k+3} \left(-A \sin \frac{k\pi}{3} - B \cos \frac{k\pi}{3} \right)$ $= -\frac{1}{8} \left(\frac{1}{2}\right)^k \left(A \sin \frac{k\pi}{3} + B \cos \frac{k\pi}{3} \right)$ $= -\frac{1}{8} u_k$ <p>$\therefore \alpha = -\frac{1}{8}$</p> $\sum_{r=1}^{\infty} u_{3r-2}$ $= \frac{u_1}{1 - \left(-\frac{1}{8}\right)}$ $= \frac{8}{9} u_1$	
9(b)(i)	<p>Case 1: First signal requires 1 microsecond There are 2 different signals that require 1 microsecond and for the remaining $n-1$ microseconds, a_{n-1} messages can be transmitted, so total number of messages is $2a_{n-1}$</p> <p>Case 2: First signal requires 2 microseconds There are 3 different signals that require 2 microseconds and for the remaining $n-2$ microseconds, a_{n-2} messages can be transmitted, so total number of messages is $3a_{n-2}$</p>	

	<p>Combining the two cases above, the recurrence relation is</p> $a_n = 2a_{n-1} + 3a_{n-2}$	
9(b)(ii)	$\lambda^2 - 2\lambda - 3 = 0$ $\lambda = -1 \text{ or } \lambda = 3$ <p>Hence $a_n = A(-1)^n + B(3)^n$</p> <p>Note that $a_1 = 2$ and $a_2 = 7$</p> $-A + 3B = 2$ $A + 9B = 7$ $A = \frac{1}{4}, B = \frac{3}{4}$ $\therefore a_n = \frac{1}{4}(-1)^n + \frac{3}{4}(3)^n$	
10(i)	<p>When $\theta = 0, r = \frac{a}{1+e}$.</p> <p>When $\theta = \pi, r = \frac{a}{1-e}$.</p> $\frac{a}{1+e} + \frac{a}{1-e} = \frac{2a}{1-e^2} = 5.9$ $\frac{\frac{a}{1-e}}{\frac{a}{1+e}} = 2.15 \Rightarrow \frac{1+e}{1-e} = 2.15$ $\frac{1+e}{1-e} = 2.15 \Rightarrow e = 0.3650793 \approx 0.365$ $\frac{2a}{1-e^2} = 5.9 \Rightarrow \frac{2a}{1-0.3650793^2} = 5.9$ $\Rightarrow a = 2.55682 \approx 2.56$	
10(ii)	<p>Required time $= \frac{\text{Area from } \theta = \frac{\pi}{2} \text{ to } \theta = 3}{\text{orbital period}} = \frac{\text{Area from } \theta = 0 \text{ to } \theta = \pi}{2(\text{Area from } \theta = 0 \text{ to } \theta = \pi)}$</p> $\frac{\text{Required time}}{130} = \frac{0.5 \int_{\frac{\pi}{2}}^3 \left(\frac{a}{1+e \cos \theta} \right)^2 d\theta}{2 \left(0.5 \int_0^\pi \left(\frac{a}{1+e \cos \theta} \right)^2 d\theta \right)}$ <p>Required time $= \frac{8.11021694}{25.45271596} \times 130 = 41.423 \approx 41.4 \text{ days}$</p>	

10(iii)	$\frac{\text{Additional time required}}{\text{orbital period}} = \frac{\text{Area from } \theta = 3 \text{ to } \theta = \pi}{2(\text{Area from } \theta = 0 \text{ to } \theta = \pi)}$ $\frac{\text{Additional time required}}{130} = \frac{0.5 \int_{\frac{\pi}{2}}^3 \left(\frac{a}{1+e \cos \theta} \right)^2 d\theta}{2 \left(0.5 \int_0^\pi \left(\frac{a}{1+e \cos \theta} \right)^2 d\theta \right)}$ $\text{Additional time required} = \frac{1.143695252}{25.45271596} \times 130 = 5.8414$ $\approx 5.84 \text{ days}$	
	$25x^2 + 4y^2 - 50x_0x - 8y_0y + 25x_0^2 + 4y_0^2 - 100 = 0$ $25(x^2 - 2x_0x + x_0^2) + 4(y^2 - 2yy_0 + y_0^2) = 100$ $25(x - x_0)^2 + 4(y - y_0)^2 = 100$ $\frac{(x - x_0)^2}{2^2} + \frac{(y - y_0)^2}{5^2} = 1$ <p>Thus, length of semi-major axis of Q is 5.</p> $\frac{(\text{Period of } Q)^2}{(\text{Period of } P)^2} = \frac{5^3}{(5.9/2)^3}$ $\text{Period of } Q = \sqrt{\frac{5^3}{(5.9/2)^3} \times 130^2} = 286.8569 \approx 287 \text{ days}$	