



CATHOLIC JUNIOR COLLEGE
JC2 PRELIMINARY EXAMINATIONS
Higher 1

CANDIDATE
NAME

CLASS

2T

INDEX
NUMBER

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PHYSICS

Paper 2

8866/02

28 August 2015

2 hours

Additional Materials: Answer Paper

READ THESE INSTRUCTIONS FIRST

Write your index number and name on all the work you hand in.

Write in dark blue or black pen on both sides of the paper. **[PILOT FRIXION ERASABLE PENS ARE NOT ALLOWED]**

You may use a soft pencil for any diagrams, graphs or rough working.

Do not use staples, paper clips, highlighters, glue or correction fluid.

Section A

Answer **all** questions.

Section B

Answer any **two** questions. **Circle the 2 questions** that you answered in the table below.

At the end of the examination, fasten all work securely together.

The number of marks is given in brackets [] at the end of each question or part of the question.

FOR EXAMINER'S USE	
SECTION A (40 MARKS)	
1	/7
2	/8
3	/7
4	/8
5	/3
6	/7
SECTION B (40 MARKS)	
7	/20
8	/20
9	/20
TOTAL	/80

This document consists of **24** printed pages

[Turn over]

PHYSICS DATA:

speed of light in free space,	c	$= 3.00 \times 10^8 \text{ m s}^{-1}$
permeability of free space,	μ_0	$= 4\pi \times 10^{-7} \text{ H m}^{-1}$
elementary charge,	e	$= 1.60 \times 10^{-19} \text{ C}$
the Planck constant,	h	$= 6.63 \times 10^{-34} \text{ J s}$
unified atomic mass constant,	u	$= 1.66 \times 10^{-27} \text{ kg}$
rest mass of electron,	m_e	$= 9.11 \times 10^{-31} \text{ kg}$
rest mass of proton,	m_p	$= 1.67 \times 10^{-27} \text{ kg}$
acceleration of free fall,	g	$= 9.81 \text{ m s}^{-2}$

PHYSICS FORMULAE:

uniformly accelerated motion,	s	$= ut + \frac{1}{2}at^2$
	v^2	$= u^2 + 2as$
work done on / by a gas,	W	$= p\Delta V$
hydrostatic pressure	p	$= \rho gh$
resistors in series,	R	$= R_1 + R_2 + \dots$
resistors in parallel,	$\frac{1}{R}$	$= \frac{1}{R_1} + \frac{1}{R_2} + \dots$

SECTION A (40 marks)**Answer all questions in Section A.**

1	A car of mass 1380 kg, travelling at 31.1 m s^{-1} , is brought to rest by applying the brakes. The average braking force is estimated to be $1.38 \times 10^4 \text{ N}$. Calculate	
	(a) the initial kinetic energy of the car,	
	kinetic energy =J	[1]
	K.E. = $\frac{1}{2} m v^2 = \frac{1}{2} (1380)(31.1)^2 = 667400 \text{ J}$	A1
	(b) the average deceleration of the car,	
	deceleration = m s^{-2}	[1]
	$F = ma \rightarrow a = F/m = 1.38 \times 10^4 / 1380 = 10.0 \text{ m s}^{-2}$	A1
	(c) the distance travelled before it comes to rest.	
	braking force =N	[2]
	Work done = KE loss	M1
	$Fd = KE$	A1
	$d = KE \text{ loss} / F = 667400 / 1.38 \times 10^4 = 48.2 \text{ m}$	
	(d) Suggest whether the answer in (c) is an over-estimation or under-estimation.	
		[2]
	In practice, air resistance and rolling friction of the road are presence.	B1
	The total decelerating force is larger and hence the distance travel will be shorter.	
	The value is an overestimation.	B1

2	(a) State what is meant by the equilibrium of a body.	
		[2]
	It does not accelerate linearly, velocity is constant	B1
	It does not change in rotational speed, angular velocity is constant	B1
	(b) Fig. 2 shows a girl supported by two ropes. She is in equilibrium. She has a weight of 392 N.	

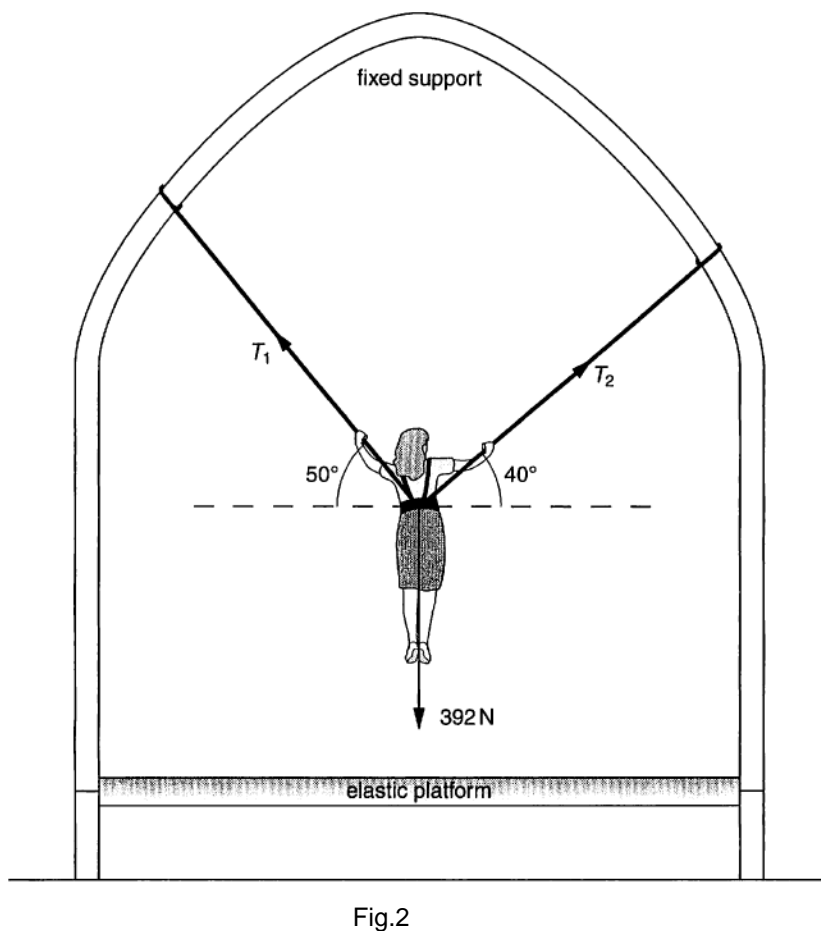


Fig.2

(i) Calculate the tension T_1 and T_2 in the ropes.

tension $T_1 = \dots\dots\dots\text{N}$
 tension $T_2 = \dots\dots\dots\text{N}$

[4]

$$T_1 \cos 50 = T_2 \cos 40$$

$$0.643 T_1 = 0.766 T_2 \dots\dots\dots(1)$$

M1

$$T_1 \sin 50 + T_2 \sin 40 = 392$$

$$0.766 T_1 + 0.643 T_2 = 392 \dots\dots\dots(2)$$

M1

$$\text{Solve (1) and (2) } T_1 = 244\text{ N } T_2 = 205\text{ N}$$

A1

A1

(ii) The girl is pulled vertically downwards so the ropes stretch. She is then released. Explain why the method you used in (i) could not be used to determine the tensions in the ropes immediately after she is released without additional information.

[2]

- the girl is not in equilibrium and the resultant force is not zero
- The downwards force is unknown & the angle of inclination of T_1 and T_2 are unknown.

B1

B1

3	A long-jumper leaps off the starting block at a speed 8.6 m s^{-1} at an angle θ to the horizontal and lands on level pit.	
(a)	Explain why the longer-jumper needs to have an upwards component of velocity at take-off, as well as forward velocity component to reach a good horizontal distance.	
		[2]
	the upwards component gives him airborne time t	B1
	The forwards component u_x gives him forward distance travelled because $x = u_x t$	B1
(b)	(i) Suppose that the angle $\theta = 35^\circ$, calculate the time to reach the maximum height and the horizontal distance of the long jumper. In your calculations, you should neglect the presence of air resistance.	
	time =s horizontal distance =m	[4]
	Vertical motion without air resistance Using " $v = u + at$ " $0 = 8.6 \sin 35 + (-9.81)t$ $t = 0.5028 = 0.50 \text{ s}$	M1 A1
	airborne time = $2 \times 0.5028 = 1.006 \text{ s}$ horizontal distance = $7.6 \cos 35 \times 1.006 = 6.26 = 6.3 \text{ m}$	M1 A1
	(ii) Why does his horizontal distance is less than the answer to (b)(i) when air resistance is taken into consideration.	
		[1]
	Air resistance opposes the motion, So the airborne time will decreases The horizontal component of the velocity also decreases with time Since horizontal distance = horizontal velocity of velocity \times airborne time The horizontal range is smaller	B1

4	<p>A glass tube of Helium gas atoms are excited when a potential difference is applied across it. When the emitted light is viewed through a spectrometer, three emission lines of blue, green and yellow colours are observed. Fig. 4.1 shows the spectral lines, together with the associated photon wavelengths of each colour.</p> <p style="text-align: center;">Blue 447 nm Green 502 nm Yellow 588 nm</p> <p style="text-align: center;">Fig. 4.1</p> <p>Light from the gas is incident on the surface of a metal plate X. The electrons liberated from the plate are attracted to the anode as shown in Fig. 4.2</p>	
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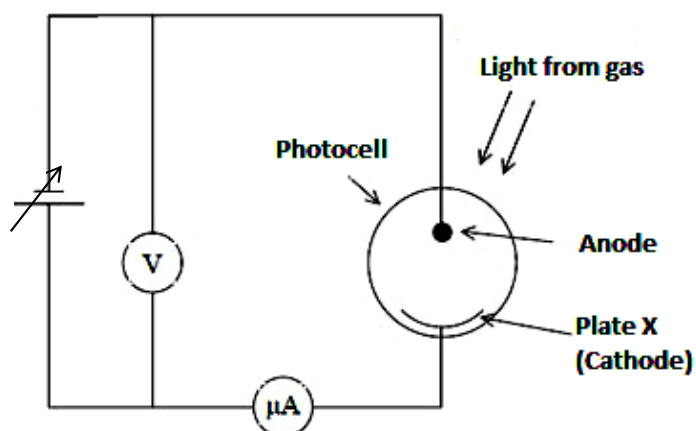


Fig 4.2

The experiment is then repeated using two other metal plates **Y** and **Z** of different work function energies. The table below shows the work function energies of the different plates.

Plate	Work Function Energy / eV
X	1.58
Y	2.42
Z	3.17

(a) What is meant by the term *work function energy* of a metal?

Work function energy is the minimum energy required to eject an electron from a metal surface in the photoelectric effect.

[1]

B1

(b) The figure below shows the variation of current I in the circuit with applied potential difference V between the metal plate and anode when the blue light from the gas is allowed to incident on plate X.

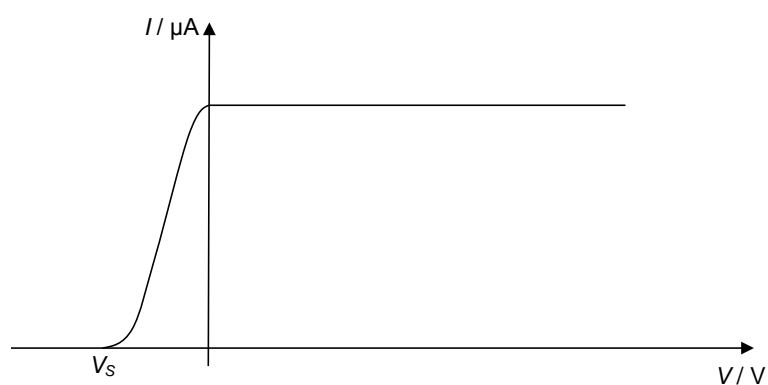
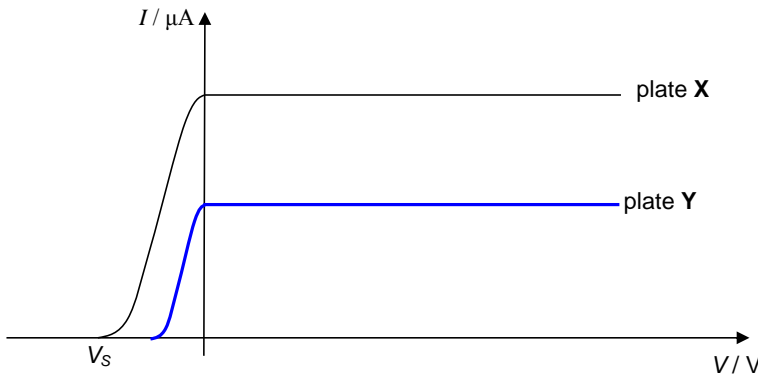
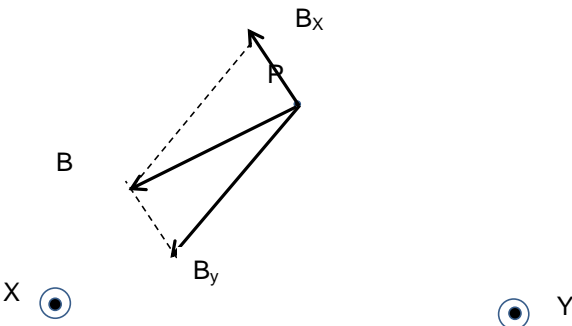


Fig. 4.3

		(i)	Calculate the stopping potential V_s	
				[3]
			Blue light $E = hf = hc / \lambda = 6.63 \times 10^{-34} \times 3 \times 10^8 / 447 \times 10^{-9} = 4.450 \times 10^{-19} \text{ J}$ X plate Work function = $(1.58)(1.60 \times 10^{-19}) \text{ J}$ $E = \phi + eV_s$ $4.450 \times 10^{-19} = (1.58)(1.60 \times 10^{-19}) + (1.60 \times 10^{-19})V_s$ $V_s = 1.2 \text{ V}$	A1 M1 A1
		(ii)	On Fig. 4.3, sketch the variation of current I with applied potential difference V when light from the gas is incident on plate Y. Explain your answers.	[3]
		(ii)	On Fig. 4.3, sketch the variation of current I with applied potential difference V when light from the gas is incident on plate Y. Explain your answers. 	[4]
			Smaller stopping potential M1 – Smaller saturated current The work function energy of plate Y is higher than plate X. Same photon energy Smaller maximum kinetic energy of the emitted electrons Smaller stopping potential The maximum current will also decrease as <ul style="list-style-type: none"> • The number of photons incident is the same, • The photon energy is the same • the work function energy is higher • less electrons can be liberated current is smaller	B1 B1 B1 B1
		(iii)	State with a reason, which of the plates used for the photoelectric effect experiments will a zero reading be registered in the micro-ammeter?	
				[2]
			The highest photon energy from the light would be the photons from the blue colour, $E = hf$ $= (6.63 \times 10^{-34}) \left(\frac{3.0 \times 10^8}{447 \times 10^{-9}} \right)$	

Comment [M1]: 3 s.f.

			$= 2.78 \text{ eV}$	M1
			Work function energies plate Y = 2.42 eV < photon energy → electrons liberated → current is not zero	
			Work function energies plate Z = 3.17 eV > photon energy → no electron liberated → current is zero	A1
5	Two wires X and Y, which are at right angles to the plane of the paper, carrying current I and 2I out of the plane of the paper as shown in Fig.5. A point P is at equal distance from the wires. On Fig. 5, draw an accurate vector diagram to show how you can determine the magnitude and direction of the resultant field at P.			
				[3]
	Fig. 5			
	Diagram shows correct Relative magnitude of Bx and By, $B_y = 2B_x$ Direction of Bx and By Parallelogram method for find B			A1 A1 A1

6	<p>In the 16th century, Kepler conducted observations of the planetary positions and deduced that for a circular orbit of a planet around the Sun, if T is the period of rotation and r is the radius of the orbit, then</p> $T^2 = 4\pi^2 r^3 / GM$ <p>where G is the gravitational constant which has a value of $6.67 \times 10^{-11} \text{ N m}^2 \text{ kg}^{-2}$ M is the mass of the Sun.</p> <p>The relation $T^2 = 4\pi^2 r^3 / GM$ is also true for the moons of the planet Jupiter.</p> <p>Data for some of the moons of Jupiter is given in Fig.6.1</p> <table border="1"> <thead> <tr> <th>Moon of Jupiter</th><th>Period T/days</th><th>Mean distance from centre of Jupiter $r / 10^9 \text{ m}$</th><th>$\log (T/\text{days})$</th><th>$\log (r/\text{m})$</th></tr> </thead> <tbody> <tr> <td>Sinope</td><td>758</td><td>23.7</td><td>2.88</td><td>10.37</td></tr> <tr> <td>Leda</td><td>239</td><td>11.1</td><td>2.38</td><td>10.05</td></tr> </tbody> </table>				Moon of Jupiter	Period T/days	Mean distance from centre of Jupiter $r / 10^9 \text{ m}$	$\log (T/\text{days})$	$\log (r/\text{m})$	Sinope	758	23.7	2.88	10.37	Leda	239	11.1	2.38	10.05
Moon of Jupiter	Period T/days	Mean distance from centre of Jupiter $r / 10^9 \text{ m}$	$\log (T/\text{days})$	$\log (r/\text{m})$															
Sinope	758	23.7	2.88	10.37															
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Callisto	16.7	1.88	1.22	9.27
Io	1.77	0.422	0.248	8.63
Metis	0.295	0.128	-0.53	8.11

Fig.6.1

(a) (i) Complete Fig.6.1 by calculating the values for $\log(T/\text{days})$ and $\log(r/m)$ and plot the data for moon Leda on Fig.6.2.

[1]

(ii) On the axes of Fig.6.2, draw the line of best fit of $\log(T/\text{days})$ against $\log(r/m)$

[1]

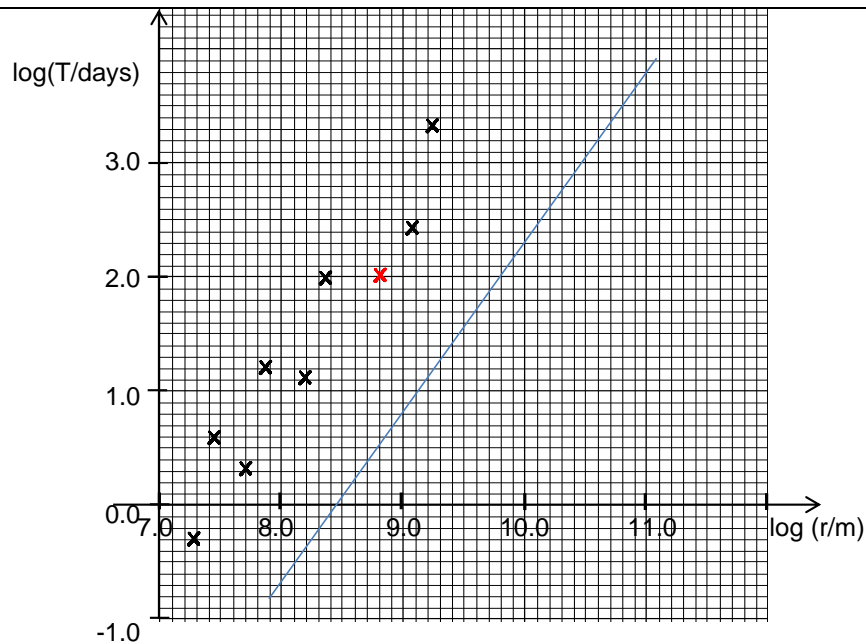


Fig.6.2

(iii) Determine the gradient of the graph in Fig.6.2

gradient = [1]

Gradient = $(3.8 - 0.8) / (11 - 9) = 1.55$ A1

(iv) Discuss whether the data Fig.6.1 support the relation $T^2 = 4\pi^2 r^3 / GM$

[2]

$T^2 = 4\pi^2 r^3 / GM$
 Take log both sides
 $2\log T = \log(4\pi^2 / GM) + 3\log r$
 $\log T = \log(4\pi^2 / GM) + 3/2 \log r$
 If the equation is correct, gradient = $3/2 = 0.667$
 Since the data give gradient = 0.667
 The data support the relation

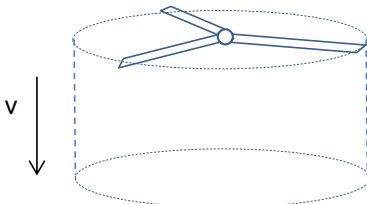
M1
A1

(b) Observation shows that the moon Ganymede orbits Jupiter with a period of 7.16

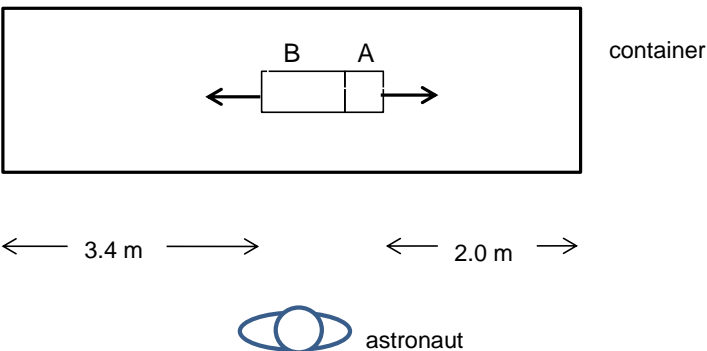
		days. Use the graphs of Fig.6.2 to estimate the orbital radius of Ganymede	
		orbital radius =m	[2]
		$\log 7.16 = 0.855$ from graph $\log r = 9.05$ $r = 1.12 \times 10^9 \text{ m}$	M1 A1
	(c)	Explain how you can use the graph on Fig.6.2 to determine the mass of Jupiter.	
		[1]
		Determine Y- intercept from the graph Since y intercept = $\log (4\pi^2 / GM)$ M can be found	A1

SECTION B (40 marks)

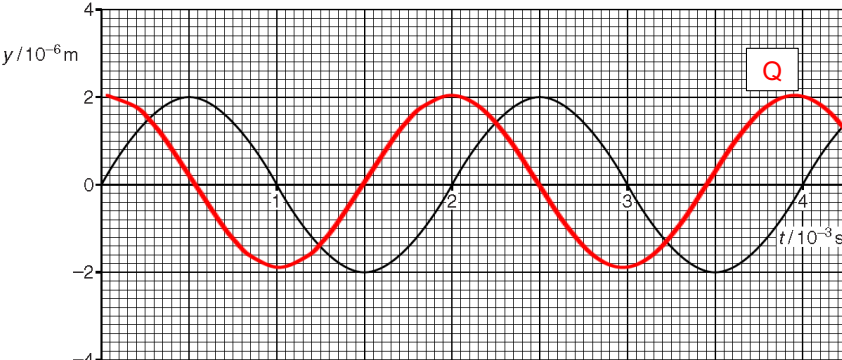
Answer only 2 out of 3 questions.

7	(a)	<p>Assume that the helicopter's main rotor blades give a vertical velocity v to a cylinder of air of cross-sectional area equal to that swept out by the blades as shown in Fig.7</p>  <p>Fig.7</p>	
	(i)	Explain, in terms of Newton's laws of motion, how a helicopter is able to hover in flight.	

			[2]
		The force on air by the blades cause a rate of change in the momentum of the air (Newton's second law)	B1
		By Newton's third law of motion, force on air is equal and opposite to the force on blades which balance the weight of the helicopter.	B1
		(ii)(1) Show that the weight of the helicopter while hovering is given by $\pi r^2 \rho v^2$ where ρ is the density of the air and r is the length of the rotor blades.	
			[3]
		Helicopter is hovering, resultant force = 0	
		Weight of helicopter = Force on helicopter by air = Rate of change in momentum of air	B1
		Force on helicopter by air = mass per unit time x velocity change = volume per unit time x density of air x velocity change $= \pi r^2 v \rho v$ $= \pi r^2 \rho v^2$	B1
		Weight of helicopter = $\pi r^2 \rho v^2$	B1
		(2) By what factor must the power increase for the helicopter to hold up a load equal to its own weight?	
		power increase by =times	[3]
		Force on helicopter $F = \pi r^2 \rho v^2$ $v = (F / \pi r^2 \rho)^{1/2}$ Power given to the air $P = \text{force on air} \times \text{velocity of air}$ $= \pi r^2 \rho v^2 \times v = \pi r^2 \rho v^3 = \pi r^2 \rho [(F / \pi r^2 \rho)^{1/2}]^3$ $= F^{3/2} / (\pi r^2 \rho)^{1/2}$ $\propto F^{3/2}$ since $\pi r^2 \rho$ is constant Let $P' = \text{new power} \& \text{new force} = F'$ Since $P \propto F^{3/2}$ $P' / P = (F' / F)^{3/2}$ $F' = 2F$ since load = weight $P' / P = (2)^{3/2} = 2.8$	M1 C1 A1
		(b) Use the Newton's laws of motions to derive the principle of conservation of momentum applied to the collision of two bodies.	
		Force on body A equal and opposite to force on B Since time taken is the same	B1
		The impulse which is the product of force and time on A is equal but opposite to B	B1
		The change in the momentum of A is equal and opposite to that of B Hence the total momentum of the two bodies is constant	B1

	(c)	<p>Fig. 7.1 shows a container of mass 45 kg floating in deep space where the effect of gravity is negligible. An astronaut, looking into it, observes an object of mass 15 kg, floating inside the container, explode into two fragments A and B of mass 5.0 kg and 10 kg respectively. The two fragments apart in the direction shown in Fig. 7.1. The fragments adhere to the walls after impact. Initially, the astronaut, container and object have no relative motion.</p>	
		 <p style="text-align: center;">Fig. 7.1</p>	
	(i)	<p>The impulse from the explosion on A is 10 kg m s^{-1}. Calculate the speeds of the fragments after explosion.</p>	
		<p style="text-align: right;">speed of A = m s^{-1} speed of B = m s^{-1}</p>	[3]
		<p>For A: Impulse on A = change in momentum of A $10 = 5v \rightarrow v = 2.0 \text{ m s}^{-1}$</p> <p>For B: Impulse on B = Impulse on A = change in momentum of B $10 = 10v \rightarrow v = 1.0 \text{ m s}^{-1}$</p>	A1 M1 A1

		(iii) Sketch the graphs of velocity and horizontal position of the container, relative to the astronaut, against time for the first 5 seconds after the explosion.	
			[4]
		<p>velocity ↑</p> <p>time →</p> <p>position ↑</p> <p>position →</p> <p>time →</p>	
		Shape of v-t graph V increases from zero to constant value V falls to zero	A1 A1
		Shape of x-t graph x increases from zero to max while v is constant x remain constant when v fall to zero	A1 A1
		(iv) Energy is generated during the explosion. State the energy conversion during the first 5 seconds during and after explosion.	
		[2]
		Energy is converted from chemical energy of the explosive to kinetic energy of A and B and	A1
		then to heat energy when A and B hit the wall	A1

<p>8 Fig.8.1 shows the variation with time t of the displacement y of the air at a point P in front of a loudspeaker emitting a sound wave of a single frequency.</p>  <p style="text-align: center;">Fig. 8.1</p>	
<p>(a) Calculate</p>	
<p>(i) the frequency f of oscillations of the air at P</p>	
<p style="text-align: right;">frequency =Hz</p>	<p>[1]</p>
<p>$f = \frac{1}{T} = \frac{1}{2 \times 10^{-3}} = 500 \text{ Hz}$</p>	<p>A1</p>
<p>(ii) the wavelength λ of the wave which is travelling at 340 m s^{-1}.</p>	
<p style="text-align: right;">Wavelength =m</p>	<p>[1]</p>
<p>$\lambda = \frac{v}{f} = \frac{340}{500} = 0.68 \text{ m}$</p>	<p>A1</p>
<p>(b) (i) Draw on Fig. 8.1 the variation with time of the displacement of the air at a point Q a distance of one quarter of a wavelength $\lambda/4$ beyond P. Label this curve Q.</p>	
<p style="text-align: right;">[2]</p>	
<p>Sinusoidal curve with same frequency and amplitude with a $\Delta t = T/4$ or 0.5 ms difference from curve P.</p>	<p>B1 B1</p>
<p>(ii) Explain the meaning of the term <i>phase difference</i>. Illustrate your answer by stating the phase difference between the displacements of the air at the points P and Q.</p>	
<p>.....</p> <p>.....</p> <p>.....</p>	<p style="text-align: right;">[2]</p>
<p>Phase difference is a measure of how much one wave is out of step with another. $\lambda/4$ has a phase difference of $\pi/2 \text{ rad}$.</p>	<p>B1 B1</p>
<p>(c) An open tube is placed in front of the loudspeaker such that its far end is at point Q, as shown in Fig. 8.2.</p>	

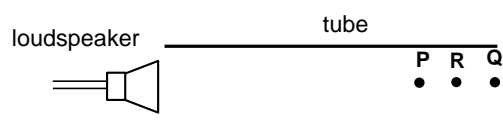
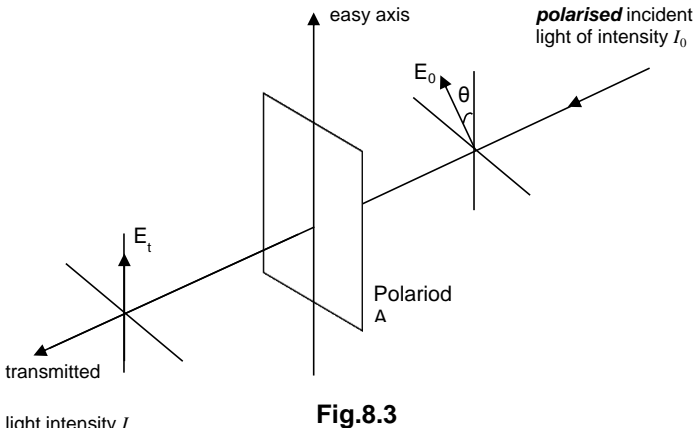


Fig. 8.2

		(i)	Explain why the frequency of the loudspeaker has to be adjusted to a particular value for a stationary sound wave to be formed in the tube.
			<p>.....</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>.....</p>
			[2]
			<p>Q must be a node</p> <p>Length of tube must be such that $PQ = \frac{1}{4} \lambda$, $\lambda = \text{wavelength}$</p> <p>Wavelength depends on frequency because speed is constant and $\lambda = v / f$</p> <p>Frequency must be of a certain value</p>
			B1
			B1
		(ii)	A stationary wave is set up in the tube. The distance between the points P and Q is $\lambda/4$. Compare and contrast the motion of the air particles at P, Q and R.
			<p>P & Q</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>P & R</p> <p>.....</p> <p>.....</p> <p>.....</p>
			[4]
			<p>Air molecules oscillate/vibrate along the axis of the tube at maximum amplitude at Q</p> <p>They are at rest at P.</p>
			B1
			B1
			<p>Amplitude of P > that of R</p> <p>Phase of P same as R</p>
			B1
			B1

	(iii)	A student attempts to determine the speed of the sound in the tube by calculating the wavelength of the waves by measuring the distance between P and Q and using the expression $\lambda = 4 \times \text{distance PQ}$. Give two reasons why his measurement of the speed is unlikely to be accurate and suggest the improvements to reduce the uncertainty.	
		[4]
		Due to the fact that the antinode is at a distance outside the rim, wavelength $\lambda/4 > PQ$ To include the end correction c such that $\lambda/4 = PQ + c$	B1 B1
		Due to the fact that the position of node is difficult to detect, there is an uncertainty in the measurement of the length PQ Consider measuring the distance D between 1 st node and Nth node along the tube Use the expression $(N-1) \lambda/2 = D$ to calculate the wavelength	B1 B1
	(d)	Light can be polarised using a polarizer, such as a sheet of Polaroid. A polariser has an axis for the 'easy' transmission of light (the easy axis). It transmits the component of the electric field (E-field) of light which is parallel to this axis. In a perfect polariser, this component is transmitted without absorption. The component perpendicular to the easy axis is completely absorbed.	
		<p>Fig.8.3 shows a perfect polarizer A with its easy axis vertical.</p>  <p style="text-align: center;">Fig.8.3</p> <p>A parallel beam of polarised light of intensity I_0 is incident on the polarizer A with its E-field, of amplitude E_0, at an angle θ to the vertical. The transmitted light has amplitude E_t.</p>	
	(i)	Show that I_1 is given by $I_t = I_0 \cos^2 \theta$	
			[3]
		Transmitted amplitude $E_t = E_0 \cos \theta$	B1
		Transmitted intensity $I_t = k E_t^2$ Incident intensity $I_0 = k E_0^2$	M1
		Hence $I_t = k E_t^2 = k (E_0 \cos \theta)^2 = k E_0^2 \cos^2 \theta = I_0 \cos^2 \theta$	M1
	(ii)	The polarised light of intensity I_0 is now incident on A with its E-field parallel to	

the easy axis (i.e. the angle θ is set at 0°). A second polarizer B is now placed in front of A, with its easy axis parallel to that of A. Keeping the polarizer A fixed, polarizer B is then rotated so that its easy axis makes an increasing angle ϕ with the easy axis of Polaroid A. On Fig.8.4, sketch a graph to show how the intensity I_t of the light transmitted by the polariser combination varies with the angle ϕ , for values of ϕ between 0 and 2π rad. Label the axes with appropriate values.

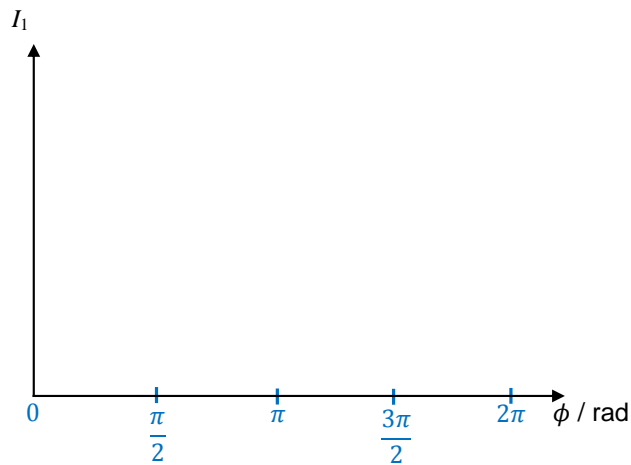


Fig. 7.4

[2]

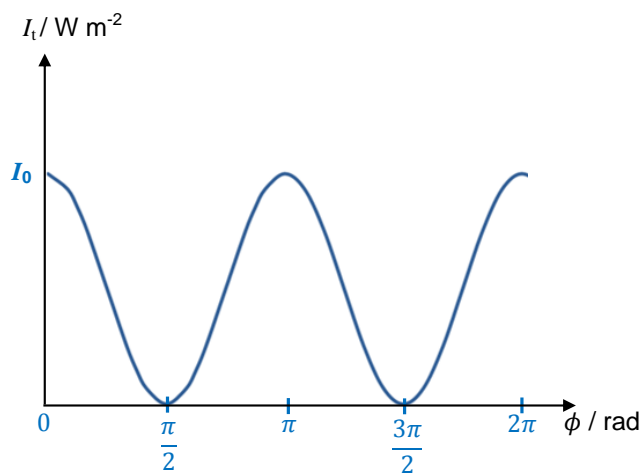
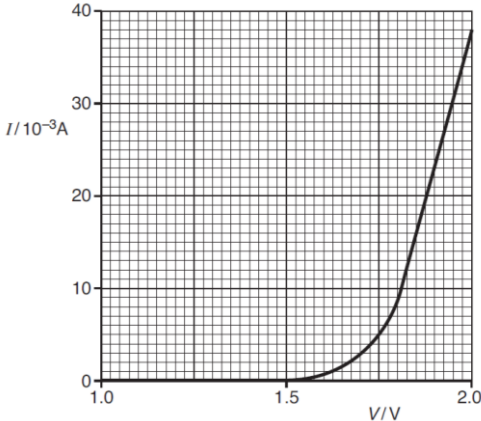
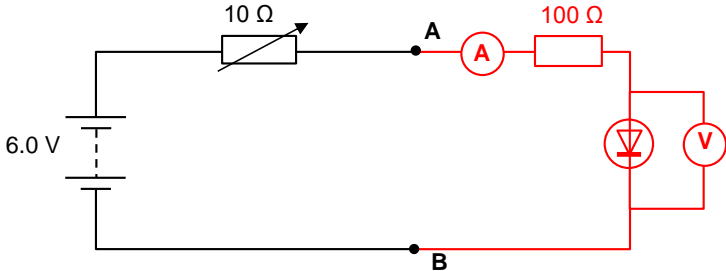
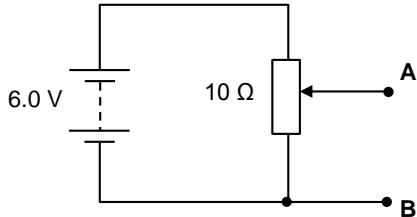


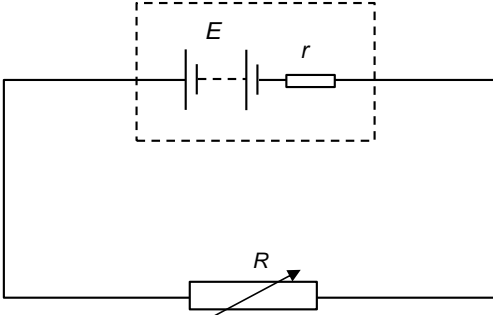
Fig. 6.4

Correct shape of graph
 Axes are labelled with appropriate values
 Zero intensity at $\frac{\pi}{2}$, $\frac{3\pi}{2}$ rad and I_0 intensity at $0, \pi, 2\pi$ rad.

B1
B1

9	a	Fig. 9.1 shows the I - V characteristic of a <i>light-emitting diode</i> (LED).	
		 <p style="text-align: center;">Fig. 9.1</p>	
	i	Describe the significant features of the graph in terms of current, voltage and resistance.	
		<p>.....</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>.....</p>	[4]
		No current or LED does not conduct until V is greater than 1.5 V	B1
		Below 1.5 V, LED has infinite resistance and acts as open circuit	B1
		Above 1.5 V, LED resistance decreases (with increasing current/voltage) or brightness/intensity of LED increases with current/voltage above 1.5 V	B1
		Above 1.8 V current rises almost linearly with increase in p.d.	B1

	ii	Calculate the resistance of the LED at 1.9 V	
		Resistance = Ω	[2]
		From the graph, at $V = 1.9 \text{ V}$, $I = 23 \times 10^{-3} \text{ A}$ $R = V/I = 83 \Omega$	M1 A1
b	<p>In order to carry out an investigation to determine the I-V characteristic of an LED a student connects the circuit as shown in Fig. 9.2.</p>  <p style="text-align: center;">Fig. 9.2</p>		
	<p>Explain why the circuit in Fig. 9.2 is not appropriate to obtain the graph in Fig 9.1.</p> <p>The range of variable resistor is not suitable</p> <p>Suppose voltage across the diode = 1.9 V, the current is 31.5 mA and resistance = 60Ω</p> <p>The potential difference across the variable resistor and the fixed resistor = $6.0 - 1.9 = 4.1 \text{ V}$</p> <p>The resistance of the variable resistor and the fixed resistor should be $4.1 / 0.0315 = 130 \Omega$</p> <p>Hence the variable resistance should have a resistance of 30Ω</p>		B1 B1 B1
c	<p>Another student uses the 10Ω variable resistor as a potential divider as shown in Fig. 9.3. The rest of the circuit is then completed between terminals A and B as for Fig. 9.2 in (b).</p>  <p style="text-align: center;">Fig. 9.3</p>		
	<p>Explain why the circuit of Fig. 9.3 is more suitable for obtaining the I-V characteristic of the LED than the circuit of Fig. 9.2.</p>		

			[2]
		The p.d. across LED can be adjust from zero to maximum value of 2 V The current in the LED is not affect by the position of the contact.	B1 B1
d	Fig. 9.4 shows a battery of e.m.f E and internal resistance r is connected to a variable resistor of resistance R .	 <p style="text-align: center;">Fig. 9.4</p> <p>The total power produced in the battery is P_T. The power dissipated in the variable resistor is P_R.</p>	
	The variation of P_T and of P_R with resistance R of the variable resistor are show in Fig. 9.5.		

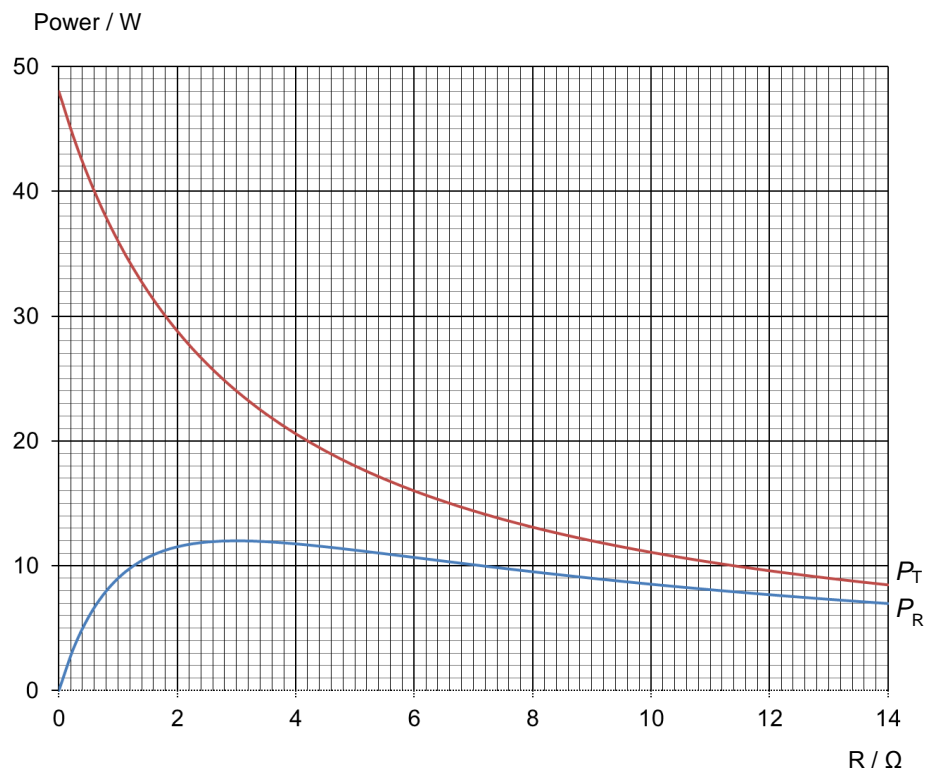


Fig. 9.5

i		For resistance $R = 6.0 \, \Omega$, use Fig. 9.5	
	1.	to show that the current in the circuit is 1.3 A	
			[2]
		From the graph, when $R = 6.0 \, \Omega$, $P_R = 10.5 \, \text{W}$	M1
		$P = I^2 R \Rightarrow I^2 = \frac{10.5}{6} \Rightarrow I = 1.323 = 1.3 \, \text{A}$	A1
	2.	to determine the e.m.f. E of the battery.	
		e.m.f. =V	[2]
		From the graph, when $R = 6.0 \, \Omega$, $P_T = 16 \, \text{W}$ Since current in the circuit is 1.3 A	B1
		$P_T = EI \Rightarrow E = \frac{16}{1.323} = 12.09 = 12 \, \text{V}$	B1
ii		For any value of R , the value of P_T is greater than that of P_R .	
	1.	Suggest what is represented by the quantity $(P_T - P_R)$.	[1]
		Power dissipated in the internal resistance	B1

			2.	Use your values of P_T and P_R at $R = 6.0 \, \Omega$ and your answer to (i)(1) to determine the internal resistance r of the battery.	
				internal resistance = Ω	[2]
				$P_T - P_R = I^2 r$ $\Rightarrow r = \frac{16 - 10.5}{1.323^2} = 3.142 = 3.1 \, \Omega$	M1 A1
	iii	1.		Use Fig 9.5 to determine the efficiency of power transfer from the battery to the variable resistor when $R = 3.0 \, \Omega$.	
				efficiency =	[1]
				At $R = 3 \, \Omega$, $P_R = 12 \, \text{W}$ and $P_T = 24 \, \text{W}$ $\text{efficiency of power transfer} = \frac{12}{24} \times 100 \% = 50 \%$	A1
		2.		Discuss, based on Fig 9.5 but without mathematical calculations, how the efficiency changes with R .	
				[3]
				PR increases from zero to a maximum and then decreases to a very low value PT decreases continuously As efficiency = PR/PT , At $R = 0$, $PR = 0$, efficiency = 0 As R increases, PR increases and PT decreases hence Efficiency increases Beyond max value of PR , both PT and PR decreases but PT decreases faster than PR , hence efficiency increases further When R increases further, PR approaches the value of PT , hence efficiency approaches 1	B1 B1 B1

-- END OF PAPER --

[Turn over