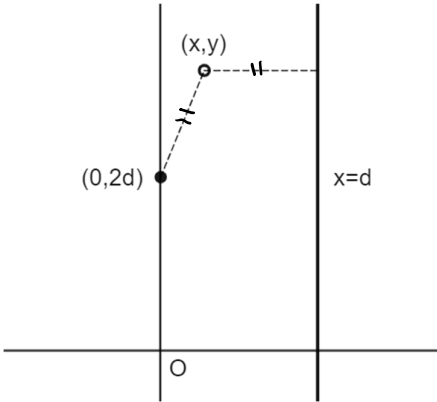
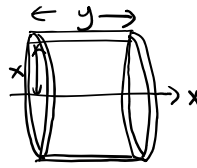
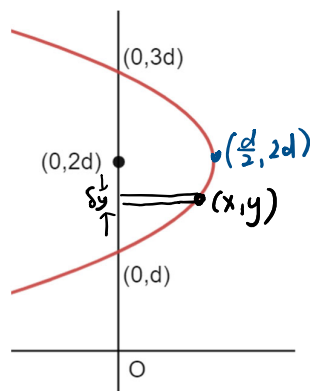


1(a)	$w^3 = 1$ $w^3 - 1 = 0$ $(w-1)(w^2 + w + 1) = 0$ Since w is non-real, it satisfies $w^2 + w + 1 = 0$. $\therefore w^2 + w = -1$.	- GC is not allowed and given 2 marks, the intent is not to solve for w .
1(b)	$(1 + 2w + 3w^2)(1 + 2w^2 + 3w) = 3$ LHS: $[1 + 2(w + w^2) + w^2][1 + 2(w^2 + w) + w]$ $= [1 + 2(-1) + w^2][1 + 2(-1) + w]$ $= (w^2 - 1)(w - 1)$ $= w^3 - (w^2 + w) + 1$ $= 1 - (-1) + 1$ $= 3$ Alternative LHS $= (1 + 2w + 3w^2) + (2w^2 + 4w^3 + 6w^4) + (3w + 6w^2 + 9w^3)$ $= 1 + 5w + 11w^2 + 13w^3 + 6w^4$ $= 1 + 5w + 11w^2 + 13 + 6w \left(\because w^3 = 1 \Rightarrow w^4 = w \right)$ $= 14 + 11w + 11w^2$ $= 14 + 11(-1)$ $= 3$ $= \text{RHS}$	- Make good use of result in (a) to simplify. - Note the efficient way to evaluate w^4 .
2(a)	 <p>distance from (x, y) to $(0, 2d) = \sqrt{x^2 + (y - 2d)^2}$ distance from (x, y) to line $= x - d$ $\sqrt{x^2 + (y - 2d)^2} = x - d$ $x^2 + (y - 2d)^2 = (x - d)^2$ $(y - 2d)^2 = (x - d)^2 - x^2$ $= (x - d - x)(x - d + x)$ $= -d(2x - d)$ $(y - 2d)^2 = d(d - 2x)$ (shown)</p>	From definition, $d > x$. $ x - d = d - x$

(b)



By shell method,

$$\delta A \approx 2\pi xy \delta y$$

$$(y - 2d)^2 = d(d - 2x)$$

$$\Rightarrow d - 2x = \frac{(y - 2d)^2}{d}$$

$$\Rightarrow x = \frac{d}{2} - \frac{(y - 2d)^2}{2d}$$

$$\text{Volume} = 2\pi \int_d^{3d} xy \, dy$$

$$= 2\pi \int_d^{3d} xy \, dy$$

$$= 2\pi \int_d^{3d} \left(\frac{d}{2} - \frac{(y - 2d)^2}{2d} \right) y \, dy$$

$$= \pi d \int_d^{3d} y \, dy - \frac{\pi}{d} \int_d^{3d} y(y - 2d)^2 \, dy$$

$$= \pi d \left[\frac{y^2}{2} \right]_d^{3d} - \frac{\pi}{d} \left[\int_d^{3d} (y - 2d)(y - 2d)^2 + 2d(y - 2d)^2 \, dy \right]$$

$$= \frac{\pi d}{2} (9d^2 - d^2) - \frac{\pi}{d} \left[\frac{(y - 2d)^4}{4} \right]_d^{3d} - 2\pi \left[\frac{(y - 2d)^3}{3} \right]_d^{3d}$$

$$= 4\pi d^3 - \frac{\pi}{4d} (d^4 - d^4) - \frac{2\pi}{3} (d^3 + d^3)$$

$$= \frac{8}{3} \pi d^3 \text{ cu. units}$$

Alternative (Disc Method)

$$(y - 2d)^2 = d(d - 2x) \Rightarrow y = 2d \pm \sqrt{d(d - 2x)}$$

Required volume

= volume generated by upper curve y_U - volume generated by lower curve y_L

$$= \int_0^{\frac{d}{2}} \pi y_U^2 \, dx - \int_0^{\frac{d}{2}} \pi y_L^2 \, dx$$

$$= \pi \int_0^{\frac{d}{2}} \left[2d + \sqrt{d(d - 2x)} \right]^2 - \left[2d - \sqrt{d(d - 2x)} \right]^2 \, dx$$

$$= \pi \int_0^{\frac{d}{2}} 8d \sqrt{d(d - 2x)} \, dx$$

$$= 8\pi d \times \frac{1}{-2d} \int_0^{\frac{d}{2}} -2d \sqrt{d(d - 2x)} \, dx$$

$$= -4\pi \left[\frac{[d(d - 2x)]^{3/2}}{3/2} \right]_0^{\frac{d}{2}}$$

$$= -\frac{8\pi}{3} [0 - d^3]$$

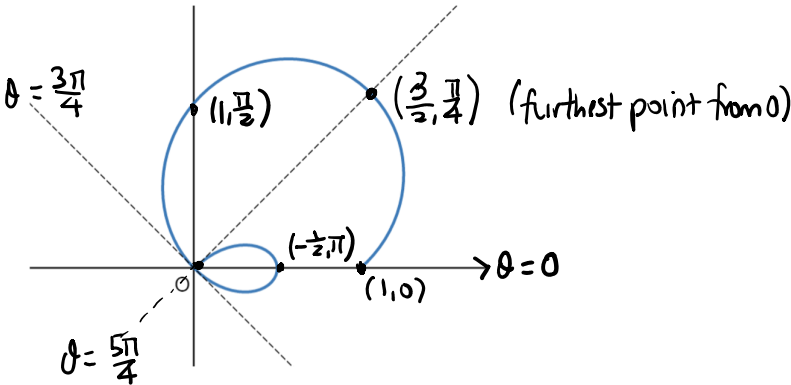
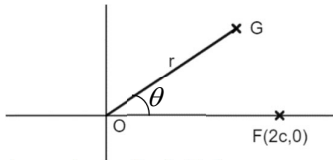
$$= \frac{8\pi}{3} d^3 \text{ cu. units}$$

Alternative:

Expand $y(y - 2d)^2$; the method shown is simpler to evaluate limits.

3(a)	$\frac{2k}{2k+1} - \frac{2k+2}{2k+3} = \frac{2k(2k+3) - (2k+2)(2k+1)}{(2k+1)(2k+3)}$ $= \frac{4k^2 + 6k - (4k^2 + 6k + 2)}{(2k+1)(2k+3)}$ $= \frac{-2}{(2k+1)(2k+3)} < 0 \quad (\because (2k+1) \& (2k+3) > 0 \text{ for } k > 0)$ $\therefore \frac{2k}{2k+1} < \frac{2k+2}{2k+3}$	
(b)	<p>Let P_n be the proposition that $u_n \leq \left(\frac{2n}{2n+1}\right)^n, n \in \mathbb{Z}^+ \dots$</p> <p>Consider P_1:</p> <p>LHS $= u_1 = \frac{2}{3}$ (given)</p> <p>RHS $= \frac{2(1)}{2(1)+1} = \frac{2}{3}$</p> <p>Hence $u_1 \leq \frac{2}{3}$</p> <p>$\therefore P_1$ is true</p> <p>Assume that P_k is true for some positive integer $k, u_k \leq \left(\frac{2k}{2k+1}\right)^k$.</p> <p>To show P_{k+1} is true, $u_{k+1} \leq \left(\frac{2k+2}{2k+3}\right)^{k+1}$</p> <p>LHS of P_{k+1}</p> $= u_{k+1}$ $= \frac{2k+2}{2k+3} u_k$ $\leq \left(\frac{2k+2}{2k+3}\right) \left(\frac{2k}{2k+1}\right)^k$ $\leq \left(\frac{2k+2}{2k+3}\right) \left(\frac{2k+2}{2k+3}\right)^k \quad \text{since } \frac{2k}{2k+1} < \left(\frac{2k+2}{2k+3}\right)$ $= \left(\frac{2k+2}{2k+3}\right)^{k+1}$ $\therefore u_{k+1} \leq \left(\frac{2k+2}{2k+3}\right)^{k+1}$ <p>$\therefore P_k$ is true $\Rightarrow P_{k+1}$ is true</p> <p>Since P_1 is true and P_k is true $\Rightarrow P_{k+1}$ is true, by mathematical induction, P_n is true for all positive integers n.</p>	<p>\Rightarrow implies</p> <p>\rightarrow tends to</p> <p>\mapsto maps to</p>
4(a)	<p>$f(x) = x^k - a \Rightarrow f'(x) = kx^{k-1}$</p> <p>By Newton-Raphson method, $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$</p> $\therefore x_{n+1} = x_n - \frac{x_n^k - a}{kx_n^{k-1}}$	

	$x_{n+1} = x_n - \frac{x_n^k}{kx_n^{k-1}} + \frac{a}{kx_n^{k-1}}$ $= x_n - \frac{x_n}{k} + \frac{a}{kx_n^{k-1}}$ $= \frac{1}{k} \left[(k-1)x_n + \frac{a}{x_n^{k-1}} \right] \text{ (shown)}$	A1
(b)	Since $\sqrt[3]{25} \approx \sqrt[3]{27} = 3$, 3 is a reasonable initial estimate.	B1
(c)	Using $x_1 = 3$, from GC, $x_2 = 2.92592...$ $x_3 = 2.924018...$ $x_4 = 2.924017...$ $x_5 = 2.924017...$ $\therefore \sqrt[3]{25} = 2.924$ (3 dp)	M1 A1
(d)		Question stated to sketch suitable graphs (hence more than 1), so the graphs of $y = x$ and $y = \frac{1}{3} \left(2x + \frac{25}{x^2} \right)$ are expected
5	$v_{n+2} - 2v_{n+1} + 2v_n = 4, v_1 = 2, v_2 = 0$ $v_n + w_n = k \Rightarrow v_n = k - w_n$ $v_{n+2} - 2v_{n+1} + 2v_n = 4$ becomes $(k - w_{n+2}) - 2(k - w_{n+1}) + 2(k - w_n) = 4$ $\therefore w_{n+2} - 2w_{n+1} + 2w_n = k - 4$ For this equation to be homogeneous, $k = 4$. $w_1 = 4 - v_1 = 2, w_2 = 4 - v_2 = 4$. $w_{n+2} - 2w_{n+1} + 2w_n = 0$ Auxiliary equation is $\lambda^2 - 2\lambda + 2 = 0$ $\lambda = \frac{2 \pm \sqrt{4-8}}{2} = 1 \pm i$ $\therefore w_n = (\sqrt{2})^n \left[A \cos \frac{n\pi}{4} + B \sin \frac{n\pi}{4} \right]$ $w_1 = 2 \Rightarrow 2 = A + B$ $v_2 = 4 \Rightarrow 4 = 2(0 + B)$ $\Rightarrow B = 2$ $\Rightarrow A = 0$ $\therefore w_n = (\sqrt{2})^n \left[2 \sin \frac{n\pi}{4} \right]$ $\Rightarrow v_n = 4 - 2^{\frac{n}{2}+1} \sin \frac{n\pi}{4}$	It is totally unthinking to write auxiliary equation as: $\lambda^2 - 2\lambda + 2 = 4$.

(b)	$v_{4n+2} = 4 - 2^{\frac{4n+2}{2}+1} \sin \frac{(4n+2)\pi}{4}$ $= 4 - 2^{2n+2} \sin(2n+1) \frac{\pi}{2}$ $= \begin{cases} 4 - 2^{2n+2}(-1), & n \text{ is odd} \\ 4 - 2^{2n+2}(1), & n \text{ is even} \end{cases}$ $= \begin{cases} 4(1+4^n), & n \text{ is odd} \\ 4(1-4^n), & n \text{ is even} \end{cases}$									
6(a)	<table><tr><td>x</td><td>$\frac{3\pi}{4}$</td><td>π</td><td>$\frac{5\pi}{4}$</td></tr><tr><td>y^2</td><td>0</td><td>$\frac{1}{4}$</td><td>0</td></tr></table> $\int_{\frac{3\pi}{4}}^{\frac{5\pi}{4}} y^2 \, dx \approx \frac{\frac{5\pi}{4} - \frac{3\pi}{4}}{6} \left[0 + 0 + 4 \left(\frac{1}{4} \right) \right] = \frac{1}{12} \pi \approx 0.262 \text{ (3sf)}$	x	$\frac{3\pi}{4}$	π	$\frac{5\pi}{4}$	y^2	0	$\frac{1}{4}$	0	
x	$\frac{3\pi}{4}$	π	$\frac{5\pi}{4}$							
y^2	0	$\frac{1}{4}$	0							
(b)	 <p>Area of the inner loop $= \frac{1}{2} \int_{\frac{3\pi}{4}}^{\frac{5\pi}{4}} r^2 d\theta$</p> $\approx \frac{1}{2} \left(\frac{\pi}{12} \right) = \frac{\pi}{24} = 0.131 \text{ (3sf)}$									
7(a)	Locus is an ellipse.									
(b)	 $OG + GF = 2a$ $r + \sqrt{r^2 + 4c^2 - 4rc \cos \theta} = 2a \text{ (use cosine rule to find GF)}$ $\sqrt{r^2 + 4c^2 - 4rc \cos \theta} = 2a - r$ $r^2 + 4c^2 - 4rc \cos \theta = 4a^2 - 4ar + r^2$ $4ar \left(1 - \frac{c}{a} \cos \theta \right) = 4(a^2 - c^2)$ $r = \frac{a - \frac{c^2}{a}}{\left(1 - \frac{c}{a} \cos \theta \right)} \text{ (shown)}$ <p>$\therefore p = a - \frac{c^2}{a} \text{ and } q = \frac{c}{a}.$</p>	A1 p A1 q								

(c)	q represents the eccentricity of the conic section.	
(d)	<p>Arc length = $\int_0^\pi \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$</p> $= \int_0^\pi \sqrt{\left(\frac{a - \frac{c^2}{a}}{1 - \frac{c}{a} \cos \theta}\right)^2 + \frac{\left(\frac{c^2}{a} - a\right)^2 \left(\frac{c}{a} \sin \theta\right)^2}{\left(1 - \frac{c}{a} \cos \theta\right)^4}} d\theta$ <p>For small values of c, the ellipse approaches the circle with centre at O and radius a. \therefore arc length $\approx \pi a$.</p> <p>Alternative:</p> $\lim_{c \rightarrow 0} \sqrt{\left(\frac{a - \frac{c^2}{a}}{1 - \frac{c}{a} \cos \theta}\right)^2 + \frac{\left(\frac{c^2}{a} - a\right)^2 \left(\frac{c}{a} \sin \theta\right)^2}{\left(1 - \frac{c}{a} \cos \theta\right)^4}} = \sqrt{\frac{a^2}{1} + \frac{a^2 \times 0}{1}} = a$ <p>\therefore arc length $\rightarrow \int_0^\pi a d\theta = a\pi$</p>	
8(a)	Number of ways = $12! = 479001600$	
(b)	<p>WWWWW MMMM MMMMMMM WWWWWMM</p> <p>Number of ways = $5! \times 7! + {}^7P_5 \times 5! \times 2! \times 3 = 2419200$</p>	
(c)	<p>Consider complementary cases involving two particular girls are adjacent to each other.</p> <p>Case 1: Both seated in front row $2! \times {}^{10}C_3 \times 4! \times 7! = 29030400$</p> <p>Case 2: Both seated in back row $2! \times {}^{10}C_5 \times 6! \times 5! = 43545600$</p> <p>Number of ways $= 479001600 - (29030400 + 43545600)$ $= 406425600$</p>	
(d)	Number of ways = $\frac{{}^{12}C_4 \times {}^8C_4 \times {}^4C_4}{3!} = 5775$	
9 (a)	<p>$\overrightarrow{AB} = \begin{pmatrix} -6 \\ -4 \\ 0 \end{pmatrix}$ $\overrightarrow{AC} = \begin{pmatrix} -6 \\ 0 \\ 1 \end{pmatrix}$</p> <p>$\vec{r} = \begin{pmatrix} -6 \\ -4 \\ 0 \end{pmatrix} \times \begin{pmatrix} -6 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -4 \\ 6 \\ -24 \end{pmatrix} // \begin{pmatrix} 2 \\ -3 \\ 12 \end{pmatrix}$</p> <p>$\therefore$ equation of plane ABC is $\vec{r} \cdot \begin{pmatrix} 2 \\ -3 \\ 12 \end{pmatrix} = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -3 \\ 12 \end{pmatrix} = 12$</p> <p>Cartesian equation is $2x - 3y + 12z = 12$.</p>	

(b)	<p>Consider line OD: $\vec{r} = \lambda \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix}, \lambda \in \mathbb{R}$</p> <p>When OD intersects plane ABC, $2(2\lambda) - 3(0) + 12(3\lambda) = 12$. $\lambda = 0.3$</p> <p>\therefore point of intersection is $(0.6, 0, 0.9)$.</p>	<p>Answer in coordinates form, not position vector.</p>
(c)	<p>Shortest distance = $\vec{AD} \cdot \hat{n} = \frac{1}{\sqrt{4+9+144}} \left \begin{pmatrix} 0 \\ 0 \\ 9 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -3 \\ 12 \end{pmatrix} \right = \frac{108}{\sqrt{157}}$ units.</p>	
(d)	<p>Area of plane $ABC = \frac{1}{2} \vec{AB} \times \vec{AC} = \frac{1}{2} \sqrt{628} = \sqrt{157}$</p> <p>$\therefore$ Volume of tetrahedron = $\frac{1}{3} \times \sqrt{157} \times \frac{108}{\sqrt{157}} = 36$ cu. units.</p>	
10(a)	<p>$x = at^2, \quad y = 2at, \quad -\sqrt{a} \leq t \leq \sqrt{a}$</p> <p>$\frac{dx}{dt} = 2at, \quad \frac{dy}{dt} = 2a$</p> <p>$\therefore \frac{dy}{dx} = \frac{1}{t}$</p> <p>Gradient of $TS = \frac{dy}{dx} \Big _P = \frac{1}{t}$</p> <p>$\therefore \tan \theta = \text{gradient of } TS = \frac{1}{t}$ (shown)</p> <p>Gradient of $QP = \frac{2at - 0}{at^2 - a} = \frac{2t}{t^2 - 1}$</p> <p>$\therefore \tan \phi = \frac{2t}{t^2 - 1}$</p> <p>$\tan \phi = \frac{\frac{2}{\tan \theta}}{\frac{1}{\tan^2 \theta} - 1}$</p> <p>$= \frac{2 \tan^2 \theta}{\tan \theta (1 - \tan^2 \theta)}$</p> <p>$= \frac{2 \tan \theta}{1 - \tan^2 \theta}$</p> <p>$= \tan 2\theta$</p> <p>Since $0 < \phi, \theta < \pi, \quad \phi = 2\theta$ (shown)</p>	<p>When $\tan A = \tan B$, there are many possible relationships between A and B. A good answer should include justifying why $A = B$.</p>
(b)	<p>$\angle QPR = \pi - 2\theta$ (corresponding angles)</p> <p>$\angle TPQ = \pi - (\pi - 2\theta) - \theta$ (sum of angles on a straight line)</p> <p>$\therefore \angle TPQ = \theta$ (shown)</p>	
(c)	<p>The inner reflective surface of the car headlight is to have a <u>parabolic</u> shape with the <u>light source located at point Q</u> (focus) so that light from <u>Q</u> is reflected parallel to the road.</p>	<p>2 marks – one each to the underlined factors.</p>

(d)	<p>Surface area = $2\pi \int_0^{\sqrt{a}} y \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$</p> $= 2\pi \int_0^{\sqrt{a}} 2at \sqrt{4a^2 t^2 + 4a^2} dt$ $= 8\pi a^2 \int_0^{\sqrt{a}} t \sqrt{t^2 + 1} dt$ $= 4\pi a^2 \left[\frac{2(t^2 + 1)^{3/2}}{3} \right]_0^{\sqrt{a}}$ $= \frac{8\pi a^2}{3} [(a+1)^{3/2} - 1]$	Only need to consider the upper half (or lower half) of the curve.
11(a)	D_1 is always 30 m above ground.	
(b)	<p>When $\mathbf{r}_1 = \mathbf{r}_2$,</p> $\begin{pmatrix} 0 \\ 0 \\ 30 \end{pmatrix} + t \begin{pmatrix} 3 \\ -2 \\ 0 \end{pmatrix} = \begin{pmatrix} 10 \\ 8 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \\ 3 \end{pmatrix}$ $3t = 10 - t \dots (1)$ $-2t = 8 + 2t \dots (2)$ $30 = 3t \dots (3)$ $(1) \Rightarrow t = 2.5, \quad (2) \Rightarrow t = -2 \quad (3) \Rightarrow t = 10$ <p>Since there is no consistent value of t, $\mathbf{r}_1 \neq \mathbf{r}_2$ at all times.</p> <p>$\therefore D_1$ and D_2 will not coincide.</p> $\overrightarrow{D_1 D_2} = \begin{pmatrix} 10 \\ 8 \\ -30 \end{pmatrix} + t \begin{pmatrix} -4 \\ 4 \\ 3 \end{pmatrix}$ $ \overrightarrow{D_1 D_2} = \sqrt{(10 - 4t)^2 + (8 + 4t)^2 + (3t - 30)^2}$ $= \sqrt{1064 - 196t + 41t^2}$ $= \sqrt{41 \left(t - \frac{196}{2(41)} \right)^2 + 1064 - 41 \left(\frac{98}{41} \right)^2}$ $= \sqrt{41 \left(t - \frac{98}{41} \right)^2 + \frac{34020}{41}} \geq \sqrt{\frac{34020}{41}}$ <p>Minimum distance occurs when $t = \frac{98}{41}$.</p> <p><u>Alternative:</u></p> <p>Minimum distance occurs when $\frac{d}{dt}(1064 - 196t + 41t^2) = 0$</p> $\Rightarrow 82t = 196$ $\Rightarrow t = \frac{98}{41}$ <p>\therefore minimum $\overrightarrow{D_1 D_2} = \sqrt{\frac{34020}{41}} = 28.8 \text{ m (3sf)}$</p>	d

(c)	<p>Angle of elevation = angle between path of D_2 and ground</p> $= 90^\circ - \cos^{-1} \frac{\left \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 2 \\ 3 \end{pmatrix} \right }{\sqrt{14}}$ $= 90 - \cos^{-1} \frac{3}{\sqrt{14}}$ $= 53.3^\circ$	
(d)	<p>At $t = 7$, $\mathbf{r}_1 = \begin{pmatrix} 21 \\ -14 \\ 30 \end{pmatrix}$ and $\mathbf{r}_2 = \begin{pmatrix} 3 \\ 22 \\ 21 \end{pmatrix}$.</p> <p>$\therefore h_1 = 30, h_2 = 21$.</p> <p>$A_1 = 2(30)^2, A_2 = 2(21)^2$.</p> <p>Centre of these circular areas are $(21, -14)$ and $(3, 22)$ on the $x - y$ plane</p> <p>with radii $R_1 = \sqrt{\frac{A_1}{\pi}} = 30\sqrt{\frac{2}{\pi}}$ $R_2 = 21\sqrt{\frac{2}{\pi}}$ respectively.</p> <p>Distance between the 2 centres $= \sqrt{(21-3)^2 + (-14-22)^2} \approx 40.249$</p> <p>$R_1 + R_2 \approx 40.692 >$ distance between the 2 centres, the areas observed by both drones overlapped. (shown)</p> 