

H2 Mathematics (9758) Chapter 6A 3D Vector Geometry (Lines) Discussion Questions Solutions

Level 1

- 1 Find a <u>vector equation</u>, a <u>cartesian equation</u> and a set of <u>parametric equations</u> of the following lines:
 - (a) passing through the point with position vector $7\mathbf{i} + 2\mathbf{j} 4\mathbf{k}$ and parallel to $\mathbf{i} 3\mathbf{j} + \mathbf{k}$,
 - (b) passing through the points (1, -2, 1) and (0, 4, 9),

(c)	passing through the point $(3,0,2)$ and parallel to the line x	$z = \frac{y+4}{3}, z = 1.$
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Q1	Vector Equation	Cartesian Equation	Parametric Equation
(a)	$l_1: \mathbf{r} = \begin{pmatrix} 7\\2\\-4 \end{pmatrix} + \lambda \begin{pmatrix} 1\\-3\\1 \end{pmatrix}, \lambda \in \mathbb{R}$	$x - 7 = \frac{y - 2}{-3} = z + 4$	$x = 7 + \lambda$ $y = 2 - 3\lambda$
		OR $x-7 = \frac{2-y}{3} = z+4$	$z = -4 + \lambda$, $\lambda \in \mathbb{R}$
(b)	$l_{2}: \mathbf{r} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -6 \\ -8 \end{pmatrix}, \mu \in \mathbb{R}$	$x - 1 = \frac{y + 2}{-6} = \frac{z - 1}{-8}$	$x = 1 + \mu$ $y = -2 - 6\mu$
		OR $x-1 = -\frac{y+2}{6} = \frac{1-z}{8}$	$z=1-8\mu$, $\mu\in\mathbb{R}$
(c)	$l_{5}: \mathbf{r} = \begin{pmatrix} 3 \\ 0 \\ 2 \end{pmatrix} + \gamma \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}, \gamma \in \mathbb{R}$	$x-3=\frac{y}{3}, \ z=2$	$x = 3 + \gamma$ $y = 3\gamma$ $z = 2, \ \gamma \in \mathbb{R}$
			$z=2, \ \gamma \in \mathbb{R}$

2 For the following pairs of lines, determine whether they are parallel lines, intersecting lines or skew lines. Find the coordinates of the point of intersection for intersecting lines.

(a)
$$\frac{x-1}{3} = \frac{y-1}{-2} = z-1$$
, $\mathbf{r} = -2\mathbf{i} + 3\mathbf{j} + \alpha (2\mathbf{i} + 3\mathbf{j} - \mathbf{k})$ where α is a real parameter.

(b)
$$\mathbf{r} = -2\mathbf{i} + 3\mathbf{j} + \lambda(2\mathbf{i} + 3\mathbf{j} - \mathbf{k})$$
, $\mathbf{r} = (-1 - 6\mu)\mathbf{i} + (3 - 9\mu)\mathbf{j} + (3\mu)\mathbf{k}$, where λ and μ are real parameters.

Q2	Solution
(a)	$l_1: \frac{x-1}{3} = \frac{y-1}{-2} = z - 1 \Longrightarrow \mathbf{r} = \begin{pmatrix} 1\\1\\1 \end{pmatrix} + \beta \begin{pmatrix} 3\\-2\\1 \end{pmatrix}, \ \beta \in \mathbb{R}$
	$l_2: \mathbf{r} = \begin{pmatrix} -2\\ 3\\ 0 \end{pmatrix} + \alpha \begin{pmatrix} 2\\ 3\\ -1 \end{pmatrix}, \ \alpha \in \mathbb{R}$
	$\begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}$ is not parallel to $\begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix}$, therefore l_1 and l_2 are not parallel lines.
	Let $\begin{pmatrix} 1\\1\\1\\1 \end{pmatrix} + \beta \begin{pmatrix} 3\\-2\\1 \end{pmatrix} = \begin{pmatrix} -2\\3\\0 \end{pmatrix} + \alpha \begin{pmatrix} 2\\3\\-1 \end{pmatrix} \Rightarrow \begin{cases} 1+3\beta = -2+2\alpha & -(1)\\1-2\beta = 3+3\alpha & -(2)\\1+\beta = -\alpha & -(3) \end{cases}$
	$(3) \times 2: 2 + 2\beta = -2\alpha \qquad -(4)$
	(2)+(4): $3=3+\alpha \implies \alpha=0$ From (3), $\beta=-1$
	Put $\beta = -1$, $\alpha = 0$ in equation (1): LHS = $1 - 3 = -2$
	RHS = -2 = LHS Thus (1) holds.
	$\therefore l_1$ and l_2 are intersecting lines and the coordinates of their point of intersection are $(-2,3,0)$.
	Alternative
	$\int -2\alpha + 3\beta = -3 \qquad -(5)$
	Re-arranging, we get $\begin{cases} -2\alpha + 3\beta = -3 & -(5) \\ -3\alpha - 2\beta = 2 & -(6) \\ \alpha + \beta = -1 & -(7) \end{cases}$
	$\alpha + \beta = -1$ $-(7)$
	Using GC, to solve equations (5), (6) and (7), $\alpha = 0$, $\beta = -1$.
	$\therefore l_1$ and l_2 are intersecting lines and the coordinates of their point of intersection are
	(-2,3,0).

(b)
$$l_{3}: \mathbf{r} = -2\mathbf{i} + 3\mathbf{j} + \lambda(2\mathbf{i} + 3\mathbf{j} - \mathbf{k}) \qquad l_{4}: \mathbf{r} = (-1 - 6\mu)\mathbf{i} + (3 - 9\mu)\mathbf{j} + (3\mu)\mathbf{k}$$
$$l_{3}: \mathbf{r} = \begin{pmatrix} -2\\ 3\\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 2\\ 3\\ -1 \end{pmatrix}, \quad \lambda \in \mathbb{R} \qquad l_{4}: \mathbf{r} = \begin{pmatrix} -1\\ 3\\ 0 \end{pmatrix} + \mu \begin{pmatrix} -6\\ -9\\ 3 \end{pmatrix}, \quad \mu \in \mathbb{R}$$
Since $\mathbf{d}_{4} = \begin{pmatrix} -6\\ -9\\ 3 \end{pmatrix} = -3 \begin{pmatrix} 2\\ 3\\ -1 \end{pmatrix} = -3\mathbf{d}_{3}, \quad \mathbf{d}_{3} / / \mathbf{d}_{4}, \text{ thus } l_{3} \text{ and } l_{4} \text{ are parallel lines.}$ If l_{3} and l_{4} are the same line, then there exist $\lambda \in \mathbb{R}$ such that
$$\begin{pmatrix} -1\\ 3\\ 0 \end{pmatrix} = \begin{pmatrix} -2\\ 3\\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 2\\ 3\\ -1 \end{pmatrix} \Rightarrow \quad \begin{cases} 1 = 2\lambda\\ 0 = \lambda\\ 0 = \lambda\\ 0 = \lambda \end{cases}$$
Since the values of λ are inconsistent for all 3 equations, $(-1,3,0)$ does not lie on l_{3} . Thus l_{2} and l_{4} are distinct parallel lines.

3 The lines
$$l_1$$
 and l_2 have equations $\mathbf{r} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$ and $\mathbf{r} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$ respectively,

where *s* and *t* are real parameters.

- (i) Show that l_1 passes through the point A(2,-1,-4), but that l_2 does not.
- (ii) Find the acute angle between l_2 and the line joining A(2,-1,-4) and B(1,-1,1).

Solution **Q3 (i)** $l_1: \mathbf{r} = \begin{pmatrix} \mathbf{s} \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} \mathbf{l} \\ 2 \\ 4 \end{pmatrix}, \quad \mathbf{s} \in \mathbb{R} \qquad l_2: \mathbf{r} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}, \quad t \in \mathbb{R}$ When s = -1, $\mathbf{r} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} -1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix}$. Therefore, l_1 passes through (2, -1, -4). Alternatively, Let $\begin{pmatrix} 3\\1\\0 \end{pmatrix} + s \begin{pmatrix} 1\\2\\4 \end{pmatrix} = \begin{pmatrix} 2\\-1\\-4 \end{pmatrix}$ for some $s \in \mathbb{R} \implies \begin{cases} 3+s=2 \implies s=-1\\1+2s=-1 \implies s=-1\\4s=-4 \implies s=-1 \end{cases}$ The value of s are consistent for all 3 equations, so l_1 passes through (2, -1, -4). Let $\begin{pmatrix} 1\\-1\\1 \end{pmatrix} + t \begin{pmatrix} 2\\1\\-1 \end{pmatrix} = \begin{pmatrix} 2\\-1\\-4 \end{pmatrix}$ for some $t \in \mathbb{R} \implies \begin{cases} 1+2t=2 \implies t=\frac{1}{2}\\-1+t=-1 \implies t=0\\1-t=-4 \implies t=5 \end{cases}$ The values of t are inconsistent for all 3 equations, so l_2 does not pass through $\overrightarrow{AB} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 5 \end{pmatrix}$ (ii) The line joining A(2,-1,-4) and B(1,-1,1) has direction vector $\begin{vmatrix} 1 \\ 0 \end{vmatrix}$. Let θ be the required acute angle. $\cos \theta = \frac{\left| \begin{pmatrix} -1 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 5 \end{pmatrix} \right|}{\sqrt{6}\sqrt{26}} = \frac{7}{\sqrt{6}\sqrt{26}} \implies \theta = 55.9^{\circ} (1 \text{ d.p.})$

- 4 Given that point *A* has position vector $\begin{pmatrix} 2\\0\\1 \end{pmatrix}$ and point *B* has position vector $\begin{pmatrix} 1\\0\\2 \end{pmatrix}$, find the
 - (i) length of the projection of \overrightarrow{AB} onto the z-axis,
 - (ii) projection vector of \overrightarrow{AB} onto the z-axis.

Q4	Solution
(i)	$\overrightarrow{AB} = \overrightarrow{OB} - \overrightarrow{OA} = \begin{pmatrix} 1\\0\\2 \end{pmatrix} - \begin{pmatrix} 2\\0\\1 \end{pmatrix} = \begin{pmatrix} -1\\0\\1 \end{pmatrix}$
	$\therefore \text{ Length of projection of } \overrightarrow{AB} \text{ onto } z \text{-axis } = \left \frac{\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}}{\sqrt{(0+0+1)}} \right = \frac{ 0+0+1 }{\sqrt{1}} = 1 \text{ unit}$
(ii)	Projection vector of \overrightarrow{AB} onto z-axis $= \frac{\begin{pmatrix} -1\\0\\1 \end{pmatrix} \begin{pmatrix} 0\\0\\1 \end{pmatrix}}{\sqrt{(0+0+1)}} \begin{pmatrix} 0\\0\\1 \end{pmatrix} = \begin{pmatrix} 0\\0\\1 \end{pmatrix}$

5 Find the coordinates of the foot of perpendicular from the point P(7, -2, 4) to the line $\mathbf{r} = (2 + \lambda)\mathbf{i} + (3 - 2\lambda)\mathbf{j} + \mathbf{k}$, where λ is a real parameter.

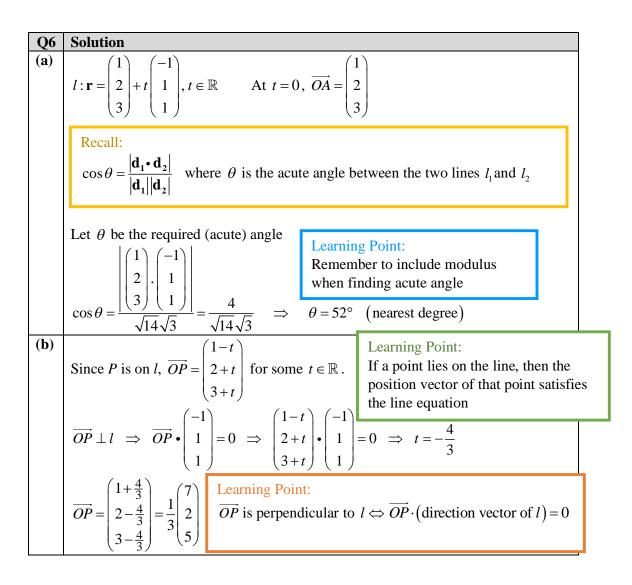
Q5 Solution $\mathbf{r} = \begin{pmatrix} 2\\3\\1 \end{pmatrix} + \lambda \begin{pmatrix} 1\\-2\\0 \end{pmatrix}, \ \lambda \in \mathbb{R}$ Let *F* be the foot of perpendicular from *P* to the line. Since *F* lies on the line, $\overrightarrow{OF} = \begin{pmatrix} 2+\lambda\\3-2\lambda\\1 \end{pmatrix}$ for some $\lambda \in \mathbb{R}$. $\overrightarrow{PF} = \begin{pmatrix} 2+\lambda\\3-2\lambda\\1 \end{pmatrix} - \begin{pmatrix} 7\\-2\\4 \end{pmatrix} = \begin{pmatrix} -5+\lambda\\5-2\lambda\\-3 \end{pmatrix}$ Since *PF* is perpendicular to the line, $\overrightarrow{PF} \cdot \begin{pmatrix} 1\\-2\\0 \end{pmatrix} = 0 \implies (-5+\lambda) - 2(5-2\lambda) = 0 \implies \lambda = 3$ Substitute $\lambda = 3$ into \overrightarrow{OF} : The position vector of *F* is $\overrightarrow{OF} = \begin{pmatrix} 5\\-3\\1 \end{pmatrix}$ and the coordinates of *F* is (5, -3, 1)

Level 2

6 The equation of a straight line *l* is $\mathbf{r} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$, where *t* is a parameter.

The point *A* on *l* is given by t = 0, and the origin of the position vectors is *O*.

- (a) Calculate the acute angle between *OA* and *l*, giving your answer correct to the nearest degree.
- (b) Find the position vector of the point P on l such that OP is perpendicular to l.
- (c) A point Q on l is such that the length of OQ is 5 units. Find the two possible position vectors of Q.
- (d) The points *R* and *S* on *l* are given by $t = \lambda$ and $t = 2\lambda$ respectively. Show that there is no value of λ for which *OR* and *OS* are perpendicular.

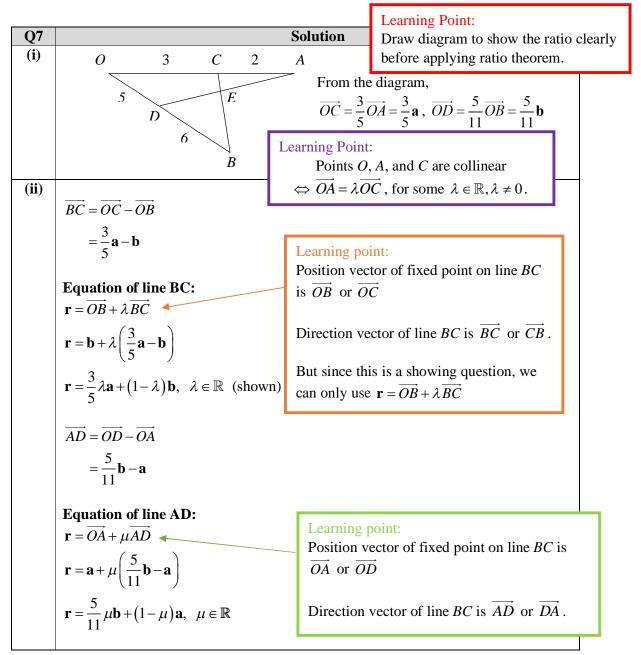


(c)
Since
$$Q$$
 is on l , $\overline{OQ} = \begin{pmatrix} 1-t \\ 2+t \\ 3+t \end{pmatrix}$ for some $t \in \mathbb{R}$.
 $|\overline{OQ}| = \sqrt{(1-t)^2 + (2+t)^2 + (3+t)^2} = 5$
 $\Rightarrow 3t^2 + 8t - 11 = 0$
 $\Rightarrow (3t + 11)(t - 1) = 0$
 $\therefore t = -\frac{11}{3}$ or $t = 1$
 $\overline{OQ} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{11}{3} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 14 \\ -5 \\ -2 \end{bmatrix}$ or $\overline{OQ} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 4 \end{bmatrix}$
(d)
 $\overline{OR} = \begin{bmatrix} 1-\lambda \\ 2+\lambda \\ 3+\lambda \end{bmatrix}, \quad \overline{OS} = \begin{bmatrix} 1-2\lambda \\ 2+2\lambda \\ 3+2\lambda \end{bmatrix}$
 $= (1-\lambda)(1-2\lambda) + (2+\lambda)(2+2\lambda) + (3+\lambda)(3+2\lambda)$
 $= (1-\lambda)(1-2\lambda) + (2+\lambda)(2+2\lambda) + (3+\lambda)(3+2\lambda)$
 $= 1-2\lambda - \lambda + 2\lambda^2 + 4 + 4\lambda + 2\lambda + 2\lambda^2 + 9 + 6\lambda + 3\lambda + 2\lambda^2$
 $= 6\lambda^2 + 12\lambda + 14$
 $= 6[(\lambda+1)^2 - 1^2] + 14$
 $= 6[(\lambda+1)^2 - 1^2] + 14$
 $= 6[(\lambda+1)^2 + 8 > 0 \text{ for all } \lambda \in \mathbb{R}$
Since there is no value of λ such that $\overline{OR} \cdot \overline{OS} = 0$
Microsoft expendence is $|\Delta| | |A| + 2\lambda + 2\lambda^2 + 9 + 6\lambda + 3\lambda + 2\lambda^2| = 0$
 $(1-\lambda)(1-2\lambda) + (2+\lambda)(2+2\lambda) + (3+\lambda)(3+2\lambda) = 0$
 $1-2\lambda - \lambda + 2\lambda^2 + 4 + 4\lambda + 2\lambda + 2\lambda^2 + 9 + 6\lambda + 3\lambda + 2\lambda^2 = 0$
 $(1-\lambda)(1-2\lambda) + (2+\lambda)(2+2\lambda) + (3+\lambda)(3+2\lambda) = 0$
 $1-2\lambda - \lambda + 2\lambda^2 + 4 + 4\lambda + 2\lambda + 2\lambda^2 + 9 + 6\lambda + 3\lambda + 2\lambda^2 = 0$
 $6\lambda^2 + 12\lambda + 14 = 0$
Since discriminant $= 12^2 - 4(6)(14) = -192 < 0$, there is no real roots for $6\lambda^2 + 12\lambda + 14$. Hence, there is no value of λ for which OR and OS are perpendicular.

7 N2015/I/7

Referred to the origin *O*, points *A* and *B* have position vectors **a** and **b** respectively. Point *C* lies on *OA*, between *O* and *A*, such that OC: CA = 3: 2. Point *D* lies on *OB*, between *O* and *B*, such that OD: DB = 5: 6.

- (i) Find the position vectors \overrightarrow{OC} and \overrightarrow{OD} , giving your answers in terms of **a** and **b**. [2]
- (ii) Show that the vector equation of the line *BC* can be written as $\mathbf{r} = \frac{3}{5}\lambda \mathbf{a} + (1-\lambda)\mathbf{b}$, where λ is a parameter. Find in a similar form the vector equation of the line *AD* in terms of a parameter μ . [3]
- (iii) Find, in terms of a and b, the position vector of the point *E* where the lines *BC* and *AD* meet and find the ratio *AE* : *ED*.



$=\frac{3}{5}\lambda \mathbf{a} + (1-\lambda)\mathbf{b} = \frac{5}{11}\mu\mathbf{b} + (1-\mu)\mathbf{a}$ Useful technique: Solving 2 unknowns in a given equation involving vectors, $\frac{3}{5}\lambda = 1-\mu \qquad \text{or}$ $1-\lambda = \frac{5}{11}\mu(2)$	(iii)	Position vector of E, int	ersection of A	AD and BC		
$1 - \lambda = -\frac{1}{2} \mu(2)$		5 11		parallel vectors,	unknowns in a giver	-
$\mu = 1 - \frac{1}{5}\lambda(1)$ Solving (1) and (2), $1 - \lambda = \frac{5}{11} \left(1 - \frac{3}{5}\lambda\right)$ $1 - \lambda = \frac{5}{11} - \frac{3}{11}\lambda$ Recall: For a and b are non-zero and non parallel vectors, $\lambda \mathbf{a} = \mu \mathbf{b} \implies \lambda = \mu = 0$		$\mu = 1 - \frac{3}{5}\lambda - (1)$ Solving (1) and (2), $1 - \lambda = \frac{5}{11} \left(1 - \frac{3}{5}\lambda \right)$	Recall: For a and b	are non-zero and i	non parallel vectors,	
$\lambda = \frac{3}{4}$ $\therefore \overrightarrow{OE} = \frac{3}{5} \left(\frac{3}{4}\right) \mathbf{a} + \left(1 - \frac{3}{4}\right) \mathbf{b}$ $= \frac{9}{20} \mathbf{a} + \frac{1}{4} \mathbf{b}$ $\overrightarrow{AE} = \overrightarrow{OE} - \overrightarrow{OA}$ $= \frac{9}{20} \mathbf{a} + \frac{1}{4} \mathbf{b} - \mathbf{a}$ $= \frac{1}{4} \mathbf{b} - \frac{11}{20} \mathbf{a}$ $= \frac{11}{20} \left(\frac{5}{11} \mathbf{b} - \mathbf{a}\right)$ Alternative (Shorter) $\mu = 1 - \frac{3}{5} \lambda = 1 - \frac{3}{5} \left(\frac{3}{4}\right) = \frac{11}{20}$ $\mathbf{r} = \overrightarrow{OA} + \mu \overrightarrow{AD}$ $\overrightarrow{OE} = \overrightarrow{OA} + \mu \overrightarrow{AD}$ $\overrightarrow{OE} = \overrightarrow{OA} + \frac{11}{20} \overrightarrow{AD}$ $= \overrightarrow{OA} + \overrightarrow{AE}$ So, $\overrightarrow{AE} = \frac{11}{20} \overrightarrow{AD}$ $\therefore AE : ED \Rightarrow 11:9$		$\lambda = \frac{3}{4}$ $\therefore \overrightarrow{OE} = \frac{3}{5} \left(\frac{3}{4} \right) \mathbf{a} + \left(1 - \frac{3}{4} \right)$ $= \frac{9}{20} \mathbf{a} + \frac{1}{4} \mathbf{b}$ $\overrightarrow{AE} = \overrightarrow{OE} - \overrightarrow{OA}$ $= \frac{9}{20} \mathbf{a} + \frac{1}{4} \mathbf{b} - \mathbf{a}$ $= \frac{1}{4} \mathbf{b} - \frac{11}{20} \mathbf{a}$	b	$\mu = 1 - \frac{3}{5}\lambda = 1 - \frac{3}{5}$ $\mathbf{r} = \overrightarrow{OA}$ $\overrightarrow{OE} = \overrightarrow{OA}$ $= \overrightarrow{OA}$ So, \overrightarrow{AE}	$\frac{3}{5}\left(\frac{3}{4}\right) = \frac{11}{20}$ $\vec{A} + \mu \vec{A} \vec{D}$ $\vec{A} + \frac{11}{20} \vec{A} \vec{D}$ $\vec{A} + \vec{A} \vec{E}$ $= \frac{11}{20} \vec{A} \vec{D}$	
$=\frac{11}{20}\overrightarrow{AD}$ $\therefore AE:ED \Rightarrow 11:9$ Learning point: Express $\overrightarrow{AE} = \frac{11}{20}\overrightarrow{AD}$ as A, D and E are collinear. To find the ratio, can consider its fraction : $\frac{AE}{AD} = \frac{11}{20}$ (using length AE and AD) $\therefore AE:ED \Rightarrow 11:9$ (using length AE and ED)			Express \overline{AE} To find the $\frac{AE}{AD} = \frac{11}{20}$ (1)	$\vec{E} = \frac{11}{20} \overrightarrow{AD}$ as A, D is ratio, can consider is using length AE an	its fraction : d <i>AD</i>)	

Level 3

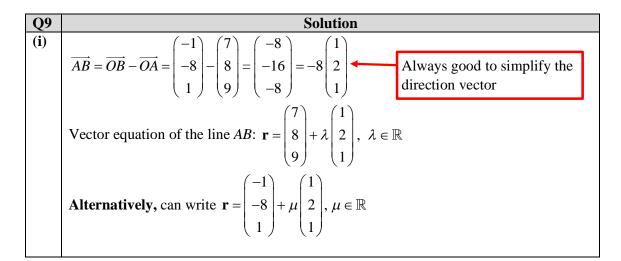
8 Relative to the origin *O*, the point *A* has coordinates (4, 4, 7) and the line *l* has equation $\mathbf{r} = -\mathbf{i} + \mathbf{j} + 2\mathbf{k} + \lambda(6\mathbf{i} + \mathbf{j} + \mathbf{k})$. Find the position vector of

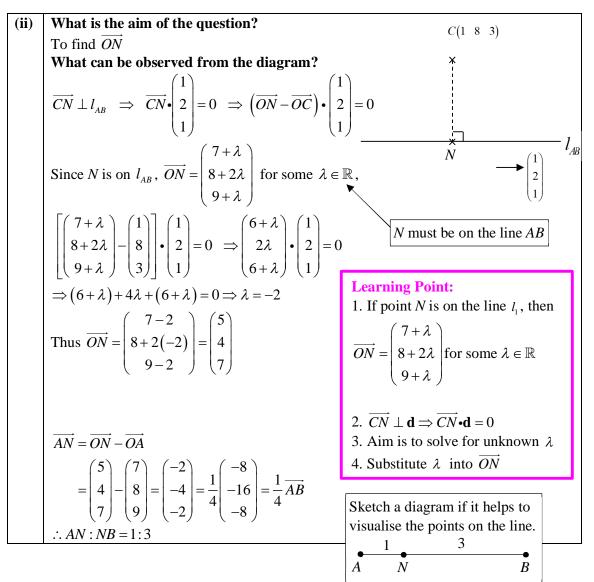
- (i) the foot of perpendicular from A to l,
- (ii) the point A', the reflection of A in the line l.

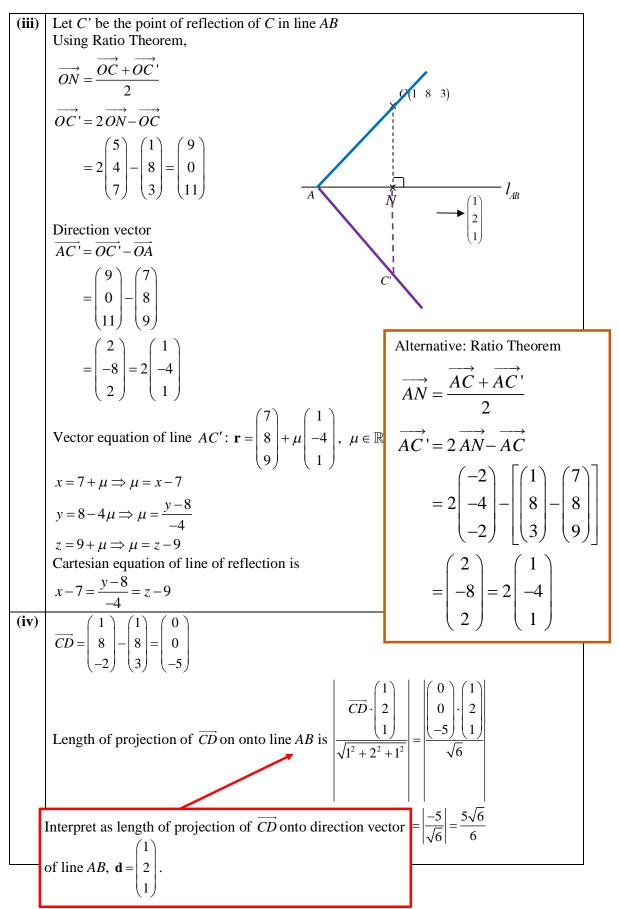
Hence or otherwise, find the shortest distance from A to line l.

Q8 Solution (i) Let F be the foot of the perpendicular from A to l. *l*: $\mathbf{r} = \begin{pmatrix} -1\\1\\2 \end{pmatrix} + \lambda \begin{pmatrix} 6\\1\\1 \end{pmatrix}, \lambda \in \mathbb{R}$ Since *F* lies on *l* then $\overrightarrow{OF} = \begin{pmatrix} -1+6\lambda \\ 1+\lambda \\ 2+\lambda \end{pmatrix}$ for some $\lambda \in \mathbb{R}$. $\overrightarrow{AF} = \overrightarrow{OF} - \overrightarrow{OA} = \begin{pmatrix} -1+6\lambda \\ 1+\lambda \\ 2+\lambda \end{pmatrix} - \begin{pmatrix} 4 \\ 4 \\ 7 \end{pmatrix} = \begin{pmatrix} 6\lambda-5 \\ \lambda-3 \\ \lambda-5 \end{pmatrix}$ $\overrightarrow{AF} \perp l \implies \begin{pmatrix} 6\lambda - 5\\ \lambda - 3\\ \lambda - 5 \end{pmatrix} \begin{pmatrix} 6\\ 1\\ 1 \end{pmatrix} = 0 \implies 36\lambda - 30 + \lambda - 3 + \lambda - 5 = 0 \implies \lambda = 1$ Therefore, the position vector of the foot of the perpendicular from A to l is $\overrightarrow{OF} = \begin{pmatrix} -1+6(1)\\1+1\\2+1 \end{pmatrix} = \begin{pmatrix} 5\\2\\2\\2 \end{pmatrix}.$ **(ii)** Let *A* 'be the reflection of *A* in the line *l*. By Ratio Theorem, $\overrightarrow{OF} = \frac{\overrightarrow{OA} + \overrightarrow{OA'}}{2} \implies \overrightarrow{OA'} = 2\overrightarrow{OF} - \overrightarrow{OA} = 2\begin{pmatrix} 5\\2\\3 \end{pmatrix} - \begin{pmatrix} 4\\4\\7 \end{pmatrix} = \begin{pmatrix} 6\\0\\-1 \end{pmatrix}$ Hence shortest distance from A to line l is $\left| \overrightarrow{AF} \right| = \begin{pmatrix} 6(1)-5\\1-3\\1-5 \end{pmatrix} = \begin{pmatrix} 1\\-2\\-4 \end{pmatrix} = \sqrt{21}$.

- 9 2012/I/9 (modified)
 - (i) Find a vector equation of the line through the points A and B with position vectors $7\mathbf{i}+8\mathbf{j}+9\mathbf{k}$ and $-\mathbf{i}-8\mathbf{j}+\mathbf{k}$ respectively. [3]
 - (ii) The perpendicular to this line from the point *C* with position vector $\mathbf{i} + 8\mathbf{j} + 3\mathbf{k}$ meets the line at the point *N*. Find the position vector of *N* and the ratio *AN* : *NB*. [5]
 - (iii) Find a Cartesian equation of the line which is a reflection of the line *AC* in the line *AB*. [4]
 - (iv) The point *D* has position vector $\mathbf{i} + 8\mathbf{j} 2\mathbf{k}$. Find the length of projection of *CD* onto line *AB*. [4]







[4]

10 2017(9758)/I/10

Electrical engineers are installing electricity cables on a building site. Points (x, y, z) are defined relative to a main switching site at (0,0,0), where units are metres. Cables are laid in straight lines and the widths of cables can be neglected.

An existing cable C starts at the main switching site and goes in the direction $\begin{bmatrix} 1\\ 1\\ -2 \end{bmatrix}$.

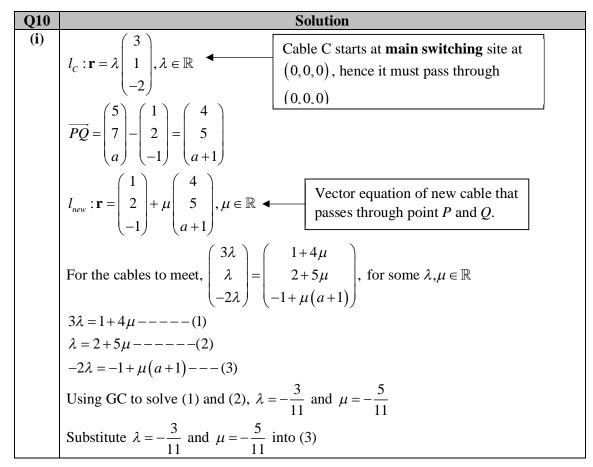
A new cable is installed which passes through points P(1,2,-1) and Q(5,7,a).

(i) Find the value of *a* for which *C* and the new cable will meet.

To ensure that the cables do not meet, the engineers use a = -3. The engineers wish to connect each of the points P and Q to a point R on C.

- (ii) The engineers wish to reduce the length of cable required and believe in order to do this that angle PRQ should be 90°. Show that this is not possible. [4]
- (iii) The engineers discover that the ground between P and R is difficult to drill through and now decide to make the length of PR as small as possible. Find the coordinates of R in this case and the exact minimum length. [5]

Extend: How can we find the exact minimum length without first finding the coordinates of R?



 l_c

(ii)
Since R lies on
$$l_c$$
, $\overrightarrow{OR} = \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix}$ for some $\lambda \in \mathbb{R}$
 $\overrightarrow{RP} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} - \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix} = \begin{pmatrix} 1-3\lambda \\ 2-\lambda \\ -1+2\lambda \end{pmatrix}$ for some $\lambda \in \mathbb{R}$
 $\overrightarrow{RP} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} - \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix} = \begin{pmatrix} 5-3\lambda \\ 7-\lambda \\ -3+2\lambda \end{pmatrix}$
 $\overrightarrow{RP} \cdot \overrightarrow{RQ} = \begin{pmatrix} 1-3\lambda \\ \lambda \\ -2\lambda \end{pmatrix} = \begin{pmatrix} 5-3\lambda \\ 7-\lambda \\ -3+2\lambda \end{pmatrix}$
 $\overrightarrow{RP} \cdot \overrightarrow{RQ} = \begin{pmatrix} 1-3\lambda \\ 2-\lambda \\ -1+2\lambda \end{pmatrix} + \begin{pmatrix} 5-3\lambda \\ 7-\lambda \\ -3+2\lambda \end{pmatrix}$
 $\overrightarrow{RP} \cdot \overrightarrow{RQ} = \begin{pmatrix} 1-3\lambda \\ 2-\lambda \\ -1+2\lambda \end{pmatrix} + \begin{pmatrix} 5-3\lambda \\ 7-\lambda \\ -3+2\lambda \end{pmatrix}$
 $= 14\lambda^2 - 35\lambda + 22$
 $= 14\left(\lambda^2 - \frac{35}{14}\lambda + \left(\frac{35}{28}\right)^2 - \left(\frac{35}{28}\right)^2\right) + 22$
 $= 14\left(\lambda^2 - \frac{35}{14}\lambda + \left(\frac{35}{28}\right)^2 - \left(\frac{35}{28}\right)^2\right) + 22$
 $= 14\left(\lambda - \frac{35}{28}\right)^2 \ge 0$ for all $\lambda \in \mathbb{R}$, $14\left(\lambda - \frac{35}{28}\right)^2 + \frac{1}{8} > 0$.
Since $\overrightarrow{RP} \cdot \overrightarrow{RQ} \neq 0$, it is not possible that $\angle PRQ = 90^\circ$.
Alternative Method:
If angle PRQ is 90°, then $\overrightarrow{RP} \cdot \overrightarrow{RQ} = 0$
 $\begin{pmatrix} 1-3\lambda \\ 2-\lambda \\ -1+2\lambda \end{pmatrix} + \begin{pmatrix} 5-3\lambda \\ 2-\lambda \\ -3+2\lambda \end{pmatrix} = 0$
 $\lambda^2 (9+1+4) + \lambda(-18-9-8) + (5+14+3) = 0$
 $14\lambda^2 - 35\lambda + 22 = 0$
Since discriminant $= (-35)^2 - 4(14)(22) = -7 < 0$, there is no real roots for
 $14\lambda^2 - 35\lambda + 22 = 0$ and thus $\overrightarrow{RP} \cdot \overrightarrow{RQ} \neq 0$. Hence, it is not possible that
 $\angle PRQ = 90^\circ$.

(iii)
Since R lies on
$$l_c$$
, $\overline{OR} = \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix}$ for some $\lambda \in \mathbb{R}$
 $\overline{PR} = \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3\lambda - 1 \\ \lambda - 2 \\ 1 - 2\lambda \end{pmatrix}$ for some $\lambda \in \mathbb{R}$
 $\overline{PR} = \begin{pmatrix} 3\lambda \\ \lambda \\ -2\lambda \end{pmatrix} - \begin{pmatrix} 1 \\ \lambda - 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3\lambda - 1 \\ \lambda - 2 \\ 1 - 2\lambda \end{pmatrix}$
In order for the length of PR to be as small as possible, \overline{PR} has to be perpendicular to l_c .
 $\overline{PR} \cdot \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix} = 0$
 $9\lambda - 3 + \lambda - 2 - 2 + 4\lambda = 0$
 $14\lambda = 7$
 $\lambda = \frac{1}{2}$
 $\therefore \overline{OR} = \frac{1}{2} \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix}$, coordinates of R is $\left(\frac{3}{2}, \frac{1}{2}, -1\right)$
Reminder to answer the question and give the coordinates of R.
 $\overrightarrow{OR} = \frac{1}{2} \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix}$, coordinates of R is $\left(\frac{3}{2}, \frac{1}{2}, -1\right)$
Exact Minimum length $= \sqrt{\left(\frac{1}{2}\right)^2 + \left(-\frac{3}{2}\right)^2}$
 $= \frac{\sqrt{10}}{2}$

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- (a) The non-zero vectors **a**, **b** and **c** are such that $\mathbf{a} \times \mathbf{b} = \mathbf{c} \times \mathbf{a}$. Given that $\mathbf{b} \neq -\mathbf{c}$, find a linear relationship between **a**, **b** and **c**. [3]
- (b) The variable vector **v** satisfies the equation $\mathbf{v} \times (\mathbf{i} 3\mathbf{k}) = 2\mathbf{j}$. Find the set of vectors **v** and fully describe this set geometrically. [5]

Q11	Solution		
(a)	$\mathbf{a} \times \mathbf{b} = \mathbf{c} \times \mathbf{a}$		
	Useful technique : Shift all terms to one side so that a zero vector is "created" on the other side.		
	$\mathbf{a} \times \mathbf{b} - \mathbf{c} \times \mathbf{a} = 0$ $(\mathbf{a} \times \mathbf{b}) + (\mathbf{a} \times \mathbf{c}) = 0$ $\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = 0$ $\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = 0$ $\mathbf{a} \times (\mathbf{c} + \mathbf{b}) = \mathbf{a} \times \mathbf{c} + \mathbf{a} \times \mathbf{b}$ $\mathbf{b} = \mathbf{a} \times \mathbf{c} + \mathbf{a} \times \mathbf{b}$ $\mathbf{c} \times \mathbf{c} = 0 \text{ (zero vector)}$ $\mathbf{c} \times \mathbf{c} = -\mathbf{c} \times \mathbf{a}$		
	Learning point: $\mathbf{a} \times \mathbf{b} = 0$ $\Rightarrow \mathbf{a}$ is parallel to \mathbf{b} $\mathbf{OR} \ \mathbf{a} = 0 \ \mathbf{OR} \ \mathbf{b} = 0$		
	Since $\mathbf{b} \neq -\mathbf{c}$, $\mathbf{b} + \mathbf{c} \neq 0$ and given $\mathbf{a} \neq 0$, hence \mathbf{a} is parallel to $\mathbf{b} + \mathbf{c}$. Therefore, a linear relationship between \mathbf{a} , \mathbf{b} and \mathbf{c} is $\mathbf{a} = \lambda (\mathbf{b} + \mathbf{c})$ for some $\lambda \in \mathbb{R}, \lambda \neq 0$.		

(b)
Given
$$\mathbf{v} \times \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$
, let $\mathbf{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$.
Since column vector is involved, we can start by expressing $\mathbf{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$
 $\Rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} = \begin{pmatrix} -3y \\ -(-3x-z) \\ -y \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$.
 $\Rightarrow y = 0$ and $3x + z = 2 \Rightarrow x = \frac{2}{3} - \frac{1}{3}z$ (Replacing z with λ)
Arranging,
 $x = \frac{2}{3} - \frac{1}{3}\lambda$
 $y = 0$, $\lambda \in \mathbb{R}$
 $z = -\lambda$
Therefore,
the set of vectors \mathbf{v} is $\begin{cases} x \\ y \\ z \end{cases} \in \mathbb{R}^3$: $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3$: $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} -1 \\ 3 \\ 0 \\ 1 \end{pmatrix}$ for
 $\begin{cases} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3$: $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 3 \\ 0 \\ -1 \end{pmatrix}$.
This set is the set of position vectors of all points lying on the line passing through
point $\begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix}$ with direction $\begin{pmatrix} -\frac{1}{3} \\ 0 \\ 1 \end{pmatrix}$.