

Qn	Solution
<b>1</b>	<b>Mathematical Induction</b>
<b>(a)</b>	$\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 0 & 0.5 \end{pmatrix}$ $\mathbf{A}^2 = \begin{pmatrix} 1 & 1.5 \\ 0 & 0.25 \end{pmatrix} = \begin{pmatrix} 1 & 2-0.5 \\ 0 & 0.5^2 \end{pmatrix}$ $\mathbf{A}^3 = \begin{pmatrix} 1 & 1.75 \\ 0 & 0.125 \end{pmatrix} = \begin{pmatrix} 1 & 2-0.5^2 \\ 0 & 0.5^3 \end{pmatrix}$ $\text{Conjecture: } \mathbf{A}^n = \begin{pmatrix} 1 & 2-(0.5)^{n-1} \\ 0 & (0.5)^n \end{pmatrix}$
<b>(b)</b>	<p>Let <math>P_n</math> be the proposition that <math>\mathbf{A}^n = \begin{pmatrix} 1 &amp; 2-(0.5)^{n-1} \\ 0 &amp; (0.5)^n \end{pmatrix}</math> for all positive integers <math>n</math>.</p> <p>When <math>n = 1</math></p> $\text{LHS} = \mathbf{A} = \begin{pmatrix} 1 & 1 \\ 0 & 0.5 \end{pmatrix}$ $\text{RHS} = \begin{pmatrix} 1 & 2-(0.5)^0 \\ 0 & 0.5^1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 0.5 \end{pmatrix}$ <p>Since LHS = RHS, <math>P_1</math> is true.</p> <p>Assume <math>P_k</math> is true for some positive integer <math>k</math></p> <p>i.e. <math>\mathbf{A}^k = \begin{pmatrix} 1 &amp; 2-(0.5)^{k-1} \\ 0 &amp; (0.5)^k \end{pmatrix}</math></p> <p>When <math>n = k + 1</math></p> $\begin{aligned} \mathbf{A}^{k+1} &= \mathbf{A}\mathbf{A}^k \\ &= \begin{pmatrix} 1 & 1 \\ 0 & 0.5 \end{pmatrix} \begin{pmatrix} 1 & 2-(0.5)^{k-1} \\ 0 & (0.5)^k \end{pmatrix} \\ &= \begin{pmatrix} 1 & 2-(0.5)^{k-1} + (0.5)^k \\ 0 & (0.5)^{k+1} \end{pmatrix} \\ &= \begin{pmatrix} 1 & 2-(0.5)^k \\ 0 & (0.5)^{k+1} \end{pmatrix} \end{aligned}$ <p><math>\therefore P_k \text{ true} \Rightarrow P_{k+1} \text{ true.}</math></p> <p>Since <math>P_1</math> is true and <math>P_k</math> is true <math>\Rightarrow P_{k+1}</math> is true, by Mathematical Induction, <math>P_n</math> is true for all positive integers <math>n</math>.</p>

Qn	Solution
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2	Complex Numbers
(a)	$\cos 5\theta + i \sin 5\theta = (\cos \theta + i \sin \theta)^5 \quad (\text{by De Moivre's Theorem})$ $= \cos^5 \theta + i5 \cos^4 \theta \sin \theta - 10 \cos^3 \theta \sin^2 \theta$ $- i10 \cos^2 \theta \sin^3 \theta + 5 \cos \theta \sin^4 \theta + i \sin^5 \theta$ $\tan 5\theta = \frac{\sin 5\theta}{\cos 5\theta}$ <p>By comparing real and imaginary parts,</p> $\tan 5\theta = \frac{5 \cos^4 \theta \sin \theta - 10 \cos^2 \theta \sin^3 \theta + \sin^5 \theta}{\cos^5 \theta - 10 \cos^3 \theta \sin^2 \theta + 5 \cos \theta \sin^4 \theta}$ $= \frac{5x - 10x^3 + x^5}{1 - 10x^2 + 5x^4} \quad (\text{dividing throughout by } \cos^5 \theta)$
(b)	$\tan \left( 5 \left( \frac{\pi}{5} \right) \right) = 0$ $5x - 10x^3 + x^5 = 0$ $x = 0 \quad \text{or} \quad x^2 = \frac{10 \pm \sqrt{100 - 4(5)}}{2}$ $= 5 \pm 2\sqrt{5}$ <p>Since <math>\tan \left( 5 \left( \frac{k\pi}{5} \right) \right) = 0</math> for <math>k = -2, -1, 0, 1, 2</math>,</p> <p><math>\tan^2 \left( \frac{\pi}{5} \right)</math> is the smaller value.</p> $\tan^2 \left( \frac{\pi}{5} \right) = 5 - 2\sqrt{5}$

Qn	Solution
<b>3</b>	<b>Recurrence Relations</b>
<b>(a)</b>	$x^2 - 3x + 1 = 0$ $x = \frac{3 \pm \sqrt{9 - 4(1)(1)}}{2} = \frac{3 \pm \sqrt{5}}{2}$ $\alpha = \frac{3 - \sqrt{5}}{2} \quad \text{and} \quad \beta = \frac{3 + \sqrt{5}}{2}$
<b>(b)</b>	<p>Note that <math>\alpha</math> and <math>\beta</math> are the limits of the sequence if the sequence converges.</p> <p>Consider <math>\alpha &lt; x_n &lt; \beta</math>:</p> $\begin{aligned} (x_{n+1})^2 - (x_n)^2 &= 3x_n - 1 - (x_n)^2 \\ &= -(x_n - \alpha)(x_n - \beta) \end{aligned}$ <p>Since <math>\alpha &lt; x_n &lt; \beta</math>, <math>(x_n - \alpha) &gt; 0</math> and <math>(x_n - \beta) &lt; 0</math>.</p> <p>Thus, <math>(x_{n+1})^2 - (x_n)^2 &gt; 0</math></p> <p>Also, <math>(x_{n+1})^2 - (x_n)^2 = (x_{n+1} - x_n)(x_{n+1} + x_n)</math></p> <p>Since <math>x_n</math> and <math>x_{n+1}</math> are positive, then <math>(x_{n+1} + x_n) &gt; 0</math></p> <p>Thus, <math>(x_{n+1} - x_n) &gt; 0 \Rightarrow x_{n+1} &gt; x_n</math></p> <p>Since <math>\alpha &lt; x_n &lt; \beta</math>, we have <math>(x_{n+1})^2 = 3x_n - 1 &lt; 3\beta - 1 = \beta^2</math>.</p> <p>Thus, <math>x_{n+1} &lt; \beta</math> since <math>x_{n+1} &gt; 0</math></p> <p>Therefore if <math>\alpha &lt; x_n &lt; \beta</math>, then <math>\alpha &lt; x_n &lt; x_{n+1} &lt; \beta</math> for all <math>n \in \mathbb{Z}^+</math>.</p> <p>Thus, the sequence increases and converges to <math>\beta</math>.</p>

Qn	Solution
4	<b>Recurrence Relation</b>
(a)	$\frac{1}{1-x} = (1-x)^{-1}$ $= 1 + x + x^2 + \dots$ $= \sum_{r=0}^{\infty} x^r$
(b)	$f(x) = \sum_{r=0}^{\infty} u_r x^r$ $xf(x) = \sum_{r=0}^{\infty} u_r x^{r+1} = \sum_{r=1}^{\infty} u_{r-1} x^r$ $x^2 f(x) = \sum_{r=0}^{\infty} u_r x^{r+2} = \sum_{r=2}^{\infty} u_{r-2} x^r$ $f(x) - xf(x) - x^2 f(x) = \sum_{r=0}^{\infty} u_r x^r - \sum_{r=1}^{\infty} u_{r-1} x^r - \sum_{r=2}^{\infty} u_{r-2} x^r$ $= u_0 x^0 + u_1 x^1 - u_0 x^1 + \sum_{r=2}^{\infty} [u_r - u_{r-1} - u_{r-2}] x^r$ $= x$ <p>Thus,</p> $f(x)(1-x-x^2) = x$ $f(x) = \frac{-x}{x^2 + x - 1}$
	$f(x) = \frac{-x}{x^2 + x - 1} = \frac{A}{x - \alpha} + \frac{B}{x - \beta} \text{ where } \alpha = \frac{-1 - \sqrt{5}}{2} \text{ and } \beta = \frac{-1 + \sqrt{5}}{2}.$ <p>Solving:</p> $A = -\frac{-1 - \sqrt{5}}{2} \div \left( \frac{-1 - \sqrt{5}}{2} - \frac{-1 + \sqrt{5}}{2} \right) = \frac{-1 - \sqrt{5}}{2\sqrt{5}}$ $B = -\frac{-1 + \sqrt{5}}{2} \div \left( \frac{-1 + \sqrt{5}}{2} - \frac{-1 - \sqrt{5}}{2} \right) = -\frac{-1 + \sqrt{5}}{2\sqrt{5}}$

$f(x) = \frac{A}{x-\alpha} + \frac{B}{x-\beta}$ $= -\frac{A}{\alpha} \left( \frac{1}{1-\left(\frac{x}{\alpha}\right)} \right) - \frac{B}{\beta} \left( \frac{1}{1-\left(\frac{x}{\beta}\right)} \right)$ $= -\frac{A}{\alpha} \sum_{r=0}^{\infty} \left( \frac{x}{\alpha} \right)^r - \frac{B}{\beta} \sum_{r=0}^{\infty} \left( \frac{x}{\beta} \right)^r$ $= \sum_{r=0}^{\infty} \left( -\frac{A}{\alpha} \left( \frac{1}{\alpha} \right)^r - \frac{B}{\beta} \left( \frac{1}{\beta} \right)^r \right) x^r$ <p>Comparing with <math>f(x) = \sum_{r=0}^{\infty} u_r x^r</math>, we get</p> $u_r = -\frac{A}{\alpha} \left( \frac{1}{\alpha} \right)^r - \frac{B}{\beta} \left( \frac{1}{\beta} \right)^r$ $u_n = -\frac{1}{\sqrt{5}} \left( \frac{2}{-1-\sqrt{5}} \right)^n + \frac{1}{\sqrt{5}} \left( \frac{2}{-1+\sqrt{5}} \right)^n$	<p>using result from part (a)</p>
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Qn	Solution
<b>5</b>	<b>Numerical Methods</b>
<b>(a)</b>	<p>Note that <math>f</math> is continuous for all <math>x \in \mathbb{R}</math>.</p> $f(0) = -\frac{1}{3} < 0$ $f(1) = 0.825 > 0$ $f'(x) = 2 - \cos x > 0 \quad \text{for all } x \in \mathbb{R}$ <p>Since <math>f</math> is continuous and is a strictly increasing function, and <math>f(0)f(1) &lt; 0</math>, <math>C</math> cuts the <math>x</math>-axis exactly once in the interval <math>0 &lt; x &lt; 1</math>.</p>
<b>(b)</b>	<p>Using <math>x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}</math> with <math>x_0 = 0</math>,</p> $x_1 = 0.333333$ $x_2 = 0.327515$ $x_3 = 0.327509$ $x_4 = 0.327509$ <p>To verify:</p> $f(0.32745) = -6.29 \times 10^{-5} < 0$ $f(0.32755) = 4.24 \times 10^{-5} > 0$ <p>Thus, <math>x</math>-intercept of <math>C = 0.3275</math> (4 d.p.)</p>
<b>(c)</b>	<p><b>Possible Explanation 1:</b></p> <p>For <math>y =  f(x) </math>, there will be a kink at <math>x = 0.3275</math> for the first quadratic segment from <math>x = 0</math> to <math>x = 0.5</math> when using Simpson's Rule with four strips. Thus, the estimation might not be good.</p> <p><b>Possible Explanation 2:</b></p> <p>For <math>y = f(x)</math>, the curve is below the <math>x</math>-axis from <math>x = 0</math> to <math>x = 0.3275</math> and above the <math>x</math>-axis from <math>x = 0.3275</math> to <math>x = 1</math>. The use of Simpson's Rule with four strips will split the region into 2 parts: from <math>x = 0</math> to <math>x = 0.5</math> and from <math>x = 0.5</math> to <math>x = 1</math> for estimation. Thus, this estimation might not be good as the regions under and above the <math>x</math>-axis are not properly accounted for using Simpson's Rule with four strips.</p>
<b>(d)</b>	<p><b>Method 1:</b></p> <p>Using <math>y =  f(x) </math></p> $A = \int_0^1  f(x)  \, dx$ $\approx \frac{1}{3} \left( \frac{1-0}{6} \right) \left[  f(0)  + 4 \left  f\left(\frac{1}{6}\right) \right  + 2 \left  f\left(\frac{1}{3}\right) \right  + 4 \left  f\left(\frac{1}{2}\right) \right  + 2 \left  f\left(\frac{2}{3}\right) \right  + 4 \left  f\left(\frac{5}{6}\right) \right  +  f(1)  \right]$ $= 0.31774 \quad (5 \text{ d.p.})$

**Method 2:**Using  $y = f(x)$  $A$ 

$$\approx -\int_0^{\frac{1}{3}} f(x) \, dx + \int_{\frac{1}{3}}^1 f(x) \, dx$$

$$\approx -\frac{1}{3} \left( \frac{1-0}{6} \right) \left[ f(0) + 4f\left(\frac{1}{6}\right) + f\left(\frac{1}{3}\right) \right]$$

$$+ \frac{1}{3} \left( \frac{1-0}{6} \right) \left[ f\left(\frac{1}{3}\right) + 4f\left(\frac{1}{2}\right) + 2f\left(\frac{2}{3}\right) + 4f\left(\frac{5}{6}\right) + f(1) \right]$$

$$= 0.31705 \quad (5 \text{ d.p.})$$

Qn	Solution
<b>6</b>	<b>Matrices and Linear Spaces</b>
<b>(a)(i)</b>	$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & k_1 & 0 & k_1 \\ 0 & 0 & k_2 & k_2 \end{bmatrix} = \begin{bmatrix} 0 & ak_1 & bk_2 & ak_1 + bk_2 \\ 0 & ck_1 & dk_2 & ck_1 + dk_2 \end{bmatrix}$ $\therefore O'(0,0)$ $P'(ak_1, ck_1)$ $Q'(bk_2, dk_2)$ $R'(ak_1 + bk_2, ck_1 + dk_2)$
<b>(ii)</b>	<p>Note that <math>O'P'R'Q'</math> is a parallelogram</p> <p>Area of parallelogram <math>O'P'R'Q'</math></p> $= \left  \begin{pmatrix} ak_1 \\ ck_1 \\ 0 \end{pmatrix} \times \begin{pmatrix} bk_2 \\ dk_2 \\ 0 \end{pmatrix} \right  = \left  \begin{pmatrix} 0 \\ 0 \\ adk_1k_2 - bck_1k_2 \end{pmatrix} \right $ $=  adk_1k_2 - bck_1k_2 $ $=  ad - bc   k_1k_2 $ $=  \det(\mathbf{A})  \times \text{area of rectangle } OPRQ$
<b>(b)(i)</b>	<p>Let <math>\mathbf{A}</math> and <math>\mathbf{B}</math> be orthogonal matrices.</p> $(\mathbf{AB})(\mathbf{AB})^T$ $= \mathbf{ABB}^T\mathbf{A}^T$ $= \mathbf{AIA}^T$ $= \mathbf{I}$ $(\mathbf{AB})^T(\mathbf{AB})$ $= \mathbf{B}^T\mathbf{A}^T\mathbf{AB}$ $= \mathbf{B}^T\mathbf{IB}$ $= \mathbf{I}$ <p>Therefore, <math>\mathbf{AB}</math> is an orthogonal matrix.</p>
<b>(ii)</b>	$\det(\mathbf{MM}^T) = \det(\mathbf{I}) = 1$ $\det \mathbf{M} \det \mathbf{M}^T = 1$ $(\det \mathbf{M})^2 = 1$ $\det \mathbf{M} = 1 \text{ or } \det \mathbf{M} = -1$
<b>(iii)</b>	$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ $\det \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = -1$ <p>but</p> $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$

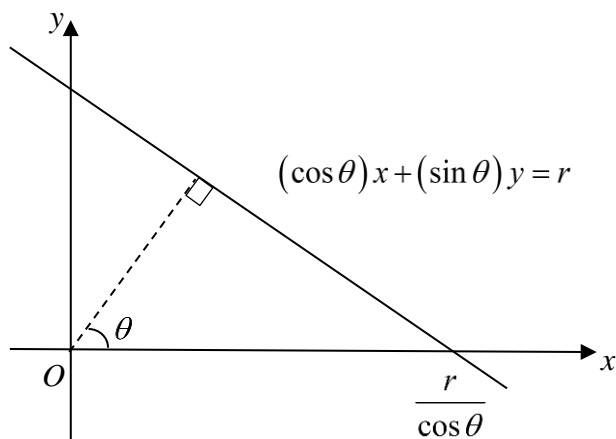


	Hence, $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ is not orthogonal
(iv)	$\begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{bmatrix}$ $= \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 & -\cos \theta \sin \theta + \cos \theta \sin \theta \\ 0 & 1 & 0 \\ -\cos \theta \sin \theta + \cos \theta \sin \theta & 0 & \sin^2 \theta + \cos^2 \theta \end{bmatrix}$ $= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ <p><b>Alternative</b></p> $\begin{bmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$ $= \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 & \cos \theta \sin \theta - \cos \theta \sin \theta \\ 0 & 1 & 0 \\ \cos \theta \sin \theta - \cos \theta \sin \theta & 0 & \sin^2 \theta + \cos^2 \theta \end{bmatrix}$ $= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
	$\mathbf{B}^{-1} = \mathbf{B}^T = \begin{bmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{bmatrix}$ <p>Since <math>\mathbf{B}\mathbf{B}^T = \mathbf{I}</math> and <math>\mathbf{B}\mathbf{B}^{-1} = \mathbf{I}</math> imply that <math>\mathbf{B}^{-1} = \mathbf{B}^T</math>.</p>

Qn	Solution
7	<b>Matrices and Linear Spaces</b>
(a)	<p>Since <math>\begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix}</math> is an eigenvector of <math>\mathbf{M}</math>,</p> $\begin{pmatrix} 3 & 1 & 3 \\ -1 & -1 & k \\ 1 & 3 & k \end{pmatrix} \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix} = \lambda \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix} \text{ for some } \lambda \in \mathbb{R}.$ $\begin{pmatrix} 3 & 1 & 3 \\ -1 & -1 & k \\ 1 & 3 & k \end{pmatrix} \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix} = \lambda \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 36 \\ -9+k \\ 3+k \end{pmatrix} = \lambda \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix}$ <p>Solving, <math>\lambda = 3, k = 0</math>.</p> <p>Solve for <math>\lambda \mathbf{I} - \mathbf{M} = \mathbf{0}</math>,</p> $\begin{vmatrix} \lambda-3 & -1 & -3 \\ 1 & \lambda+1 & 0 \\ -1 & -3 & \lambda \end{vmatrix} = 0$ $(\lambda-3)(\lambda+1)(\lambda) + (-3)(1)(-3) - (-3)(-1)(\lambda+1) - (1)(-1)(\lambda) = 0$ $\lambda^3 - 2\lambda^2 - 5\lambda + 6 = 0$ $\lambda = -2 \text{ or } \lambda = 1 \text{ or } \lambda = 3$ <p>Solve for <math>\mathbf{M}\mathbf{x} = \lambda\mathbf{x}</math>,</p> <p>When <math>\lambda = -2</math></p> $\left( \begin{array}{ccc c} -5 & -1 & -3 & 0 \\ 1 & -1 & 0 & 0 \\ -1 & -3 & -2 & 0 \end{array} \right) \xrightarrow{\text{Gauss-Jordan Elimination}} \left( \begin{array}{ccc c} 1 & 0 & 1/2 & 0 \\ 0 & 1 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$ $\mathbf{x} = s \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix}, s \in \mathbb{R}.$ <p><math>\therefore</math> one possible eigenvector for the eigenvalue <math>-2</math> is <math>\begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix}</math>.</p> <p>When <math>\lambda = 1</math>,</p> $\left( \begin{array}{ccc c} -2 & -1 & -3 & 0 \\ 1 & 2 & 0 & 0 \\ -1 & -3 & 1 & 0 \end{array} \right) \xrightarrow{\text{Gauss-Jordan Elimination}} \left( \begin{array}{ccc c} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$

	$\mathbf{x} = t \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}, t \in \mathbb{R}.$ <p><math>\therefore</math> one possible eigenvector for the eigenvalue 1 is <math>\begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}.</math></p>
<b>(b)</b>	<p>Since the plane <math>P</math> intersects the line <math>\mathbf{r} = \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}</math> at a unique point, <math>P</math> is not parallel to <math>\begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}.</math></p> <p>Since <math>O</math> is invariant under <math>\mathbf{M}</math>,</p> <p>Equation of <math>P: \mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix}, s, t \in \mathbb{R}.</math></p> $\mathbf{n}_p = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 12 \\ -3 \\ 1 \end{pmatrix} = 2 \begin{pmatrix} 2 \\ 7 \\ -3 \end{pmatrix}$ <p>Equation of <math>P: \mathbf{r} \cdot \begin{pmatrix} 2 \\ 7 \\ -3 \end{pmatrix} = 0</math></p> $2x + 7y - 3z = 0$

Qn	Solution
<b>8</b>	<b>Polar Curves + Definite Integral</b>
(a)	<p>Note that for trivial cases where <math>\theta = k\pi, k \in \mathbb{Z}</math>, it is easily observed that the shortest distance from origin to the line is <math>r</math>.</p> <p>Suppose <math>\theta \neq k\pi, k \in \mathbb{Z}</math>.</p> <p>Differentiate <math>(\cos \theta)x + (\sin \theta)y = r</math> ---(1) with respect to <math>x</math>,</p> $(\cos \theta) + (\sin \theta) \frac{dy}{dx} = 0$ $\frac{dy}{dx} = -\frac{\cos \theta}{\sin \theta}$ <p>Equation of the line perpendicular to <math>(\cos \theta)x + (\sin \theta)y = r</math>, passing through <math>O</math>, is</p> $y = -\frac{1}{\left(-\frac{\cos \theta}{\sin \theta}\right)}x$ $= \frac{\sin \theta}{\cos \theta}x \quad \text{---(2)}$ <p>Sub (2) into (1),</p> $(\cos \theta)x + \left(\frac{\sin^2 \theta}{\cos \theta}\right)x = r$ $x = r \cos \theta$ <p>Sub into (2),</p> $y = r \sin \theta$ $\therefore \text{shortest distance} = \sqrt{(r \cos \theta)^2 + (r \sin \theta)^2} = r$ <p>Since the gradient of the line represented by equation (2) is <math>y = \frac{\sin \theta}{\cos \theta} = \tan \theta</math>, <math>\theta</math> is the <u>angle the normal makes with the positive x-axis</u>.</p> <p><b><u>Alternative method</u></b></p> <p>Since gradient of line is <math>-\cot \theta</math>, gradient of normal to the line is <math>\tan \theta</math>. Angle that normal makes with the positive <math>x</math>-axis is <math>\theta</math>.</p>



Shortest distance from origin to the line

$$= \frac{r}{\cos \theta} \cos \theta = r$$

**Alternative method**

Since gradient of line is  $-\cot \theta$ , gradient of normal to the line is  $\tan \theta$ . Angle that normal makes with the positive  $x$ -axis is  $\theta$ .

$$\begin{aligned} &(\cos \theta)x + (\sin \theta)y = r \\ \Rightarrow &(\cos \theta)x + (\sin \theta)y - r = 0 \end{aligned}$$

Distance from O to line  $L$

$$\begin{aligned} &= \frac{|(\cos \theta)(0) + (\sin \theta)(0) - r|}{\sqrt{\cos^2 \theta + \sin^2 \theta}} \\ &= r \end{aligned}$$

**(b)**

Differentiate  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  with respect to  $x$ ,

$$\begin{aligned} \frac{2x}{a^2} + \frac{2y \left( \frac{dy}{dx} \right)}{b^2} &= 0 \\ \frac{dy}{dx} &= -\frac{b^2 x}{a^2 y} \end{aligned}$$

Equation of tangent at  $P(x_0, y_0)$ ,

$$\begin{aligned} y - y_0 &= -\frac{b^2 x_0}{a^2 y_0} (x - x_0) \\ \frac{yy_0}{b^2} - \frac{y_0^2}{b^2} &= \frac{x_0^2}{a^2} - \frac{xx_0}{a^2} \\ \frac{xx_0}{a^2} + \frac{yy_0}{b^2} &= \frac{x_0^2}{a^2} + \frac{y_0^2}{b^2} \\ \frac{xx_0}{a^2} + \frac{yy_0}{b^2} &= 1 \quad \text{---(3)} \quad \left( \text{Since } P(x_0, y_0) \text{ lies on } C \right) \end{aligned}$$

**(c)**

Comparing (3) with (1),

	$\frac{x_0}{a^2} = \frac{\cos \theta}{r} \quad \text{and} \quad \frac{y_0}{b^2} = \frac{\sin \theta}{r}$ $x_0 = \frac{a^2 \cos \theta}{r} \quad \text{and} \quad y_0 = \frac{b^2 \sin \theta}{r}$ <p>where <math>r</math> is the shortest distance from <math>O</math> to <math>X</math>, and <math>\theta</math> is the angle it makes with the positive <math>x</math>-axis.</p> <p>Since <math>(x_0, y_0)</math> lies on <math>C</math>,</p> $\frac{\left(\frac{a^2 \cos \theta}{r}\right)^2}{a^2} + \frac{\left(\frac{b^2 \sin \theta}{r}\right)^2}{b^2} = 1$ $a^2 \cos^2 \theta + b^2 \sin^2 \theta = r^2 \quad (\text{Shown})$
(d)	<p>Since <math>a = 3</math> and <math>b = 2</math>, the polar equation of the pedal curve is</p> $9 \cos^2 \theta + 4 \sin^2 \theta = r^2.$ <p>Differentiate both sides with respect to <math>\theta</math>,</p> $-18 \cos \theta \sin \theta + 8 \sin \theta \cos \theta = 2r \left( \frac{dr}{d\theta} \right)$ $\frac{-5 \sin \theta \cos \theta}{\sqrt{9 \cos^2 \theta + 4 \sin^2 \theta}} = \frac{dr}{d\theta}$ $\left( \frac{dr}{d\theta} \right)^2 = \frac{25 \sin^2 \theta \cos^2 \theta}{9 \cos^2 \theta + 4 \sin^2 \theta}$ <p>Required arc length</p> $= \int_0^{2\pi} \sqrt{\left(9 \cos^2 \theta + 4 \sin^2 \theta\right) + \left(\frac{25 \sin^2 \theta \cos^2 \theta}{9 \cos^2 \theta + 4 \sin^2 \theta}\right)} d\theta$ $= 16.484$ $\approx 16.5$ <p><b><u>Alternative method</u></b></p> <p>Since <math>a = 3</math> and <math>b = 2</math>, the polar equation of the pedal curve is</p> $9 \cos^2 \theta + 4 \sin^2 \theta = r^2$ $\therefore r = \pm \sqrt{9 \cos^2 \theta + 4 \sin^2 \theta}.$ <p>Required arc length</p> $= \int_0^{2\pi} \sqrt{\left(9 \cos^2 \theta + 4 \sin^2 \theta\right) + \left(\frac{dr}{d\theta}\right)^2} d\theta$ $= 16.484$ $\approx 16.5$

Qn	Solution
9	<b>Differential Equations</b>
(a)	$m \frac{d^2 s}{dt^2} = mg - K \frac{ds}{dt}$ $\frac{d^2 s}{dt^2} + \frac{K}{m} \frac{ds}{dt} = g$ <p>Homogeneous equation: <math>\frac{d^2 s}{dt^2} + \frac{K}{m} \frac{ds}{dt} = 0</math></p> <p>Auxiliary equation: <math>x^2 + \frac{K}{m} x = 0</math></p> $\Rightarrow x \left( x + \frac{K}{m} \right) = 0$ $\Rightarrow x = 0 \text{ or } x = -\frac{K}{m}$ <p>Complementary function: <math>s_c = A + Be^{-\frac{K}{m}t}</math></p> <p>Let particular integral be <math>s_p = Ct + D</math></p> $\frac{d^2 s_p}{dt^2} + \frac{K}{m} \frac{ds_p}{dt} = \frac{KC}{m} = g \Rightarrow C = \frac{mg}{K}$ $s = 0 \text{ at } t = 0 \Rightarrow D = 0$ <p>General Solution: <math>s = A + Be^{-\frac{K}{m}t} + \frac{mg}{K}t</math></p> $\frac{ds}{dt} = -\frac{K}{m}Be^{-\frac{K}{m}t} + \frac{mg}{K}$ <p>It is given that <math>s = 0</math> and <math>\frac{ds}{dt} = v_1</math> at <math>t = 0</math>.</p> $A + B = 0$ $v_1 = -\frac{KB}{m} + \frac{mg}{K}$ $\therefore B = -\frac{m}{K} \left( v_1 - \frac{mg}{K} \right)$ $A = \frac{m}{K} \left( v_1 - \frac{mg}{K} \right)$ <p>Particular solution:</p> $s = \frac{m}{K} \left( v_1 - \frac{mg}{K} \right) - \frac{m}{K} \left( v_1 - \frac{mg}{K} \right) e^{-\frac{K}{m}t} + \frac{mg}{K}t$ $s = \frac{mg}{K} \left[ t + \left( \frac{v_1}{g} - \frac{m}{K} \right) \left( 1 - e^{-\frac{K}{m}t} \right) \right]$
	<p>Alternative (H2 Math method with substitution):</p> $m \frac{d^2 s}{dt^2} = mg - K \frac{ds}{dt}$ $\frac{d^2 s}{dt^2} + \frac{K}{m} \frac{ds}{dt} = g$ <p>Let <math>v = \frac{ds}{dt}</math></p>

	$m \frac{dv}{dt} = mg - Kv$ $\int \frac{m}{mg - Kv} dv = \int 1 dt$ $-\frac{m}{K} \ln  mg - Kv  = t + c$ $mg - Kv = Ae^{-\frac{K}{m}t}$ $v = \frac{1}{K} \left( mg - Ae^{-\frac{K}{m}t} \right)$ <p>When <math>t = 0</math>, <math>v = v_1</math>,</p> $v_1 = \frac{1}{K} (mg - A)$ $A = mg - v_1 K$ $v = \frac{1}{K} \left( mg - (mg - v_1 K) e^{-\frac{K}{m}t} \right)$ $s = \int \frac{1}{K} \left( mg - (mg - v_1 K) e^{-\frac{K}{m}t} \right) dt$ $s = \frac{mg}{K} t + \frac{(mg - v_1 K)}{K} e^{-\frac{K}{m}t} + D$ <p><math>s = 0</math> at <math>t = 0</math>.</p> $D = -\frac{(mg - v_1 K)}{K}$ $s = \frac{mg}{K} t + \frac{(mg - v_1 K)}{K} e^{-\frac{K}{m}t} - \frac{(mg - v_1 K)}{K}$ $s = \frac{mg}{K} \left[ t + \left( \frac{v_1}{g} - \frac{m}{K} \right) \left( 1 - e^{-\frac{K}{m}t} \right) \right]$
(b)	$m \frac{d^2s}{dt^2} = mg - K \frac{ds}{dt}$ <p>Terminal velocity is attained at <math>\frac{d^2s}{dt^2} = 0</math>.</p> $mg - K \frac{ds}{dt} = 0$ $\frac{ds}{dt} = \frac{mg}{K}$ <p>Terminal velocity <math>v_2 = \frac{mg}{K}</math></p>



(c)	$\frac{ds}{dt} = \frac{mg}{K} \left[ 1 + \frac{K}{m} \left( \frac{v_1}{g} - \frac{m}{K} \right) \left( e^{-\frac{K}{m}t} \right) \right]$ <p> <math>m = 75, g = 9.8, K = 110</math> and <math>v_1 = 54</math>.            Using GC,  <math display="block">\frac{ds}{dt} &lt; 1.02 \left( \frac{75(9.8)}{110} \right)</math> <math display="block">\Rightarrow t &gt; 4.0019506</math> <math display="block">\Rightarrow s &gt; 58.911587</math>           Let <math>a</math> be altitude.  <math>a &lt; 941.088</math>            Altitude is <math>\leq 941</math> m.         </p>
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Qn	Solution
10	Conics
(a)	<div data-bbox="336 197 1129 622" data-label="Figure"> </div> <p data-bbox="279 672 564 707">Volume of the display</p> $  \begin{aligned}  &= 2\pi \int_0^r xy \, dx \\  &= 2\pi \int_0^r xe^{-x^2} \, dx \\  &= 2\pi \left[ -\frac{1}{2}e^{-x^2} \right]_0^r \\  &= 2\pi \left[ \frac{1}{2} - \frac{1}{2}e^{-r^2} \right]  \end{aligned}  $ <p data-bbox="279 1059 906 1137">As <math>r \rightarrow \infty</math>, volume of display <math>\rightarrow 2\pi \left( \frac{1}{2} - 0 \right) = \pi</math>.</p> <p data-bbox="279 1149 1187 1238">Therefore, the theoretical maximum volume of the solid ceramic display is <math>\pi</math> units<sup>3</sup>.</p> <p data-bbox="279 1261 325 1296"><b>OR</b></p> <p data-bbox="279 1319 564 1355">Volume of the display</p> $  \begin{aligned}  &= \pi \int_{e^{-r^2}}^1 x^2 \, dy \\  &= \pi \int_{e^{-r^2}}^1 -\ln y \, dy \\  &= -\pi \left\{ [y \ln y]_{e^{-r^2}}^1 - \int_{e^{-r^2}}^1 1 \, dy \right\} \\  &= -\pi \left\{ [0 - e^{-r^2}(-r^2)] - [y]_{e^{-r^2}}^1 \right\} \\  &= -\pi \left\{ [0 - e^{-r^2}(-r^2)] - [1 - e^{-r^2}] \right\} \\  &= \pi (1 - r^2 e^{-r^2} - e^{-r^2})  \end{aligned}  $ <p data-bbox="279 1809 703 1854">As <math>r \rightarrow \infty</math>, <math>r^2 e^{-r^2} \rightarrow 0</math>, <math>e^{-r^2} \rightarrow 0</math>.</p> <p data-bbox="279 1865 788 1910"><math>\therefore</math> volume of display <math>\rightarrow \pi (1 - 0 - 0) = \pi</math>.</p> <p data-bbox="279 1955 1187 2045">Therefore, the theoretical maximum volume of the solid ceramic display is <math>\pi</math> units<sup>3</sup>.</p>

(b)(i)	<p>Distance from vertex of the parabolic primary mirror to <math>O</math></p> $= 80 - \frac{100}{2} = 30.$ <p>Equation of parabola:</p> $y^2 = 4(80)(x + 30)$ $y^2 = 320x + 9600$
(b)(ii)	<p>The distance from <math>O</math> to the vertex of the hyperbolic secondary mirror is 20cm, i.e., <math>a = 20</math>.</p> <p>Since <math>F_1F_2 = 100\text{cm}</math> and <math>F_1</math> and <math>F_2</math> are equidistant from <math>O</math>,</p> $c = \frac{100}{2} = 50.$ $\therefore e = \frac{c}{a} = \frac{50}{20} = \frac{5}{2}$
(b)(iii)	<p>Cartesian equation of the hyperbola representing the cross-section of the secondary mirror:</p> $\frac{x^2}{20^2} - \frac{y^2}{b^2} = 1$ $a^2 + b^2 = c^2$ $20^2 + b^2 = 50^2$ $b^2 = 2100$ $\therefore \frac{x^2}{400} - \frac{y^2}{2100} = 1 \quad \text{---(1)}$ <p>Since the diameter of the parabolic primary mirror is 24cm, when <math>y = 12</math>,</p> $12^2 = 320x + 9600$ $x = \frac{144 - 9600}{320}$ $x = -29.55$ <p>The equation of the line passing through points <math>(-29.55, 12)</math> and <math>F_1(50, 0)</math>:</p> $\frac{y - 0}{x - 50} = \frac{12 - 0}{-29.55 - 50}$ $x = 50 - \frac{79.55}{12}y \quad \text{---(2)}$ <p>Sub (2) into (1),</p> $\frac{\left(50 - \frac{79.55}{12}y\right)^2}{400} - \frac{y^2}{2100} = 1$ <p>Using GC, <math>y = 4.5108</math> or <math>y = 10.639</math> (N.A.)</p> <p><math>\therefore</math> Minimum diameter <math>= 2 \times 4.5108 \approx 9.02\text{cm}</math> (3 s.f.)</p>