

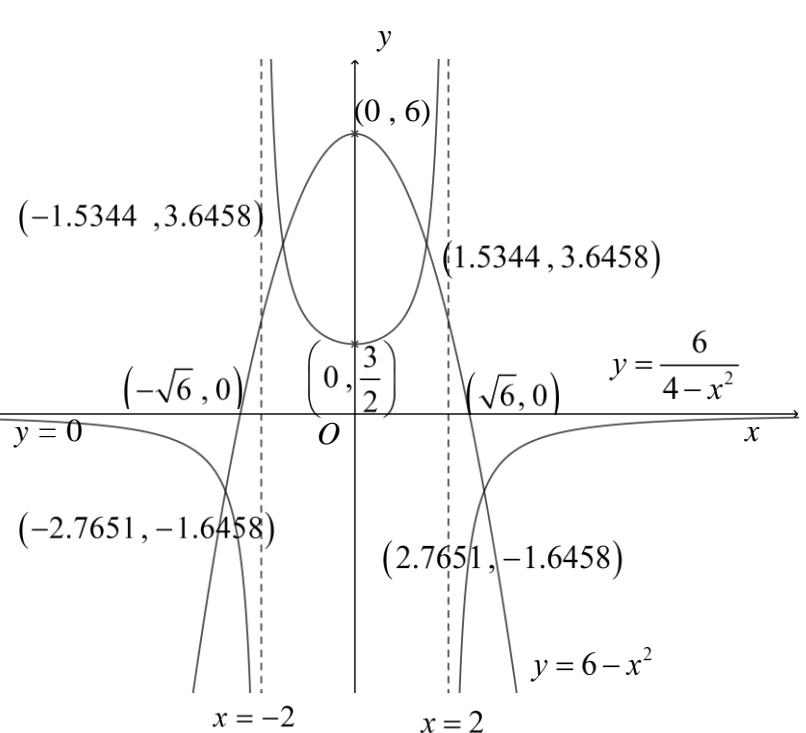
**St Andrew's Junior College**  
**2022 Preliminary Examination**  
**H2 Mathematics Paper 1 (9758/01)**

<b>Q</b>	<b>Solution</b>	<b>Mark scheme</b>
1(i)	$4(x+y)^2 + (x-y)^2 = 20 \quad \text{---- (1)}$ <p>Differentiate (1) with respect to <math>x</math></p> $8(x+y)\left(1+\frac{dy}{dx}\right) + 2(x-y)\left(1-\frac{dy}{dx}\right) = 0$ $8(x+y) + 8(x+y)\frac{dy}{dx} + 2(x-y) - 2(x-y)\frac{dy}{dx} = 0$ $10x + 6y + (8x + 8y - 2x + 2y)\frac{dy}{dx} = 0$ $\frac{dy}{dx} = -\frac{10x + 6y}{6x + 10y} = -\frac{2(5x + 3y)}{2(3x + 5y)}$ $\frac{dy}{dx} = -\frac{5x + 3y}{3x + 5y} \quad (\text{Shown})$	
(ii)	<p>Since the tangents are perpendicular to the line <math>y = x</math>, hence the gradient of tangents = -1</p> $\frac{dy}{dx} = -\frac{5x + 3y}{3x + 5y} = -1$ $5x + 3y = 3x + 5y$ $2x = 2y$ $x = y \quad \text{--- (*)}$ <p>Substituting into (1);</p>	

Q	Solution	Mark scheme
	$4(x+x)^2 + (x-x)^2 = 20$ $4(2x)^2 = 20$ $4x^2 = 5$ $x^2 = \frac{5}{4}$ $x = \pm \frac{\sqrt{5}}{2}$ <p>Given <math>y = x</math> from (*)</p> <p>When <math>x = \frac{\sqrt{5}}{2}</math>, <math>y = \frac{\sqrt{5}}{2}</math></p> <p>When <math>x = -\frac{\sqrt{5}}{2}</math>, <math>y = -\frac{\sqrt{5}}{2}</math></p> <p>Hence, the points are <math>\left(\frac{\sqrt{5}}{2}, \frac{\sqrt{5}}{2}\right)</math> and <math>\left(-\frac{\sqrt{5}}{2}, -\frac{\sqrt{5}}{2}\right)</math></p> $y - \frac{\sqrt{5}}{2} = -\left(x - \frac{\sqrt{5}}{2}\right)$ $= -x + \frac{\sqrt{5}}{2}$ $y = -x + \sqrt{5}$	

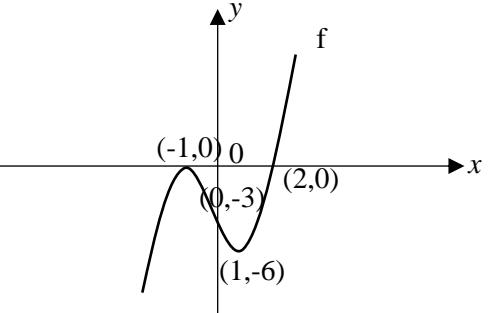
Q	Solution	Mark scheme
	$\begin{aligned}y - \left(-\frac{\sqrt{5}}{2}\right) &= -\left(x - \left(-\frac{\sqrt{5}}{2}\right)\right) \\&= -x - \frac{\sqrt{5}}{2} \\y &= -x - \sqrt{5}\end{aligned}$ <p>The equation of the tangents are <math>y = -x + \sqrt{5}</math> and <math>y = -x - \sqrt{5}</math>.</p>	

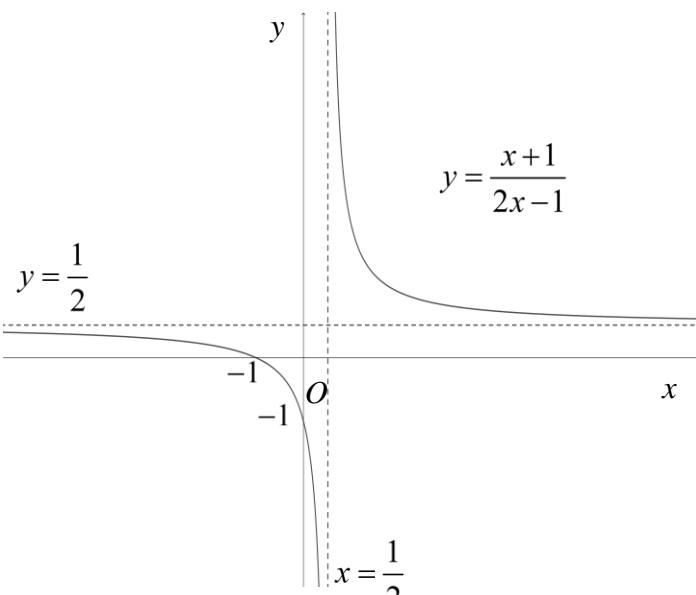
Q	Solution	Mark scheme
2(i)	$y = \frac{6}{4-x^2} = \frac{6}{(2-x)(2+x)}$ <p>Asymptotes are <math>x = 2, x = -2, y = 0</math></p> <p>Intersections with axes:</p> <p>When <math>x = 0</math>, <math>y = \frac{6}{2(2)} = \frac{3}{2}</math> (Also the stationary point)</p> $y = 6 - x^2$ <p>Intersections with axes:</p> <p>When <math>x = 0</math>, <math>y = 6 \Rightarrow (0, 6)</math></p> <p>When <math>y = 0</math>,</p> $6 - x^2 = 0$ $x^2 = 6$ $x = \sqrt{6} \text{ or } -\sqrt{6}$ $(\sqrt{6}, 0) \text{ or } (-\sqrt{6}, 0)$	

Q	Solution	Mark scheme
2 (i)	 <p style="text-align: center;"><math>y = \frac{6}{4-x^2}</math></p> <p style="text-align: center;"><math>y = 6 - x^2</math></p>	
(ii)	<p>The <math>x</math>-coordinates of the intersection points between the graphs <math>y = \frac{6}{4-x^2}</math> and <math>y = 6 - x^2</math> are <math>-2.77</math>, <math>-1.53</math>, <math>1.53</math> and <math>2.77</math> (to 3 sig. fig.)</p> <p>For <math>\frac{6}{4-x^2} &lt; 6 - x^2</math></p> <p>From the graph above,  <math>-2.77 &lt; x &lt; -2</math> or <math>-1.53 &lt; x &lt; 1.53</math> or <math>2 &lt; x &lt; 2.77</math></p>	
(iii)	Replace $x$ with $-x$ ,	

Q	Solution	Mark scheme
	<p>after the reflection about the <math>y</math>-axis, the solution is: <math>\Rightarrow 2 &lt; x &lt; 2.77</math> or <math>-1.53 &lt; x &lt; 1.53</math> or <math>-2.77 &lt; x &lt; -2</math></p> <p>Replace <math>x</math> with <math>x+4</math>,</p> <p>after the translation of 4 units in the negative <math>x</math> direction,</p> $\Rightarrow 2 < x+4 < 2.77 \text{ or } -1.53 < x+4 < 1.53 \text{ or } -2.77 < x+4 < -2$ $\Rightarrow -2 < x < -1.23 \text{ or } -5.53 < x < -2.47 \text{ or } -6.77 < x < -6$ <p>the solution set is therefore</p> $\{x \in \mathbb{R} : -6.77 < x < -6 \text{ or } -5.53 < x < -2.47 \text{ or } -2 < x < -1.23\}$	

Q	Solution	Mark Scheme
3(i)	Given $f(-1) = f(2) = 0$ but $-1 \neq 2$ and $-1, 2 \in D_f$ , $f$ is not a one-to-one function. Hence, $f$ does not have an inverse.	
(ii)	<p>Let <math>y = f(x) = ax^3 + bx^2 + cx + d</math></p> <p>Curve passes through <math>(0, -3)</math></p> $d = -3$ $y = f(x) = ax^3 + bx^2 + cx - 3$ <p>Curve passes through <math>(-1, 0)</math></p> $-a + b - c = 3 \quad \text{----- (1)}$ <p>Curve passes through <math>(2, 0)</math></p> $8a + 4b + 2c = 3 \quad \text{----- (2)}$ $\frac{dy}{dx} = 3ax^2 + 2bx + c$ <p>Tangent to the curve at <math>x = 1</math> is a horizontal line, <math>\frac{dy}{dx} = 0</math>,</p> $3a + 2b + c = 0 \quad \text{----- (3)}$ <p>Solving (1), (2) and (3) using GC, <math>a = \frac{3}{2}</math>, <math>b = 0</math>, <math>c = -\frac{9}{2}</math>,</p> <p>The equation of the curve is <math>y = f(x) = \frac{3}{2}x^3 - \frac{9}{2}x - 3</math></p>	

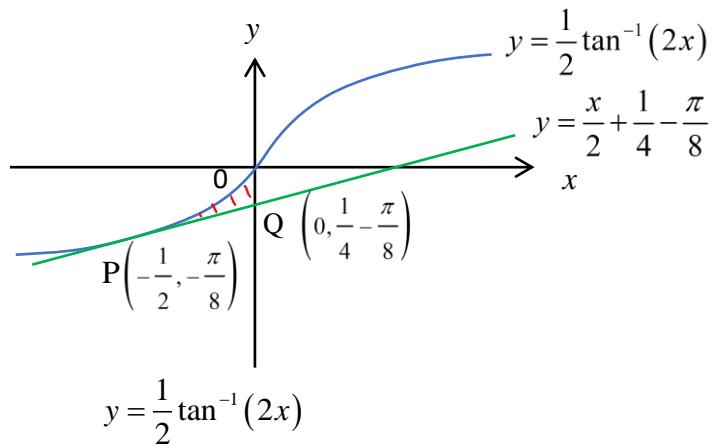
Q	Solution	Mark Scheme
(iii)		
(iv)	Smallest $k = 1$	
(v)	The graphs of $y = f(x)$ and $y = f^{-1}(x)$ are reflections of each other about the line $y = x$ .	
(vi)	<p>Since the graphs <math>y = f(x)</math>, <math>y = f^{-1}(x)</math> and <math>y = x</math> intersect at the same point, the solution of <math>f^{-1}(x) = f(x)</math> is the same as the solution of <math>f(x) = x</math>.</p> $\Rightarrow \frac{3}{2}x^3 - \frac{9}{2}x - 3 = x$ $\Rightarrow 3x^3 - 11x - 6 = 0 \text{ (shown)}$ <p>Solving the equation using GC, <math>x = 2.14</math>(3 s.f.) since <math>x \geq 1</math></p>	
(vii)	$R_f = [-6, \infty) \not\subseteq D_g = (-5, \infty)$ Hence $gf$ does not exist	

Q	Solution	Mark Scheme
4 (i)	<p><math>y = \frac{1}{2}</math></p>  $y = \frac{x+1}{2x-1}$	
	<p>From the graph above,</p> $x \leq -1 \text{ or } x > \frac{1}{2}$	

Q	Solution	Mark Scheme
(ii)	$\begin{aligned} & \int_{-2}^0 \left  \frac{x+1}{2x-1} \right  dx \\ &= \int_{-2}^0 \left  \frac{1}{2} + \frac{3}{2(2x-1)} \right  dx \\ &= \int_{-2}^{-1} \left( \frac{1}{2} + \frac{3}{2(2x-1)} \right) dx + \int_{-1}^0 -\left( \frac{1}{2} + \frac{3}{2(2x-1)} \right) dx \\ &= \left[ \frac{1}{2}x + \frac{3}{4} \ln 2x-1  \right]_{-2}^{-1} - \left[ \frac{1}{2}x + \frac{3}{4} \ln 2x-1  \right]_{-1}^0 \\ &= \left[ -\frac{1}{2} + \frac{3}{4} \ln(3) - \left( -1 + \frac{3}{4} \ln(5) \right) \right] - \left[ 0 - \left( -\frac{1}{2} + \frac{3}{4} \ln 3 \right) \right] \\ &= -\frac{1}{2} + \frac{3}{4} \ln 3 - \left( -1 + \frac{3}{4} \ln(5) \right) - \frac{1}{2} + \frac{3}{4} \ln 3 \\ &= -1 + \frac{3}{2} \ln 3 + 1 - \frac{3}{4} \ln 5 \\ &= \frac{3}{2} \ln 3 - \frac{3}{4} \ln 5 \text{ (Shown)} \end{aligned}$	

Q	Solution	Mark Scheme
5(i)	<p>When <math>x = -\frac{1}{2}</math>, <math>y = \frac{1}{2} \tan^{-1}(-1) = \frac{1}{2} \left( -\frac{\pi}{4} \right) = -\frac{\pi}{8}</math>.</p> <p>When <math>x = 0</math>, <math>y = \frac{0}{2} + \frac{1}{4} - \frac{\pi}{8} = \frac{1}{4} - \frac{\pi}{8}</math></p> <p>y-coordinate of <math>P = -\frac{\pi}{8}</math>;</p> <p>y-coordinate of <math>Q = \frac{1}{4} - \frac{\pi}{8}</math></p>	

(ii)



$$y = \frac{1}{2} \tan^{-1}(2x)$$

$$2y = \tan^{-1}(2x)$$

$$\tan(2y) = 2x$$

$$x = \frac{1}{2} \tan(2y)$$

Required volume

$$\begin{aligned}
&= \pi \int_{-\frac{\pi}{8}}^0 \left( \frac{1}{2} \tan(2y) \right)^2 dy - \frac{\pi}{3} \left( \frac{1}{2} \right)^2 \left[ \frac{1}{4} - \frac{\pi}{8} - \left( -\frac{\pi}{8} \right) \right] \\
&= \frac{\pi}{4} \int_{-\frac{\pi}{8}}^0 \tan^2(2y) dy - \frac{\pi}{48} \\
&= \frac{\pi}{4} \int_{-\frac{\pi}{8}}^0 (\sec^2(2y) - 1) dy - \frac{\pi}{48} \\
&= \frac{\pi}{4} \left[ \frac{1}{2} \tan(2y) - y \right]_{-\frac{\pi}{8}}^0 - \frac{\pi}{48} \\
&= \frac{\pi}{4} \left[ 0 - \left( -\frac{1}{2} + \frac{\pi}{8} \right) \right] - \frac{\pi}{48} \\
&= \frac{\pi}{4} \left( \frac{1}{2} - \frac{\pi}{8} \right) - \frac{\pi}{48} \\
&= \frac{\pi}{8} \left( \frac{5}{6} - \frac{\pi}{4} \right) \text{ units}^3
\end{aligned}$$

Alternatively (more tedious mtd) :

Required volume

$$\begin{aligned}
&= \pi \int_{-\frac{\pi}{8}}^0 \left( \frac{1}{2} \tan(2y) \right)^2 dy - \pi \int_{-\frac{\pi}{8}}^{\frac{1-\pi}{8}} 4 \left( y - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^2 dy \\
&= \frac{\pi}{4} \int_{-\frac{\pi}{8}}^0 \tan^2(2y) dy - 4\pi \int_{-\frac{\pi}{8}}^{\frac{1-\pi}{8}} \left( y - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^2 dy \\
&= \frac{\pi}{4} \int_{-\frac{\pi}{8}}^0 (\sec^2(2y) - 1) dy - 4\pi \int_{-\frac{\pi}{8}}^{\frac{1-\pi}{8}} \left( y - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^2 dy \\
&= \frac{\pi}{4} \left[ \frac{1}{2} \tan(2y) - y \right]_{-\frac{\pi}{8}}^0 - 4\pi \left[ \frac{\left( y - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^3}{3} \right]_{-\frac{\pi}{8}}^{\frac{1-\pi}{8}} \\
&= \frac{\pi}{4} \left[ 0 - \left( -\frac{1}{2} + \frac{\pi}{8} \right) \right] - \frac{4}{3}\pi \left[ \left( \frac{1}{4} - \frac{\pi}{8} - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^3 - \left( -\frac{\pi}{8} - \left( \frac{1}{4} - \frac{\pi}{8} \right) \right)^3 \right] \\
&= \frac{\pi}{4} \left( \frac{1}{2} - \frac{\pi}{8} \right) - \frac{4}{3}\pi \left[ \left( \frac{1}{4} \right)^3 \right] \\
&= \frac{\pi}{4} \left( \frac{1}{2} - \frac{\pi}{8} \right) - \frac{\pi}{48} \\
&= \frac{\pi}{8} \left( \frac{5}{6} - \frac{\pi}{4} \right) \text{ units}^3
\end{aligned}$$

6(i)	<p>Using Ratio Theorem,</p> $\overrightarrow{OP} = \frac{(1-\lambda)\mathbf{a} + \lambda\mathbf{b}}{1-\lambda + \lambda}$ $= (1-\lambda)\mathbf{a} + \lambda\mathbf{b}$
	$\cos(\angle AOP) = \frac{\overrightarrow{OA} \cdot \overrightarrow{OP}}{ \overrightarrow{OA}   \overrightarrow{OP} }$ $= \frac{\mathbf{a} \cdot [(1-\lambda)\mathbf{a} + \lambda\mathbf{b}]}{ \mathbf{a}   (1-\lambda)\mathbf{a} + \lambda\mathbf{b} }$ $= \frac{(1-\lambda)\mathbf{a} \cdot \mathbf{a} + \lambda\mathbf{a} \cdot \mathbf{b}}{ \mathbf{a}   (1-\lambda)\mathbf{a} + \lambda\mathbf{b} }$ $= \frac{(1-\lambda) \mathbf{a} ^2 + 0}{ \mathbf{a}   (1-\lambda)\mathbf{a} + \lambda\mathbf{b} }$ <p>since <math>\mathbf{a} \cdot \mathbf{b} = 0</math> as <math>\mathbf{a}</math> and <math>\mathbf{b}</math> are perpendicular</p> $= \frac{(1-\lambda) \mathbf{a} }{ (1-\lambda)\mathbf{a} + \lambda\mathbf{b} } \text{ (shown)}$
(ii)	$[(1-\lambda)\mathbf{a} + \lambda\mathbf{b}] \cdot [(1-\lambda)\mathbf{a} + \lambda\mathbf{b}]$ $= (1-\lambda)\mathbf{a} \cdot (1-\lambda)\mathbf{a} + (1-\lambda)\mathbf{a} \cdot \lambda\mathbf{b} + \lambda\mathbf{b} \cdot (1-\lambda)\mathbf{a} + \lambda\mathbf{b} \cdot \lambda\mathbf{b}$ $= (1-\lambda)^2  \mathbf{a} ^2 + \lambda(1-\lambda)\mathbf{a} \cdot \mathbf{b} + \lambda(1-\lambda)\mathbf{b} \cdot \mathbf{a} + \lambda^2  \mathbf{b} ^2$ $= (1-\lambda)^2  \mathbf{a} ^2 + \lambda^2  \mathbf{b} ^2,$ <p>since <math>\mathbf{a} \cdot \mathbf{b} = 0</math> given that <math>\mathbf{a}</math> and <math>\mathbf{b}</math> are perpendicular</p> <p>(Proven)</p>

Given also that  $OP$  bisects  $\angle AOB$ ,

$$\angle AOP = \frac{\pi}{4},$$

$$\cos \frac{\pi}{4} = \frac{(1-\lambda)|\mathbf{a}|}{|(1-\lambda)\mathbf{a} + \lambda\mathbf{b}|}$$

$$\frac{1}{\sqrt{2}} = \frac{(1-\lambda)|\mathbf{a}|}{|(1-\lambda)\mathbf{a} + \lambda\mathbf{b}|}$$

$$\frac{1}{2} = \frac{(1-\lambda)^2 |\mathbf{a}|^2}{|(1-\lambda)\mathbf{a} + \lambda\mathbf{b}|^2}$$

$$= \frac{(1-\lambda)^2 |\mathbf{a}|^2}{[(1-\lambda)\mathbf{a} + \lambda\mathbf{b}] \cdot [(1-\lambda)\mathbf{a} + \lambda\mathbf{b}]}$$

$$= \frac{(1-\lambda)^2 |\mathbf{a}|^2}{(1-\lambda)^2 |\mathbf{a}|^2 + \lambda^2 |\mathbf{b}|^2}$$

$$(1-\lambda)^2 |\mathbf{a}|^2 + \lambda^2 |\mathbf{b}|^2 = 2(1-\lambda)^2 |\mathbf{a}|^2$$

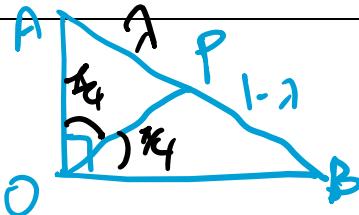
$$\text{Hence } (1-\lambda)^2 |\mathbf{a}|^2 = \lambda^2 |\mathbf{b}|^2$$

$$\frac{|\mathbf{a}|^2}{|\mathbf{b}|^2} = \frac{\lambda^2}{(1-\lambda)^2}$$

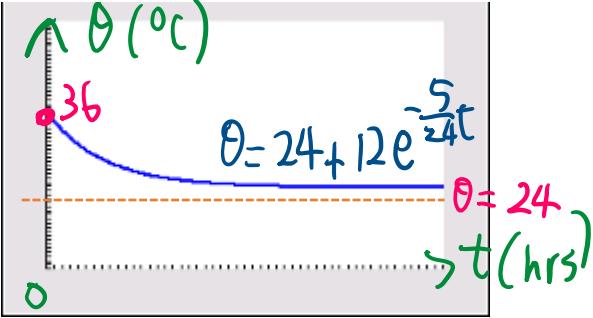
$$\frac{|\mathbf{a}|}{|\mathbf{b}|} = \left| \frac{\lambda}{(1-\lambda)} \right|$$

$$\frac{|\mathbf{a}|}{|\mathbf{b}|} = \pm \frac{\lambda}{1-\lambda} = \frac{\lambda}{1-\lambda}, \text{ reject } -\frac{\lambda}{1-\lambda} \text{ since } 0 < \lambda < 1 \text{ and ratio of length}$$

is positive.



<b>7(i)</b>	<p>The rate of temperature change of a dead animal body is given by</p> $\frac{d\theta}{dt} = -a(\theta - \theta_0), \text{ where } a > 0.$ $\frac{1}{(\theta - \theta_0)} \frac{d\theta}{dt} = -a$ <p>Integrating both sides</p> $\int \frac{1}{\theta - \theta_0} d\theta = -a dt$ $\ln(\theta - \theta_0) = -at + C, \text{ since } \theta - \theta_0 > 0$ <p>where <math>a</math> and <math>C</math> are arbitrary constants.</p> $\theta - \theta_0 = e^{-at+C} = Ae^{-kt}, \text{ where } A = e^C \text{ and } k = a$ $\Rightarrow \theta = \theta_0 + Ae^{-kt} \text{ (Shown)}$	
<b>(ii)</b>	$\theta_0 = 24.$ <p>When <math>t=0</math>, <math>\theta = 36</math> is <math>\frac{d\theta}{dt} = -2.5 \text{ }^{\circ}\text{C}</math>,</p> $\frac{d\theta}{dt} = -k(\theta - \theta_0), \text{ where } k > 0.$ $-2.5 = -k(36-24) \therefore k = \frac{5}{24}$ <p>Using <math>\theta = \theta_0 + Ae^{-kt}</math></p> $36 = 24 + A$ $\therefore A = 12$	

iii	 <p><math>\theta = 24 + 12e^{-\frac{5}{24}t}</math></p>	
iv	<p>A constant rate of decrease is not possible as the temperature of the body of the dead animal will become <math>0^{\circ}\text{C}</math> or even negative at some point in time, which is lower than the surrounding temperature.</p>	
8(a)	<p>Since the equation has all real coefficients, complex roots occur in complex conjugate pairs.</p> <p>Since <math>z = \frac{5}{3} - \frac{\sqrt{11}}{3}i</math> is a complex root <math>\Rightarrow</math> its conjugate <math>z = \frac{5}{3} + \frac{\sqrt{11}}{3}i</math> exists as a root of the equation.</p>	

	$(z - (-2))(z - \left(\frac{5}{3} - \frac{\sqrt{11}}{3}i\right))(z - \left(\frac{5}{3} + \frac{\sqrt{11}}{3}i\right)) = 0$ $(z+2)(z^2 - \frac{10}{3}z + 4) = 0 \quad \text{--- (*)}$ $z^3 - \frac{4}{3}z^2 - \frac{8}{3}z + 8 = 0$ $\Rightarrow 3z^3 - 4z^2 - 8z + 24 = 0 \quad \text{--- (#)}$ $\therefore a = -4, b = -8, c = 24$	
8b (i)	$w = \frac{e^{i\theta} + e^{i\phi}}{e^{i\theta} - e^{i\phi}}$ $= \frac{e^{i\left(\frac{\theta+\phi}{2}\right)} + e^{i\left(\frac{\theta-\phi}{2}\right)}}{e^{i\left(\frac{\theta+\phi}{2}\right)} - e^{i\left(\frac{\theta-\phi}{2}\right)}}$ $= \frac{2 \cos\left(\frac{\theta-\phi}{2}\right)}{2i \sin\left(\frac{\theta-\phi}{2}\right)}$ $= \frac{1}{i} \cot\left(\frac{\theta-\phi}{2}\right)$ $= -i \cot\left(\frac{\theta-\phi}{2}\right)$ $= e^{-\frac{i\pi}{2}} \cot\left(\frac{\theta-\phi}{2}\right)$	

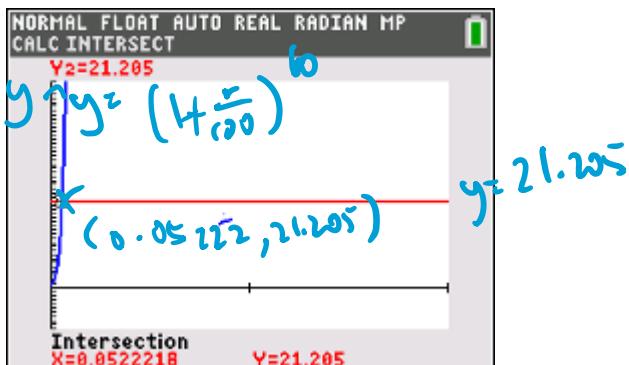
**Alternative method:**

$$\begin{aligned}
 w &= \frac{e^{i\theta} + e^{i\phi}}{e^{i\theta} - e^{i\phi}} \\
 &= \frac{(\cos \theta + i \sin \theta) + (\cos \phi + i \sin \phi)}{(\cos \theta + i \sin \theta) - (\cos \phi + i \sin \phi)} \\
 &= \frac{(\cos \theta + \cos \phi) + i(\sin \theta + \sin \phi)}{(\cos \theta - \cos \phi) + i(\sin \theta - \sin \phi)} \\
 &= \frac{2 \cos\left(\frac{\theta+\phi}{2}\right) \cos\left(\frac{\theta-\phi}{2}\right) + i \left(2 \sin\left(\frac{\theta+\phi}{2}\right) \cos\left(\frac{\theta-\phi}{2}\right)\right)}{-2 \left(\sin\left(\frac{\theta+\phi}{2}\right) \sin\left(\frac{\theta-\phi}{2}\right)\right) + i \left(2 \cos\left(\frac{\theta+\phi}{2}\right) \sin\left(\frac{\theta-\phi}{2}\right)\right)} \\
 &= \frac{\cos\left(\frac{\theta-\phi}{2}\right) \left(\cos\left(\frac{\theta+\phi}{2}\right) + i \sin\left(\frac{\theta+\phi}{2}\right)\right)}{\sin\left(\frac{\theta-\phi}{2}\right) \left(-\sin\left(\frac{\theta+\phi}{2}\right) + i \cos\left(\frac{\theta+\phi}{2}\right)\right)} \\
 &= \cot\left(\frac{\theta-\phi}{2}\right) \frac{\left(\cos\left(\frac{\theta+\phi}{2}\right) + i \sin\left(\frac{\theta+\phi}{2}\right)\right)}{i \left(\cos\left(\frac{\theta+\phi}{2}\right) + i \sin\left(\frac{\theta+\phi}{2}\right)\right)} \\
 &= \frac{1}{i} \cot\left(\frac{\theta-\phi}{2}\right) = e^{i\left(-\frac{\pi}{2}\right)} \cot\left(\frac{\theta-\phi}{2}\right) \text{ (Shown)}
 \end{aligned}$$

b (ii)	$ w  = \left  e^{-\frac{i\pi}{2}} \cot\left(\frac{\theta-\phi}{2}\right) \right  = \left  e^{-\frac{i\pi}{2}} \right  \left  \cot\left(\frac{\theta-\phi}{2}\right) \right  = \left  \cot\left(\frac{\theta-\phi}{2}\right) \right $ $\arg(w) = \begin{cases} -\frac{\pi}{2}, & \text{if } \cot\left(\frac{\theta-\phi}{2}\right) > 0 \\ \frac{\pi}{2}, & \text{if } \cot\left(\frac{\theta-\phi}{2}\right) < 0 \end{cases}$
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9(i)	<p>Let <math>T_n</math> denote the distance covered by a runner from Besto on the <math>n</math>th training session.</p> <p>Since <math>T_n</math> follows an arithmetic progression with common difference 250,</p> $T_n = 400 + 250(n-1)$ <p>Given that <math>T_n \geq 20000</math>,</p> $400 + 250(n-1) \geq 20000$ <table border="1" data-bbox="300 589 1051 759"> <thead> <tr> <th><math>n</math></th><th><math>T_n</math></th></tr> </thead> <tbody> <tr> <td>79</td><td><math>19900 &lt; 20\ 000</math></td></tr> <tr> <td>80</td><td><math>20150 &gt; 20\ 000</math></td></tr> <tr> <td>81</td><td><math>20400 &gt; 20\ 000</math></td></tr> </tbody> </table> <p>The minimum value of <math>n</math> is 80.</p>	$n$	$T_n$	79	$19900 < 20\ 000$	80	$20150 > 20\ 000$	81	$20400 > 20\ 000$	
$n$	$T_n$									
79	$19900 < 20\ 000$									
80	$20150 > 20\ 000$									
81	$20400 > 20\ 000$									
(i) Alt	<p>Let <math>T_n</math> denote the distance covered by a runner from Besto on the <math>n</math>th training session.</p> <p>Since <math>T_n</math> follows an arithmetic progression with common difference 250,</p> $T_n = 400 + 250(n-1)$ <p>Given that <math>T_n \geq 20000</math>,</p> $400 + 250(n-1) \geq 20000$ $250(n-1) \geq 19600$ $n-1 \geq 78.4$ $n \geq 79.4$									

	The minimum number of sessions for a runner to complete at least 20 km is 80.		
(ii)	$n$	Total distance covered in the $n$ th stage	
	1	$2(50)$	
	2	$\begin{aligned} &2(50) + 2(150) \\ &= 2(50) + 2(3)(50) \\ &= 2(50)[1+3] \end{aligned}$	
	3	$\begin{aligned} &2(50) + 2(150) + 2(450) \\ &= 2(50) + 2(3)(50) + 2(3)^2(50) \\ &= 2(50)[1+3+3^2] \end{aligned}$	
	...	...	
	$n$	$\begin{aligned} &2(50) + 2(3)(50) + 2(3)^2(50) + \dots + 2(3)^{n-1}(50) \\ &= 2(50)[1+3+3^2+\dots+3^{n-1}] \\ &= 100\left[\frac{1(3^n-1)}{3-1}\right] \\ &= 50(3^n-1) \end{aligned}$	
(iii)	To find the number of completed stages: $50(3^n-1) \leq 42000$		
	$n$	$50(3^n-1)$	
	5	$12100 < 42000$	
	6	$36400 < 42000$	
	7	$109300 > 42000$	
	After completing 6 stages, the runner completed 36 400 m.		

	<p>Distance remaining = <math>42\ 000 - 36\ 400 = 5600</math>  Given that <math>OP_7 = 50 \times 3^6 = 36450 &gt; 5600</math>, the runner from Besto is running away from <math>O</math> at a distance of 5600 m and has not reached <math>P_7</math>.</p>	
(iv)	<p>On the 10<sup>th</sup> session, a runner from Choco would have completed <math>400(1.1)^9</math> m  From 11<sup>th</sup> session onwards, using the new plan designed by Choco, a runner will complete <math>400(1.1)^9 \left(1 + \frac{r}{100}\right)^{60}</math>.</p> $400(1.1)^9 \left(1 + \frac{r}{100}\right)^{60} \geq 20000$ $\left(1 + \frac{r}{100}\right)^{60} \geq 21.205$ <p>Let <math>x = \frac{r}{100}</math></p>  <p>From GC, <math>x \geq 0.05222</math></p>	

	$\frac{r}{100} \geq 0.05222$ $r \geq 5.222 = 5.22 \text{ (to 3 sf)}$	
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<b>10i</b>	$X = (13 - 11\sin \theta)(13 - 11\cos \theta)$ $\frac{dX}{d\theta} = (-11\cos \theta)(13 - 11\cos \theta) + (13 - 11\sin \theta)(11\sin \theta)$ $= -143\cos \theta + 121\cos^2 \theta + 143\sin \theta - 121\sin^2 \theta$ $= 143\sin \theta - 143\cos \theta + 121(\cos \theta - \sin \theta)(\cos \theta + \sin \theta)$ $= 143\sin \theta - 143\cos \theta - 121(\sin \theta - \cos \theta)(\cos \theta + \sin \theta)$ $= 11(13(\sin \theta - \cos \theta)) - 121(\sin \theta - \cos \theta)(\cos \theta + \sin \theta)$ $= 11(\sin \theta - \cos \theta)(13 - 11\sin \theta - 11\cos \theta) \text{ (Shown)}$	
<b>(ii)</b>	$\frac{dX}{d\theta} = 0$ $\Rightarrow 11(\sin \theta - \cos \theta)(13 - 11\sin \theta - 11\cos \theta) = 0$ $\Rightarrow \sin \theta - \cos \theta = 0 \text{ or } 13 - 11\sin \theta - 11\cos \theta = 0$ $\Rightarrow \tan \theta = 1 \text{ or } 11\sin \theta + 11\cos \theta = 13 \dots\dots (\#)$  Using R-formula to equation (1), $\sqrt{2} \sin(\theta + \alpha) = \frac{13}{11}$ where $\tan \alpha = 1$ $\Rightarrow \alpha = \frac{\pi}{4}$	

	$\therefore \sqrt{2} \sin(\theta + \frac{\pi}{4}) = \frac{13}{11}$ $\sin(\theta + \frac{\pi}{4}) = \frac{13}{11\sqrt{2}} \quad \text{--- (*)}$ <p>where <math>k = \frac{13}{11\sqrt{2}}</math> and <math>\alpha = \frac{\pi}{4}</math></p> <p>Solving <math>\tan \theta = 1</math>,</p> $\Rightarrow \theta = \frac{\pi}{4}$ $\Rightarrow \sin(\theta + \frac{\pi}{4}) = 0.83567$ $\Rightarrow \theta + \frac{\pi}{4} = 0.98935$ $\Rightarrow \theta = 0.20396 \text{ since } 0 \leq \theta \leq \frac{\pi}{4}$									
iii	<p>Using first derivative test</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td><math>\theta</math></td><td>0.78</td><td><math>\frac{\pi}{4}</math></td><td>0.79</td></tr> <tr> <td><math>\frac{dX}{d\theta}</math></td><td><math>0.215 &gt; 0</math></td><td>0</td><td><math>-0.183 &lt; 0</math></td></tr> </table> <p>Hence <math>X</math> is a maximum when <math>\theta_1 = \frac{\pi}{4}</math></p> <p>Using first derivative test</p>	$\theta$	0.78	$\frac{\pi}{4}$	0.79	$\frac{dX}{d\theta}$	$0.215 > 0$	0	$-0.183 < 0$	
$\theta$	0.78	$\frac{\pi}{4}$	0.79							
$\frac{dX}{d\theta}$	$0.215 > 0$	0	$-0.183 < 0$							

	<table border="1"> <tr> <td><math>\theta</math></td><td>0.203</td><td>0.20396</td><td>0.204</td></tr> <tr> <td><math>\frac{dX}{d\theta}</math></td><td>-0.06997 &lt; 0</td><td>0</td><td>0.00318 &gt; 0</td></tr> </table>	$\theta$	0.203	0.20396	0.204	$\frac{dX}{d\theta}$	-0.06997 < 0	0	0.00318 > 0	
$\theta$	0.203	0.20396	0.204							
$\frac{dX}{d\theta}$	-0.06997 < 0	0	0.00318 > 0							
	Hence $X$ is a minimum when $\theta_2 = 0.20396$									
	<p><b>Alternatively, use second derivative test</b></p> $\frac{dX}{d\theta} = -143\cos\theta + 121\cos^2\theta + 143\sin\theta - 121\sin^2\theta$ $\frac{d^2X}{d\theta^2} = 143\sin\theta - 242\cos\theta\sin\theta + 143\cos\theta - 242\sin\theta\cos\theta$ $= 143\sin\theta - 484\cos\theta\sin\theta + 143\cos\theta$ $\left. \frac{d^2X}{d\theta^2} \right _{\theta=\frac{\pi}{4}} = -39.8 < 0$ $\left. \frac{d^2X}{d\theta^2} \right _{\theta=0.20396} = 72.999 > 0$									
iv	Hence $X$ is a maximum when $\theta = \frac{\pi}{4}$ and $X$ is a minimum when $\theta = 0.20396$ .	The greatest possible value of $X$ is 27.3 m <sup>2</sup> when $\theta = \frac{\pi}{4}$ .								

<p>To find the minimum area covered by grass, we have to use the maximum area <math>X</math>.</p> <p>The area covered by grass</p> $= 676 - 4(27.3) - \pi(11)^2$ $= 187 \text{ m}^2.$	
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