

Chapter	Content	Examples
Chapter 1: Electronic Systems	Main parts of electronic systems: Input Subsystem, Process Subsystem, Output Subsystem	Calculators, Microphones, hairdryer, ect
	<p>Block Diagram (eg thermometer)</p> <pre> graph LR     subgraph Input_Subsystem [Input Subsystem]         TS[Temperature sensor]     end     subgraph Process_Subsystem [Process Subsystem]         PC[Processing circuits]     end     subgraph Output_Subsystem [Output Subsystem]         LED_Buz[LED, Buzzer]     end     TS --&gt; PC     PC --&gt; LED_Buz                     </pre>	
	<p>How electronic systems are presented:</p> <p>Block Diagrams (see above): Provides overview of system</p> <p>Circuit Diagram: Gives information on how the circuit is built, and contains values, components and the way it is connected</p>	<p>Circuit Diagram:</p>
	<p>How does information flow in electronic systems?</p> <p>Electronic systems can only process info in the form of electric signals (voltage/currents that carry info)</p> <p>non electrical info(input) -&gt; Electrical info (process) -&gt; non electric info (output)</p>	<p>Analogue signals: 0 to 5V</p> <p>Digital signals: 0 OR 5V</p>
Chapter 2: Current Electricity	<p>Voltage: Comes in 2 forms</p> <p>Electromotive force (EMF): Total voltage of batteries connected in series or parallel</p> <p>Effective EMF in series = <math>E_1 + E_2 + E_3 + \dots + E_n</math></p> <p>Effective EMF in parallel = same with all other batteries in parallel (usually of same voltage)</p> <p>Potential Difference (P.D.): Work done to drive a unit charge through a component or in between 2 points in a circuit</p>	

	<p>Current</p> <p>Rate of flow of Electric Charge</p> <p>Conventional current flow: From positive to negative terminal (mostly used)</p> <p>Electron flow: From negative to positive terminal</p> $I = \frac{Q}{t}$ <p>I - Current (A)</p> <p>Q - Charge (Coulomb) (C)</p> <p>t - Time in seconds (s)</p> <p>* Current rating: Maximum current a conductor can carry without overheating or being damaged</p>	
	<p>Resistance</p> <p>A measure of how difficult it is for a current to flow through a component</p> $R = \frac{V}{I}$ <p>R - Resistance (Ohm) (<math>\Omega</math>)</p> <p>V - Voltage across component (V)</p> <p>I - Current (A)</p> <p>Ohm's law</p> <p>Current in a metallic conductor is directly proportional to P.D. across conductor (Linear I-V graph, start from origin)</p> <p>Non-ohmic conductors are not linear or not starting from the origin</p>	<p>Ohmic conductors: Resistor</p> <p>Non-Ohmic conductors: Filament Bulb, Semiconductor Diode</p>
	<p>Heating effect of Current</p> <p>Heat is produced when current flows through a component</p> <p>Heat is bad as it can cause electronic components to overheat and be damaged, energy is also wasted</p> <p>Power: Rate of Energy conversion</p> $P = IV \text{ or } P = \frac{E}{t}$	

	<p>Formula can be rearranged to <math>P = I^2 R</math>  or <math>P = \frac{V^2}{R}</math>  V - Voltage across component (V)  I - Current (A)  R - Resistance (Ohm) (<math>\Omega</math>)  E - Amount of energy converted (J)  t - Time in seconds (s)</p> <p>Power rating: Maximum power at which a component can be used without being damaged  *Pick power rating of 2x the calculated value</p>	<p>If power dissipated is 0.20W, pick resistor with 0.5W power rating</p>
	<p>Energy  <math>E = VIt</math>  E - Amount of energy converted (J)  V - Voltage across component (V)  I - Current (A)  t - Time in seconds (s)</p> <p>Energy efficiency: The percentage of input energy that is converted to useful energy  Efficiency = useful power output/power input x 100%</p>	
<p>Chapter 3: Resistors</p>	<p>Resistance of a conductor is affected by 4 factors</p> <ul style="list-style-type: none"> <li>- Resistivity of material</li> <li>- Length of conductor (Longer length, higher resistance)</li> <li>- Cross-Sectional area of conductor (Larger cross-sectional area, lesser resistance)</li> <li>- Temperature</li> </ul> <p>Formula: <math>R = \frac{\rho l}{A}</math>  R - Resistance (Ohm) (<math>\Omega</math>)  P - Resistivity of material (<math>\Omega\text{m}</math>)  l - Length of material (m)  A - Cross sectional area (<math>\text{m}^2</math>)</p>	

Types of resistors: Fixed resistors,  
Variable resistors

Fixed resistors: Carbon, Wire-wound  
Differences:

Carbon	Wire-wound
Low power applications	High-power applications
Low temperature stability	High temperature stability
Typical power rating range of 0.1W - 2W	Typical power rating range of 2W - 500W
Low cost	High cost

Variable resistors: Trimpot, Potentiometer.  
ect

How to determine value of resistor:  
Resistor Colour Code: Series of 4  
coloured bands on Carbon resistor  
From left to right:  
1st and 2nd band: Number  
3rd band: Multiplier (no. of 0)  
4th band: Percentage tolerance (eg  $\pm 5\%$ )

E24 series: Calculate value needed, then  
choose a value closest to the calculated  
value from the E24 series

\*Selection of Resistors:

- For non-BJTs, pick value more than  
calculated one (reduce current to prevent  
overloading/damage)
- For BJTs, pick value less than  
calculated one (increase current flowing  
through transistor before BJT, make  $I_B$   
large enough to push BJT to saturation)

Resistor with band colours  
yellow purple orange gold:  $47k\Omega$   
 $\pm 5\%$

If a  $124\Omega$  resistor value is  
calculated, use a  $130\Omega$  resistor  
from E24 series

	<p>Resistors in series/parallel</p> <p>In series:</p> $R_{eff} = R_1 + R_2 + \dots + R_n$ <p>In parallel:</p> $\frac{1}{R_{eff}} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}$	
	<p>Power rating (Resistors)</p> <p>If temperature is high enough, can cause resistor to overheat (damage resistor)</p>	<p>Resistor with power rating of 0,25W can only withstand 0.25W</p> <p>It is good practice to pick power rating 2x of calculated value (eg 0.5W)</p>
<p>Chapter 4: Circuit Theories</p>	<p>Common terms used to describe a circuit:</p> <p>Circuits - Consists of electrical components connected together with wires, provides one or more paths for current to flow</p> <p>Source - It provides the e.m.f. needed to move electric charges around the circuit.</p> <p>Load - A component which converts electrical energy supplied by a source into other forms</p> <p>Open/Closed circuit - A circuit without/with a continuous path linking the positive terminal to the negative terminal of a source.</p> <p>Short Circuit- -A low-resistance path that is usually undesirable and harmful.</p> <p>Overloading - occurs when current exceeds current rating</p>	

### Voltage and current in series and parallel

Voltage/Current in series:

$$V = V_1 + V_2 + V_3$$

$$I = I_1 = I_2$$

Voltage/Current in parallel:

$$V = V_1 = V_2 = V_3$$

$$I = I_1 + I_2 + I_3$$

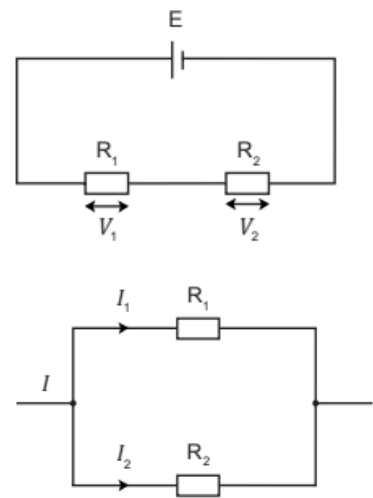
### Voltage/Current Divider

Voltage Divider:

$$V_1 = \frac{R_1}{R_1 + R_2} \times E$$

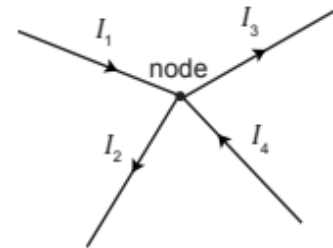
Current Divider:

$$I_2 = \frac{R_2}{R_1 + R_2} \times I$$



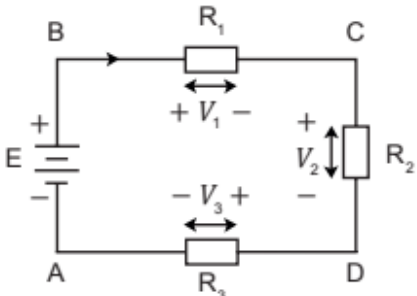
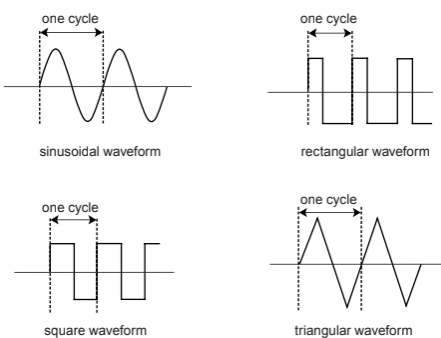
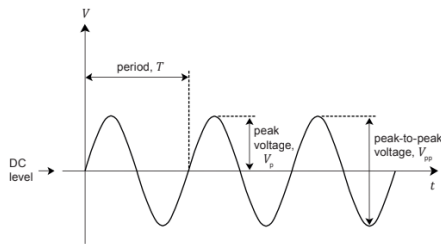
### Kirchhoff Current/Voltage Law

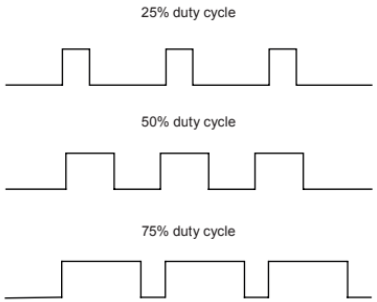
KCL: Sum of all current entering and leaving a node = 0, current that enter the node is positive, current that leaves the node is negative



$$I_1 + I_4 = I_2 + I_3$$

$$0 = I_1 + I_4 - I_2 - I_3$$

	<p>KVL: Sum of all voltages in closed loop = 0, voltage increase in loop direction is positive, voltage decrease in loop direction is negative</p> <p>* When no V, use IR as substitute</p>	 $E = V_1 + V_2 + V_3$ $0 = E - V_1 - V_2 - V_3$
Chapter 5: Alternating Currents	<p>Direct Current (DC): Current flows in 1 direction, terminals do not change polarity</p> <p>Alternating Current (AC): Current changes directions periodically (Terminals change polarity)</p>	<p>DC: Batteries</p> <p>AC: AC Generators</p>
	<p>Types of AC Waveforms</p> <p>Periodic: Sinusoidal, Rectangular, Square, Triangular</p> <p>Non-Periodic: Waveforms that do not repeat themselves (eg microphone signals)</p> <p>Waveforms are generated by Function Generator, waveforms can be observed via <b>Oscilloscope</b></p>	<p>Periodic waveforms</p> 
	<p>Describing AC waveforms</p> <p>DC Level: Voltage level which waveform oscillates about</p> <p>Peak voltage (<math>V_p</math>): Highest point from DC level</p> <p>Peak-to-Peak voltage (<math>V_{pp}</math>): Lowest to highest point</p>	

	<p>Duty cycle: Percentage of rectangular waveform when waveform is at higher level</p> <p>Period: Time taken to complete 1 cycle of waveform</p> <p>Frequency: Number of complete cycles created every second</p> <p>Formula: <math>f = \frac{1}{T}</math></p> <p>f - Frequency (Hz)</p> <p>T - Period (s)</p>	
	<p>Duty cycle is the percentage of the period of a rectangular waveform when it is at the higher voltage level</p> <p>Power supplied to a device can be controlled by adjusting Duty cycle</p> <p>Duty cycle = <math>\frac{t_{high}}{T} \times 100\%</math></p>	 <p>The image shows three rectangular waveforms stacked vertically. The top waveform is labeled '25% duty cycle' and shows a pulse that is high for one-quarter of its period. The middle waveform is labeled '50% duty cycle' and shows a pulse that is high for half of its period. The bottom waveform is labeled '75% duty cycle' and shows a pulse that is high for three-quarters of its period.</p>
<p>Chapter 6: Capacitors</p>	<p>Capacitors consists of 2 metal plates separated by a Dielectric</p> <p>Dielectric: insulating material separating two metal plates</p> <p>Charging: Safety precautions: connect a resistor between the 2 metal plates to discharge. It cannot be discharged directly as it will cause a large current spike which will damage the capacitor</p> <p>Determining how much charge a Capacitor can store</p> <p><math>C = \frac{Q}{V}</math></p> <p>C - Capacitance (F)</p> <p>Q - Charge stored (Columb) (C)</p> <p>V - Voltage (V)</p>	<p>Uses of Capacitors: Voltage-Smoothing (Full-wave rectifier), Coupling Capacitors (BJT amplifier)</p>



	<p>Factors affecting capacitance:</p> <ul style="list-style-type: none"><li>- Area of metal plates (larger = more capacitance)</li><li>- Distance separating plates (longer, less capacitance)</li><li>- Material used for Dielectric</li></ul>									
	<p>Types of Capacitors: Polarised, Non-polarised</p> <p>Electrolytic (Polarised): Short leg (-ve), -ve sign side, values on capacitor</p> <p>Ceramic (pF) (Non-polarised): No polarity To identify value: first 2 digits in pF, third digit multiplier (no of zeros after the 2 digits)</p> <p>Difference:</p> <table><tr><th>Polarised</th><th>Non-polarised</th></tr><tr><td>Have large capacitances</td><td>Have small capacitances</td></tr><tr><td>Have fixed positive and negative terminals</td><td>No fixed positive or negative terminals</td></tr><tr><td>Typically larger in size</td><td>Typically smaller in size</td></tr></table> <p>E24 series: Calculate value needed, then choose a value closest to the calculated value from the E24 series (Similar to resistors)</p> <p>Maximum working voltage: Voltage applied on capacitor must not exceed or capacitor may be damaged</p>	Polarised	Non-polarised	Have large capacitances	Have small capacitances	Have fixed positive and negative terminals	No fixed positive or negative terminals	Typically larger in size	Typically smaller in size	<p>472 is 4700pF</p> <p>If a 467nF capacitor value is calculated, use a 470nF capacitor from E24 series</p>
Polarised	Non-polarised									
Have large capacitances	Have small capacitances									
Have fixed positive and negative terminals	No fixed positive or negative terminals									
Typically larger in size	Typically smaller in size									
	<p>Capacitors in series/parallel</p> <p>In series:</p> $\frac{1}{C_{eff}} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}$									

In parallel:

$$C_{eff} = C_1 + C_2 + \dots + C_n$$

RC Circuits

$$\tau = RC$$

$\tau$  - Time constant in seconds (s)

R - Resistance ( $\Omega$ )

C - Capacitance (F)

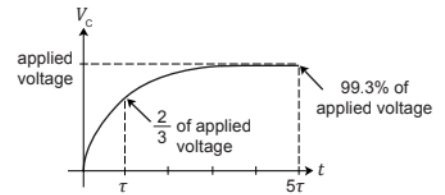
Resistor affects charging/discharging time of a capacitor

Determines charging/discharging time of capacitor

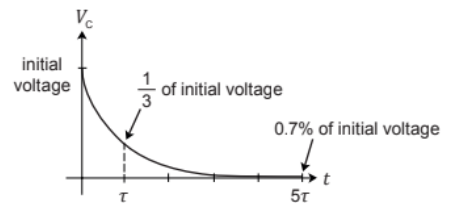
Charging/discharging:

Time	Charging	Discharging
$\tau$	$\frac{2}{3} V_{cc}$	$\frac{1}{3} V_{cc}$
$5\tau$	Fully charged	Fully discharged

Charging graph:



Discharging graph:



## Chapter 7: Semiconductor Diodes

Structure of a Diode

Types of Semiconductors after Doping:

N-type, P-type

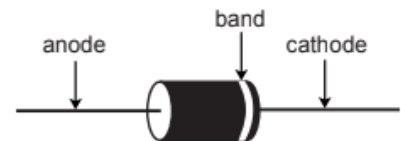
N-type: rely on negative charges to conduct (Cathode)

P-type: rely on positive charges to conduct (Anode)

They are joined together to form a PN Junction Diode

Anode(+): side without band

Cathode(-): side with band



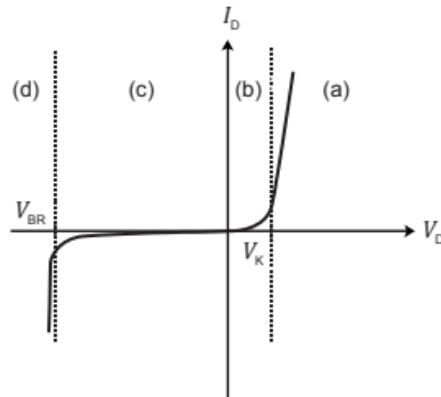
Behaviour of a Diode

Forward-biased mode: Current can pass through easily

Reverse-biased mode: Does not allow current to pass through easily

Ideal Diode: Forward-biased is perfect conductor (0 resistance), Reverse-biased is perfect insulator (infinite resistance)

Practical Diode (normal, LED, Zener) has 4 operating regions:



Forward-biased (a): Current flows through diode

Knee Voltage  $V_K$  (b): minimum amount of voltage needed for current to flow through diode (Usually 0.7V)

Reverse-biased (c): Most current cannot flow through diode (have reverse leakage current)

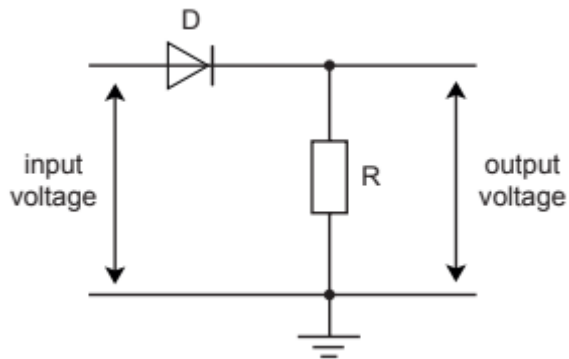
Breakdown voltage (d): current rapidly flows at opposite direction; can damage Diode

Resistor should be connected in series with diode (Current-limiting resistor)

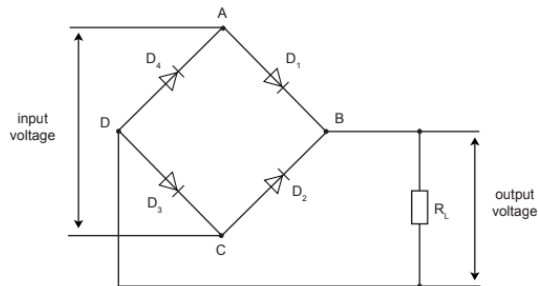
\* Resistor must be more than calculated value when selecting from E24 series

## Rectifiers

Half-wave rectifier: Only positive half of output passes through

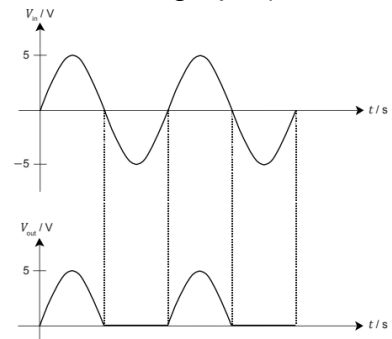


Full-wave rectifier: Output remains positive

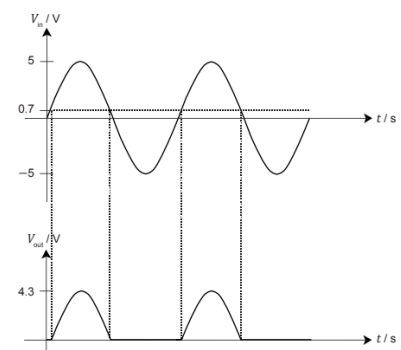


\* Practical diodes - account for Knee voltage ( $V_k$ ) when drawing output waveform graph

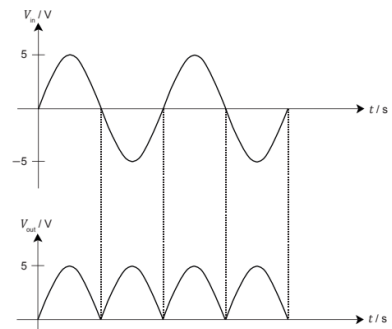
## Ideal Diode graph (Half-wave)



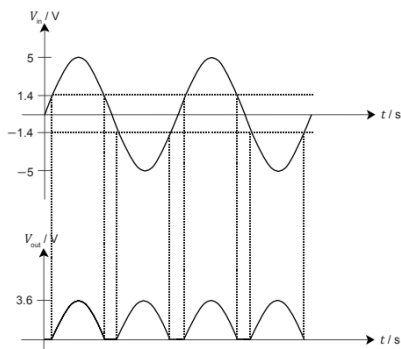
## Practical Diode graph (Half-wave)



## Ideal Diode graph (Full-wave)



## Practical Diode graph (Full-wave)



## LEDs

How to identify: Short lead/flat side is cathode pin (-)

### Reasons to use LEDs

- Longer lifespan, better energy efficiency

### Disadvantages:

- More costly than incandescent light bulbs

\* Connect LEDs in series with a current-limiting resistor

Value of current limiting Resistor:

$$R = \frac{V - V_F}{I}$$

R - Resistance (Ohm) ( $\Omega$ )

V - Voltage source (V)

$V_F$  - Forward Voltage (V)

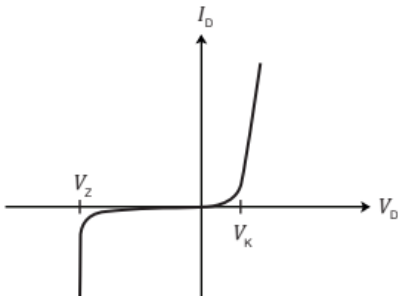
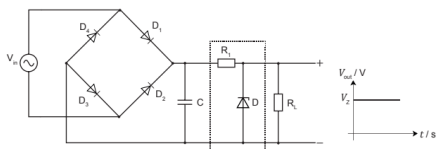
I - Current (A)

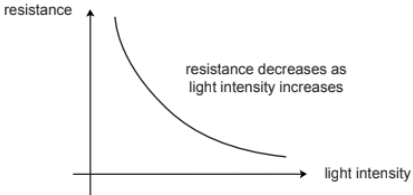
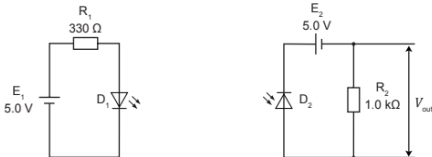
## 7-Segment Display

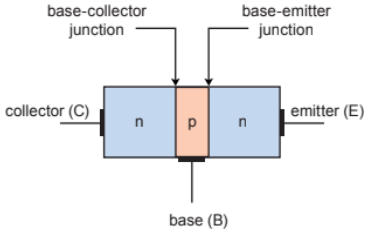
Consists of 7 segments with a decimal point

It has 2 types: Common-Anode and Common-Cathode

	<b>Common-Anode (CA)</b>	<b>Common-Cathode (CC)</b>
COM Pins	To $V_{CC}$	To GND (0V)
Segments (On)	To GND (0V)	To $V_{CC}$ through resistors
Segments (Off)	To $V_{CC}$ through resistors	To GND (0V)

	<p><b>Zener Diode</b></p> <p>Similar to normal Diode but can operate in breakdown region In breakdown region, voltage across Zener diode becomes <math>V_Z</math></p> <p><b>Analysis of circuit with Zener Diode</b>  1. Voltage-Divider to compare voltage with <math>V_Z</math> (Measure voltage across <math>R_L</math>)  When <math>V &lt; V_Z</math>, <math>V_{out} = 0V</math>  When <math>V &gt; V_Z</math>, <math>V_{out} = V_Z</math> (Voltage across load also same)  2. Power dissipated in Zener Diode  If not in breakdown, <math>P = 0W</math>  If in breakdown, <math>P = V \times I</math>  (<math>V_Z \times</math> Current across load)</p> <p><b>Applications on Rectifier (Full-Wave):</b></p> <ul style="list-style-type: none"> <li>- Capacitors to smoothen output voltage waveform (unable to keep up with fast-changing output of rectifier, hence output varies over a smaller range)</li> <li>- Zener Diode to hold output voltage at <math>V_Z</math> (become steady DC voltage)</li> </ul>	<p><b>Characteristic Graph</b></p>  
<p>Chapter 8: Input and Output Transducers</p>	<p><b>Transducers</b></p> <p>Input Transducers: Convert non-electrical information/quantities into electrical signals/quantities (Sensors)</p> <p>Output Transducers: Convert electrical signals/quantities into non-electrical signals/quantities</p> <p><b>Thermistors/LDRs</b></p> <p>Thermistor: 2 Types</p> <ul style="list-style-type: none"> <li>- PTC (Positive temperature coefficient): When temperature increase, resistance increase</li> </ul>	<p>Input Transducers: Thermistor, LDR, IR and Photodiode, ect</p> <p>Output Transducers: Motor, Buzzer, Speaker, ect</p> <p><b>NTC Thermistor/LDR Graph:</b></p>

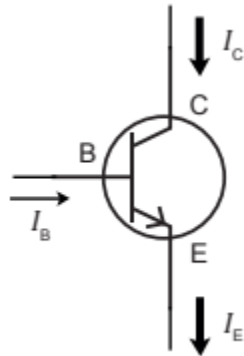
	<p>(Resistance proportional to temperature)</p> <ul style="list-style-type: none"> <li>- NTC (Negative temperature coefficient): When temperature increase, resistance increase (Resistance inversely proportional to temperature)</li> </ul> <p>* NTC mostly used</p> <p>Light-Dependent Resistor (LDR): When Light intensity increase, resistance decreases (Resistance inversely proportional to Light intensity)</p> <p>Both are commonly used in Voltage-Dividers</p>	 <p>A graph with 'resistance' on the vertical axis and 'light intensity' on the horizontal axis. A curve starts high on the y-axis and slopes downwards to the right, approaching the x-axis. A text label 'resistance decreases as light intensity increases' points to the curve.</p>
	<p>IR Diode and Photodiode</p> <p>IR diode</p> <ul style="list-style-type: none"> <li>- produces IR rays</li> </ul> <p>Photodiode</p> <ul style="list-style-type: none"> <li>- receives IR rays (allow current to flow through)</li> </ul> <p>* Photodiode is to be connected in Reverse-Biased</p> <p>Applications: Counter for items passing through, ect</p>	<p>How to use:</p>  <p>Two circuit diagrams are shown. The left diagram shows an IR diode (D1) in series with a resistor (R1, 330 Ω) connected to a 5.0 V battery (E1). The right diagram shows a photodiode (D2) in reverse bias, connected to a 5.0 V battery (E2) and a load resistor (R2, 1.0 kΩ). The output voltage (Vout) is measured across the resistor.</p>
	<p>Microphone</p> <p>(has positive/negative terminals)</p> <p>Converts sound energy to electrical energy</p> <p>shorter probe is -ve terminal</p> <p>Buzzer</p> <p>(has positive/negative terminals)</p> <p>Converts electrical energy to sound energy</p> <p>shorter probe is -ve terminal</p>	

	<p>Loudspeaker Converts electrical energy to sound energy * requires an amplifier to produce sound</p> <p>DC Motors Converts electrical energy to mechanical energy</p> <p>Electromechanical Relays Uses electromagnets to switch on other circuits comes in SPST and SPDT (SPDT: has NO (Normally open) and NC (Normally closed)) Allows low-power circuits to switch on high-power circuits</p> <p>* Both DC Motor and Electromechanical Relay requires a Flyback Diode to prevent damage Flyback Diode: Protect the transistor from a large negative voltage spike when it is turned off</p>	
Chapter 9: Bipolar Junction Transistors	<p>BJTs It consists of 3 layers of Semiconductors arranged in either PNP or NPN Centre layer is known as the Base (B) while the thicker ends are known as the Collector (C) and the Emitter (E) *BJTs can be damaged if wrongly connected, so refer to Datasheet for pin configurations</p> <p>Structure: P-type Semiconductor sandwiched by N-type Semiconductor (NPN) or Vice Versa (PNP)</p> <p>How it works: Smaller current at Base allows a larger current to flow from Collector to Emitter</p>	<p>NPN BJT Structure</p> 



## Analysis of BJT

### Current



$I_C$  - Collector Current

$I_B$  - Base Current

$I_E$  - Emitter Current

when

$I_B = 0A$ ,  $I_C$  and  $I_E = 0A$ ,  $V_{CE} = V_{CC}$  (Cutoff region)

when  $I_B$  increases,  $I_C$  and  $I_E$  increases

(Active region)

after  $I_B$  reaches a certain level

(Saturation region),  $I_C$  and  $I_E$  remains

nearly constant at maximum,  $V_{CE}$

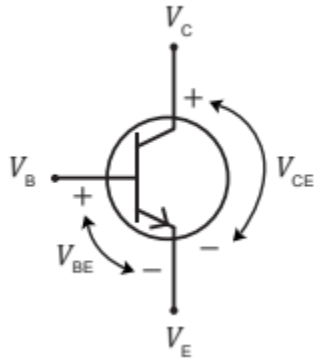
reaches saturation value

$$I_E = I_B + I_C$$

DC current gain

$$\beta_{DC} = \frac{I_C}{I_B}$$

## Voltage



Base-Emitter voltage ( $V_{BE}$ )

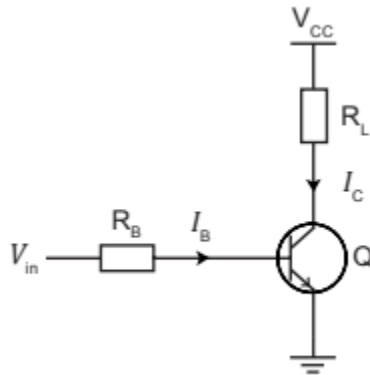
Voltage across base and emitter

To allow current to flow from base to emitter,  $V_{BE}$  must be larger than  $V_F$  (Base activation voltage) if not  $I_B = 0A$

Collector-Emitter voltage ( $V_{CE}$ )

Voltage across collector and emitter

## BJT as a switch/driver



### Advantages

Switch: Faster switching speeds, no wear and tear, no contact bounce (learn at Chapter 13)

Driver: allow smaller current to drive a load that needs large current

### Analysis

(To find resistance  $R_B$ )

\*  $V_{CE(sat)}$ ,  $R_C$ ,  $\beta_{DC}$ ,  $V_{BE}$  given

Step 1: Use an suitable value of  $V_{CC}$

Step 2: Determine  $I_{C(sat)}$

$$I_{C(sat)} = \frac{V_{CC} - V_{CE(sat)}}{R_C}$$

(Assume  $I_C = I_{C(sat)}$  and  $V_{CE} = V_{CE(sat)}$ )

\* If any other components above Collector of BJT, subtract their voltages on the numerator)

Step 3: Find  $I_B$

$$I_B = \frac{I_C}{\beta_{DC}}$$

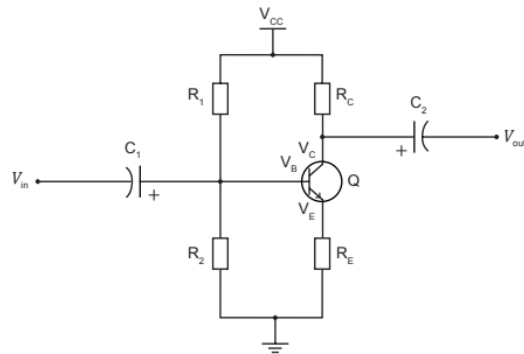
Step 4: Find  $R_B$

$$R_B = \frac{V_{in} - V_{BE}}{I_B}$$

$R_B$  value from E24 must be lower than calculated value (higher value =  $R_B$  may not be big enough)

\*  $R_B$  acts as current-limiting resistor, prevent  $I_B$  from being too large and damaging BJT

## BJT as a amplifier



\* Capacitors (Polarised) are coupling capacitors  
(allow AC signals to pass through but not DC voltages)

Analysis  
(To find the following)

\*  $V_{BE}$  given

$V_B$  :

$$V_B = \frac{R_2}{R_1 + R_2} \times V_{CC}$$

(Voltage-Divider)

$V_E$  :

$$V_E = V_B - V_{BE}$$

$I_E$  :

$$I_E = \frac{V_E}{R_E}$$

$I_C$  : assume  $I_C = I_E$

$V_C$  :

$$V_C = V_{CC} - I_C R_C$$

$V_{CE}$  :

$$V_{CE} = V_C - V_E$$

$|A_V|$  (Voltage gain):

Either

$$|A_V| = \frac{V_{PP} \text{ Output}}{V_{PP} \text{ Input}}$$

Or

$$|A_V| \approx \frac{R_C}{R_E}$$

\*Output waveform is inverted

Capacitor in parallel to  $R_E$  ( $C_3$ ): Bypassed capacitor to increase voltage gain of amplifier

Darlington Pair

2 BJTs connected together

DC current gain of Darlington pair =  $\beta_{DC}$  of both BJTs multiplied

Advantages: Creates a larger current gain than a single BJT

Disadvantages:

- Slower switching speeds of BJTs
- Base activation voltage is doubled
- Bigger voltage drop